

KNOT INVARIANTS

①

def • Knot is an injective smooth map $K: S^1 \rightarrow \mathbb{R}^3$
w. nowhere vanishing derivative.
We identify knots with the same images $K(S^1)$
(i.e. we consider equivalence classes of maps K)

- Isotopy of two knots $K_0, K_1: S^1 \rightarrow \mathbb{R}^3$ is a smooth map $\sigma: [0, 1] \times S^1 \rightarrow \mathbb{R}^3$ s.t.
 $\forall t \quad \sigma(t, -): S^1 \rightarrow \mathbb{R}^3$ is a knot
 $\sigma(0, -) = K_0, \quad \sigma(1, -) = K_1$



goal of the knot theory: find an easy way of telling whether two given knots are isotopic.

(in particular: can a knot be unknotted?)

assign an object $I(K)$ (number, polynomial, seq. of n.s., ...)

to each knot K such that $I(K) = I(K') \Leftrightarrow K \cong K'$

(isotopy invariance of I) and hope for " \Rightarrow " (or get as close to " \Rightarrow " as possible)

Overview of the lecture series:

- 1) Jones polynomial
- 2) more systematic way of producing knot invariants using ribbon categories
- 3) applications/related topics: - Yang-Baxter in statistical physics
(2) - invariants of 3-manif.
- 4) producing ribbon categories out of quantum groups
- 5) other knot invariants (HOMFLY...)
- 6) Khovanov homology as categorification of Jones pol.

lit.: Rosso, Turaev, Kazhdan: Quantum groups and knot invariants

...

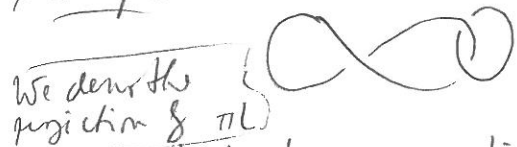
def • Link with n components is a smooth inj. map $S^1 \sqcup \dots \sqcup S^1 \rightarrow \mathbb{R}^3$ w. non-vanishing derivative.

(quantities on knot)

• isotopy of links

• link projection (aka link diagram) is the image of a projection $\mathbb{R}^3 \xrightarrow{\pi} \mathbb{R}^2$, which has only "+" singularities, and for each mod projection "above/below" data:

example:



The usual picture of links are in fact link projections.

• isotopy of link projections $(\pi_0 L_0 \text{ and } \pi_1 L_1)$: $(\cdot): \mathbb{R}^2 \times I \rightarrow \mathbb{R}^2$ w. shifting

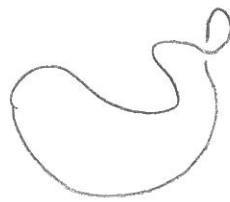
$L(-, 0) = \mathbb{1}_{\mathbb{R}^2}$ and $\forall t \in I$ $L(-, t)$ is a homeo

and
$$\left(L(-, 0) \circ \underbrace{\pi_0 L_0}_{\mathbb{R}^2} \right) \circ \underbrace{\pi_1 L_1}_{\mathbb{R}^2 \leftarrow \mathbb{R}^3 \leftarrow S^1} = L(-, 1) \circ \pi_1 L_1$$

