

Control c. 5

$$\textcircled{4} \quad \frac{\partial u}{\partial t} - \frac{\partial^2 u}{\partial x^2} = 0 \quad x \in (0, \frac{1}{2})$$

$$\frac{\partial u}{\partial x}(t, 0) = \frac{\partial u}{\partial x}(t, \frac{1}{2}) = 0 \quad u(0, x) = \delta_a \quad a \in (0, \frac{1}{2})$$

$$\text{Lösung: } T = T_{u_0^s} \quad u_0^s = \delta_a + \delta_{-a} \\ T_h = T_{u(t, \cdot)}$$

$$\text{Reihe je } T_{u(t, \cdot)} * (T_{u_0^s} * \delta_{\Sigma})$$

$$= u(t, x) = \sum_{n=-\infty}^{\infty} F(u_0^s)(n) \underbrace{F(u)(n)}_{e^{-\frac{4n^2 \pi^2 t}{L^2}}} e^{i 2n\pi x}$$

$$\langle F(\delta_a), \Psi \rangle = \langle \delta_a, F(\Psi) \rangle = \int_{\mathbb{R}} \langle \delta_a, \int_{\mathbb{R}} e^{-2\pi i \xi x} \varphi(x) dx \rangle =$$

$$= \int_{\mathbb{R}} e^{-2\pi i a x} \varphi(x) dx = \langle T_{e^{-2\pi i a x}}, \Psi \rangle$$

Troj

(1)

$$F(u_0^s) = F(\bar{u}_a + \bar{u}_{-a}) = e^{-2\pi i a x} + e^{2\pi i a x} = 2 \cos(2\pi a x)$$

$$u(t, x) = 2 \sum_{m=-\infty}^{\infty} \cos(2\pi m a) e^{-4\pi^2 m^2 t} e^{2\pi i m x}$$

u(t,0) u(t,1/4)

$$= 4 \sum_{m=1}^{\infty} \cos(2\pi m a) e^{-4\pi^2 m^2 t} \cos(2\pi m x) + 2 \quad \left. \begin{array}{l} x \in (0, \frac{1}{4}) \\ t > 0 \end{array} \right\}$$

(2) $\frac{\partial u}{\partial t} - \frac{\partial^2 u}{\partial x^2} = 0 \quad x \in (0, \frac{1}{4}) \quad t > 0$

$u(0, x) = \bar{u}_a \quad a \in (0, \frac{1}{4})$

$u(t, 0) = \frac{\partial u}{\partial x}(t, \frac{1}{4}) = 0$

Najlepiej $u(t, \frac{1}{4})$ a $\frac{\partial u}{\partial x}(t, 0)$.

Procedura podobna jak przy $x=0$ a tutaj jak $x = \frac{1}{4}$

$$\tilde{u}_0^a = \bar{u}_a + \bar{u}_{-a} + \bar{u}_{\frac{1}{2}-a} - \bar{u}_{\frac{1}{2}+a}$$

Troj $F(\tilde{u}_0^a) = F(\bar{u}_a + \bar{u}_{-a} + \bar{u}_{\frac{1}{2}-a} - \bar{u}_{\frac{1}{2}+a}) = e^{-2\pi i a x} + e^{2\pi i a x} + e^{-2\pi i (\frac{1}{2}-a)x} - e^{-2\pi i (\frac{1}{2}+a)x}$

$$= -2i \sin(2\pi a x) - 2i \sin(2\pi (\frac{1}{2}-a)x)$$

$$u(t, x) = -2i \sum_{m=-\infty}^{\infty} (\sin(2\pi m a) + \sin(\pi(1-2a)m)) e^{-4\pi^2 m^2 t} e^{2\pi i m x}$$

$$= 4 \sum_{m=1}^{\infty} (\sin(2\pi m a) + \sin(\pi(1-2a)m)) e^{-4\pi^2 m^2 t} \sin(2\pi m x)$$

$\sin(\pi(1-2a)m) = \sin(\pi m - 2\pi a m) = \sin(\pi m) \cos(2\pi a m) - \cos(\pi m) \sin(2\pi a m) = (-1)^m \sin(2\pi a m)$

liczymy $\frac{E}{4}$
 $\sin \frac{2a(2k-1)}{4} \quad (-1)^k$

$$u(t, x) = 8 \sum_{k=1}^{\infty} \sin(2\pi k(1-a)) e^{-4\pi^2 (2k-1)^2 t} \sin(2\pi (2k-1)x)$$

$$u(t, \frac{1}{4}) = 8 \sum_{k=1}^{\infty} (-1)^k \sin(2\pi k(1-a)) e^{-4\pi^2 (2k-1)^2 t}$$

$$\frac{\partial u}{\partial x}(t, 0) = 16\pi \sum_{k=1}^{\infty} (2k-1) \sin(2\pi k(1-a)) e^{-4\pi^2 (2k-1)^2 t}$$

③ Radialni symulicheski nivo

$$\frac{\partial u}{\partial t} - \Delta u = 0 \quad x \in B_{\frac{1}{2}}(0) \subset \mathbb{R}^3$$

$$u(0, x) = \chi_{[0, a]}(r) \quad r = |x| \in (0, \frac{1}{2}) \quad a \in (0, \frac{1}{2})$$

$$u(t, x) = 0 \quad |x| = \frac{1}{2}$$

Uvedemo radialni symulicheski nivo

$$u(t, x) = w(t, |x|)$$

Poba $\Delta u = \frac{\partial^2 w}{\partial r^2} + \frac{2}{r} \frac{\partial w}{\partial r}$, tj

$$\frac{\partial w}{\partial t} - \frac{\partial^2 w}{\partial r^2} - \frac{1}{r} \frac{\partial w}{\partial r} = 0$$

$$w = r^{\frac{1}{2}} \tilde{w}$$

$$\frac{\partial w}{\partial r} = \tilde{w} + r \frac{\partial \tilde{w}}{\partial r}$$

$$\frac{\partial^2 w}{\partial r^2} = 2 \frac{\partial \tilde{w}}{\partial r} + r \frac{\partial^2 \tilde{w}}{\partial r^2}$$

Ted $\frac{\partial w}{\partial t} - \frac{\partial^2 \tilde{w}}{\partial r^2} = 0$

$$w(0, x) = r \chi_{[0, a]} \quad 0 < a < \frac{1}{2}$$

$$w(\frac{1}{2}, x) = 0 \quad a \text{ dostato } w(\frac{1}{2}, 0) = 0 \quad (\text{pobota } w(\frac{1}{2}, 0) = r \tilde{w}(\frac{1}{2}, 0) = 0)$$

Ted lako prodamo

$$\tilde{w}_0 = r \chi_{[0, a]} \quad \text{na } [-\frac{1}{2}, \frac{1}{2}]$$

$$F(\tilde{w}_0) = \int_{-a}^a e^{-i \omega x} x dx = \int_{-a}^a -i \sin(2 \omega x) x dx = +i \left[\frac{x \cos(2 \omega x)}{2 \omega} \right]_{-a}^a + i \int_{-a}^a \frac{\cos(2 \omega x)}{2 \omega} dx$$

$$= \frac{-i}{2 \omega^2} \left[+ \frac{\sin(2 \omega x)}{2 \omega} \right]_{-a}^a = \frac{2i}{2 \omega^2} \sin(2 \omega a) + \frac{2i a}{\omega} \cos(2 \omega a)$$

$$w(t, r) = \frac{-i}{\sqrt{t}} \sum_{n=1}^{\infty} \frac{1}{n^2} \sin(2 \omega a n) e^{-4 \omega^2 n^2 t} e^{2 i \omega n r} \frac{\sin(2 \omega a n) - (2 \omega a n) \cos(2 \omega a n)}{2}$$

$$= \frac{-i \cdot 2i}{\sqrt{t}} \sum_{n=1}^{\infty} \frac{1}{n^2} \sin(2 \omega a n) e^{-4 \omega^2 n^2 t} \sin(2 \omega n r) \left(\frac{\sin(2 \omega a n) - (2 \omega a n) \cos(2 \omega a n)}{2} \right)$$

Ted $u(t, x) = \frac{1}{\sqrt{t} |x|} \sum_{n=1}^{\infty} \frac{1}{n^2} \sin(2 \omega a n) e^{-4 \omega^2 n^2 t} \sin(2 \omega n |x|) \left(\frac{\sin(2 \omega a n) - (2 \omega a n) \cos(2 \omega a n)}{2} \right)$