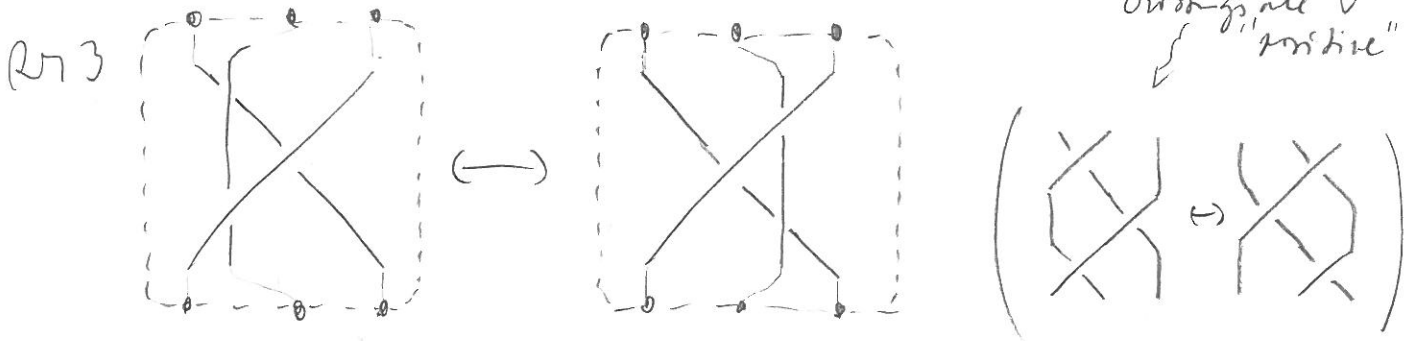
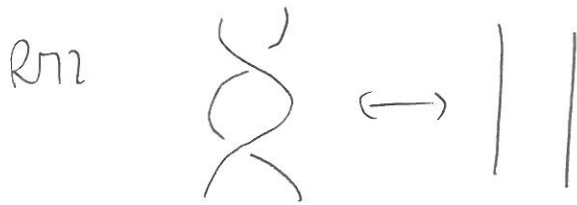
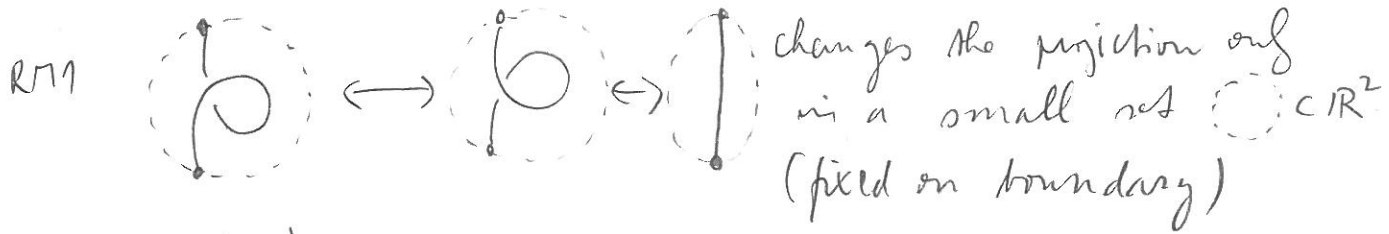
example:



isotopy of
projections
 \approx



Thm (Reidemeister) Let $\pi_1 L_1$ and $\pi_2 L_2$ be link projections of links L_1, L_2 resp. Then the links L_1, L_2 are isotopic iff one can transform $\pi_1 L_1$ into $\pi_2 L_2$ by a sequence of isotopies of link projections and the following "local moves":



Application: isotopy invariants of links can be defined on link projection and then we check invariance under (link proj. isotopies - usual def.) and R1-3.

Kauffman bracket and Jones polynomial

def. $\langle \rangle$: link projections $\rightarrow \mathbb{C}[a, a^{-1}]$ (or \mathbb{C} and $a \in \mathbb{C}$)
 is defined as follows: a param. s.t. $a^2 + a^{-2} \neq 0$

(1) $\langle \bigcirc \rangle = 1$

(2) $\langle L \sqcup \bigcirc \rangle = -(a^2 + a^{-2}) \langle L \rangle$ if \bigcirc bounds a disc which doesn't intersect L
 any link projection (abuse of notation)

(3) $\langle \text{crossing} \rangle = a \langle \text{smooth 1} \rangle + a^{-1} \langle \text{smooth 2} \rangle$
 L locally somewhere

Example

(a) $\langle \text{figure 8} \rangle = a \langle \text{figure 8 smooth} \rangle + a^{-1} \langle \bigcirc \bigcirc \rangle$
 $= a - a^{-1}(a^2 + a^{-2}) = -a^{-3}$

(b) more generally: L locally somewhere $L \cap \bigcirc$ then

$\langle L \cap \bigcirc \rangle = -a^{-3} \langle L \rangle$
 $\langle L \cap \bar{\bigcirc} \rangle = -a^3 \langle L \rangle$

Hence the Kauff. br. is NOT isotopy invariant

omit \rightarrow (c) $\langle \text{trefoil} \rangle = \langle \text{trefoil smooth} \rangle = a^3 \langle \text{trefoil smooth 1} \rangle +$
 $+ a \langle \text{trefoil smooth 2} \rangle + a \langle \text{trefoil smooth 3} \rangle + a \langle \text{trefoil smooth 4} \rangle + a^{-1} \langle \text{trefoil smooth 5} \rangle + a^{-1} \langle \text{trefoil smooth 6} \rangle$
 $+ a^{-1} \langle \text{trefoil smooth 7} \rangle + a^{-3} \langle \text{trefoil smooth 8} \rangle = a^3(a^2 + a^{-2})^2 + 3a + 3a^{-1}(a^2 + a^{-2})^2 - a^{-3}(a^2 + a^{-2})^3$

However, Kauffman br. is invariant under R42, 3!

(5)

R42:

$$\begin{aligned}
 \langle \text{crossing} \rangle &= a^2 \langle \text{cup} \rangle + \langle \text{cap} \rangle + \langle \text{cup} \rangle + a^{-2} \langle \text{cap} \rangle \\
 &= a^2 \langle \text{cup} \rangle - (a^2 + a^{-2}) \langle \text{cup} \rangle + \langle \text{cup} \rangle + a^{-2} \langle \text{cup} \rangle \\
 &= \langle \text{cup} \rangle = \langle L \rangle
 \end{aligned}$$

L modified in mag. [1] → [2]

R43:

$$\langle \text{crossing} \rangle = \langle \text{crossing} \rangle$$

$$\begin{aligned}
 \text{LHS} &= a^3 \langle \text{cup} \rangle + a \langle \text{cap} \rangle + a \langle \text{cup} \rangle + a \langle \text{cap} \rangle \\
 &+ a^{-1} \langle \text{cup} \rangle + a^{-1} \langle \text{cap} \rangle + a^{-1} \langle \text{cup} \rangle + a^{-3} \langle \text{cap} \rangle \\
 &= \underline{a^3 \langle \text{cup} \rangle} + \underline{a \langle \text{cup} \rangle} + \underline{a \langle \text{cup} \rangle} + \cancel{a \langle \text{cup} \rangle} + \\
 &+ \underline{a^{-1} \langle \text{cup} \rangle} - \cancel{a^{-1}(a^2 + a^{-2}) \langle \text{cup} \rangle} + \underline{a^{-1} \langle \text{cup} \rangle} + \cancel{a^{-3} \langle \text{cup} \rangle}
 \end{aligned}$$

$$\begin{aligned}
 \text{RHS} &= a^3 \langle \text{cup} \rangle + a \langle \text{cap} \rangle + a \langle \text{cup} \rangle + a \langle \text{cap} \rangle + \\
 &+ a^{-1} \langle \text{cup} \rangle + a^{-1} \langle \text{cap} \rangle + a^{-1} \langle \text{cup} \rangle + a^{-3} \langle \text{cap} \rangle \\
 &= \underline{a^3 \langle \text{cup} \rangle} + \underline{a \langle \text{cup} \rangle} + \underline{a \langle \text{cup} \rangle} + \cancel{a \langle \text{cup} \rangle} + \\
 &+ \underline{a^{-1} \langle \text{cup} \rangle} - \cancel{a^{-1}(a^2 + a^{-2}) \langle \text{cup} \rangle} + \underline{a^{-1} \langle \text{cup} \rangle} + \cancel{a^{-3} \langle \text{cup} \rangle}
 \end{aligned}$$

OK

How can we make $\langle \rangle$ RMI-invariant

(6)

$\langle \bigcirc \rangle = -a^3 \langle 1 \rangle$ idea: multiply $\langle L \rangle$

$\langle \bigcirc \rangle = -\bar{a}^3 \langle 1 \rangle$

by $-\bar{a}^3$ for each crossing "X"
 $-a^3$ "X"

But these crossing are indistinguishable (link projection isotopic) unless one has an orientation on each strand of the

crossing

def oriented link ... each component is oriented (an arrow in the link projection)



positive crossing \Rightarrow multiply by $-a^{-3}$

negative $-a^3$

def Let L be an oriented link.

$V(L) := (-a^3)^{-(\# \text{ of pos. cr.} - \# \text{ of neg. cross.})} \langle L \rangle \in \mathbb{C}[a]$

is called Jones polynomial of L .

Thm Jones polynomial is invariant under isotopy of oriented links.