4) Vlnová rovnice

$$\frac{1}{a^2} \frac{\partial^2 u}{\partial t^2} - \frac{\partial^2 u}{\partial x^2} = 0 \quad \begin{matrix} x \in \mathbb{R}^+ \\ t \in \mathbb{R}^+ \end{matrix}$$

$$u(0, x) = 0$$

$$\frac{\partial u}{\partial t}(0, x) = g_{\text{per}}(x)$$

a) g_{per} 1-m. modélis $g(x) = \sin^3(2\pi x)$

$$\begin{aligned} \sin 3z &= \sin z \cos 2z + \cos z \sin 2z = \sin z (\cos^2 z - \sin^2 z) + 2 \sin z \cos z \\ &= 3 \sin z (1 - \sin^2 z) - \sin^3 z = 3 \sin z - 4 \sin^3 z \end{aligned}$$

$$\begin{aligned} u(t, x) &= \frac{1}{2a} \int_{x-at}^{x+at} \sin^3(2\pi x) dx = \\ &= \frac{1}{2a} \cdot \frac{1}{4} \int_{x-at}^{x+at} (3 \sin(2\pi x) - \sin(6\pi x)) dx = \frac{1}{8a \cdot 2\pi} \left[\frac{\cos 6\pi x}{3} \Big|_{x-at}^{x+at} + 3 \cos 2\pi x \Big|_{x-at}^{x+at} \right] \end{aligned}$$

$$\Rightarrow \sin^3 z = \frac{1}{4} (3 \sin z - \sin 3z)$$

$$\begin{aligned} &= \frac{1}{6\pi a} \left[\frac{1}{3} (\cos 6\pi(x+at)) - \cos 6\pi(x-at) \right) + 3 (\cos 2\pi(x+at) - \cos 2\pi(x-at)) \right] \\ &= \frac{1}{6\pi a} \left[\frac{2}{3} + \sin(6\pi x) \sin(6\pi at) \right] \quad \# \quad 3 \cdot 2 \sin(2\pi x) \sin(2\pi at) \end{aligned}$$

odpovídá F.Ř. pomocí F.Ř. od

b) g_{per} 1-ten modélis $g(x) = \cos^4(\pi x)$

$$\begin{aligned} \cos^4(x) &= \left(\frac{1 + \cos(2x)}{2} \right)^2 = \frac{1}{4} (1 + 2 \cos(2x) + \frac{1 + \cos(4x)}{2}) \\ &= \frac{1}{8} (3 + 4 \cos(2x) + \cos(4x)) \end{aligned}$$

$$u(t, x) = \frac{1}{2a} \int_{x-at}^{x+at} \cos^4(\pi x) dx = \frac{1}{8 \cdot 2a} \int_{x-at}^{x+at} (3 + 4 \cos(2\pi x) + \cos(4\pi x)) dx$$

$$= \frac{1}{6a} \left(6at + \frac{2}{\pi} [\sin 2\pi x]_{x-at}^{x+at} + \frac{1}{4\pi} [\sin 4\pi x]_{x-at}^{x+at} \right)$$

$$= \frac{1}{6a} \left(6at + \frac{2}{\pi} (\sin 2\pi(x-at) + \sin 2\pi(x+at)) + \frac{1}{4\pi} (-\sin(4\pi(x-at)) + \sin(4\pi(x+at))) \right)$$

$$= \frac{1}{6a} \left(6at + \frac{4}{\pi} \sin 2\pi at \cos 2\pi x + \frac{1}{2\pi} (\sin(4\pi at) \cos(4\pi x)) \right)$$

Odpovídá F.Ř.

5) Wave equation

$$\frac{1}{a^2} \frac{\partial^2 u}{\partial t^2} - \frac{\partial^2 u}{\partial x^2} = 0 \quad x \in \mathbb{R}^+ + \mathbb{0} \mathbb{R}^+$$

$$u(0, x) = 0$$

$$\frac{\partial u}{\partial t}(0, x) = \delta_b \quad b > 0$$

$$u(t, 0) = 0$$

Problem on \mathbb{R} : $\tilde{g}_1(x) = \delta_b + \delta_{-b}$... Dirichlet boundary conditions

Resol $u(t, x) = T_{\frac{1}{2a}} x[-at, at] * (\delta_b - \delta_{-b})$

$$\langle T_{\frac{1}{2a}} \chi_{[-at, at]} * (\delta_b - \delta_{-b}), \varphi \rangle = \langle (\delta_b - \delta_{-b})(x), \langle T_{\frac{1}{2a}} \chi_{[-at, at]}(y), \varphi(x+y) \rangle \rangle$$

$$= \langle (\delta_b - \delta_{-b})(x), \int_{\mathbb{R}} \frac{1}{2a} \chi_{[-at, at]}(y) \varphi(x+y) dy \rangle = \frac{1}{2a} \int_{-at}^{at} (\varphi(b+y) - \varphi(y-b)) dy$$

$$= \frac{1}{2a} \int_{-at+b}^{at+b} \varphi(y) dy - \frac{1}{2a} \int_{-at-b}^{at-b} \varphi(y) dy \Rightarrow$$

$$u(t, x) = \frac{1}{2a} (\chi_{[-at+b, at+b]}(x) - \chi_{[-at-b, at-b]}(x))$$