PF: By the const., it's invariant under link proj. isotopies and under RMI

RMI2: $V(\text{crossing}) \stackrel{\text{no matter the orientation of the segments}}{\downarrow} = \langle \bigcirc \rangle \stackrel{\text{one crossing is positive, the other is negative}}{\downarrow} = \langle 1 \rangle = V(\bigcirc)$

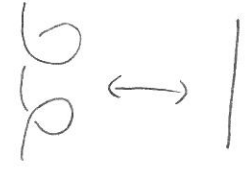
RMI3: $V(\text{crossing}) = (-a^3)^p \langle \bigcirc \rangle \stackrel{\text{pos. str. of } \langle \rangle}{\downarrow} = (-a^3)^p \langle \bigcirc \rangle = V(\text{crossing})$

$p \in \{-3, -1, 1, 3\}$ depends on the orient. of segments

\square

rem There are nonisotopic knots K_1, K_2 s.t. $V(K_1) = V(K_2)$ (Jones pol. is not complete inv.) (7)

Framed links

$\langle \rangle$ is invariant under ROT : 

a lot of them work for objects that are only ROT, ROT^2, ROT^3 invariants. They have a natural geometric model

def Framed knot is a knot K equipped with a smooth normal nowhere vanishing vector field (called framing) $v: S^1 \rightarrow \mathbb{R}^3$



$v(s) \in N_{K(s)}(K(I))$

Two framings v_0, v_1 are homotopic iff \exists homotopy $h: S^1 \times I \rightarrow \mathbb{R}^3$ s.t. $h(-, 0) = v_0(-)$
 $h(-, 1) = v_1(-)$

We identify homotopic framings
observation up to homotopy, the framing is given by an integer (= # of times it winds around $K(I)$)

v is homotopic to united framing $v': S^1 \rightarrow S^1$ topological
 and up to homotopy, this is classified by the degree

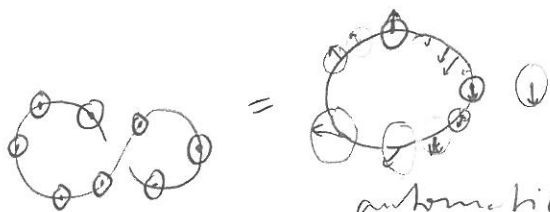
remark The framing sweeps a 2D "ribbon" whose one boundary is the knot
isotopy of framed knots \equiv isotopy of united knots & homotopy of framings, simultaneous in the obs. must

framed links, their isotopy, ...



• another eq. def. of framed knot:
 it's smooth embedding $S^1 \times D^2 \rightarrow \mathbb{R}^3$
 (compare unknot $S^1 \rightarrow \mathbb{R}^3$ solid torus embed.)

Link projection induces a canonical framing on the link: the vector fields point upwards (from the blackboard towards the reader) (8)



i.e. picture ∞ automatically induces the framing ∞^1

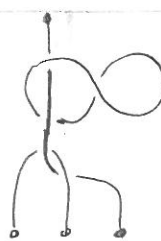
obvious For framed links:

$$\bigcirc = \bigcirc^0, \quad \bigcirc = \bigcirc^1, \quad \bigcirc = \bigcirc^{-1}$$

This shows why RM doesn't hold for framed links (but is invariant but the framing is not)

But RT0 does hold: $\bigcirc_{(-1)}^{\circ} \bigcirc_{(+1)}^{\circ} = \bigcirc^0$

In the sequel, we'll be interested in invariants of framed links.



(3,1)-Angle

Tangles

(informally) def. (b,l)-Angle ($b, l \in \mathbb{N}_0$).

set of disjoint smoothly embedded circles and arcs in $\mathbb{R}^2 \times (0,1)$ s.t. (a) The endpoints of arcs are the points $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix}, \dots, \begin{pmatrix} b \\ 0 \\ 0 \end{pmatrix}$ and $\begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}, \dots, \begin{pmatrix} l \\ 1 \\ 0 \end{pmatrix}$

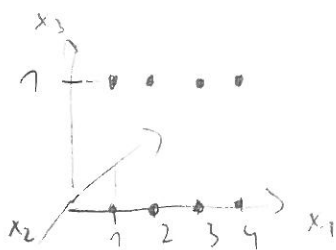
(b) The circles lie in $\mathbb{R}^2 \times (0,1)$

component of the angle is one of the circles or arcs

framed angle \equiv each component is framed

(arcs are framed by vector fields equal to $\begin{pmatrix} 0 \\ -1 \\ 0 \end{pmatrix}$ on endpoints)

oriented angle \equiv each comp. oriented



motives of (framed) tangles $\equiv (I \times S^1) \times I \rightarrow \mathbb{R}^2 \times I$ through tangles (9)

tangle projection (diagram) ...

RT0,1,2,3 for (framed) tangles ...

(ex.) (0,0) tangle is a link

Goal: organize tangles into (amorphous in) a category Tan

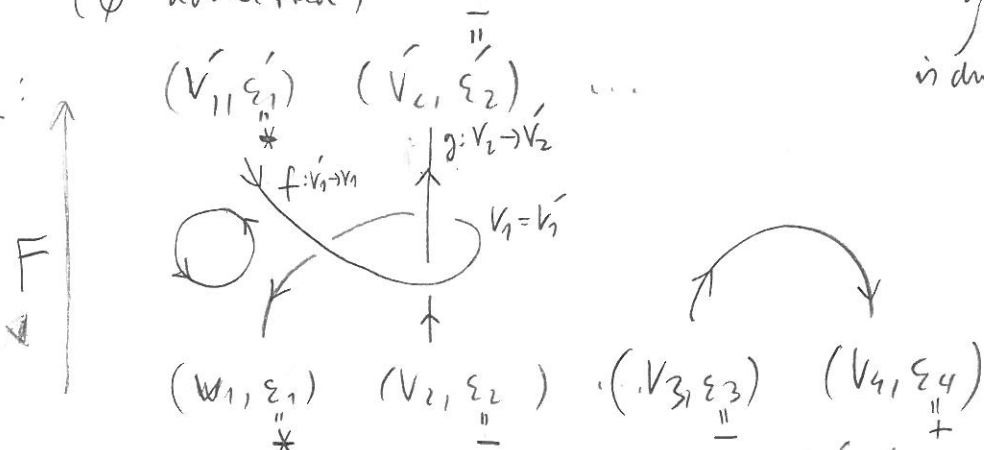
Tan is a (free, gen. of a single obj.) ribbon category.

(monoidal c.w. some restriction on \otimes and addit. str.)

def. Let \mathcal{C} be a category. A category of \mathcal{C} -coloured framed oriented tangles $\text{Tan}_{\mathcal{C}}$ consists of:

objects: sequences $((V_1, \epsilon_1), \dots, (V_n, \epsilon_n))$, $V_i \in \text{obj. } \mathcal{C}$
 $\epsilon_i \in \{+, -\}$ "dual marker"
 (\emptyset admitted) is dual is NOT dual

morphs:



between $((V_1, \epsilon_1), \dots, (V_n, \epsilon_n)) \rightarrow ((V'_1, \epsilon'_1), \dots, (V'_n, \epsilon'_n))$
 is an oriented framed (n, n) -tangle (iso class of ...)
 by an arc directed by an arc oriented $V_j \rightarrow V_i$

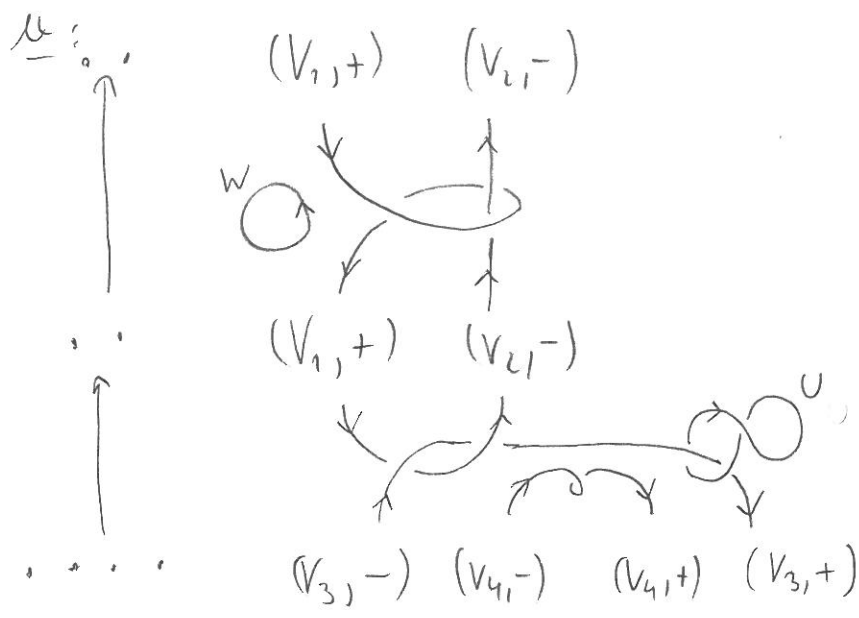
s.t. (i) if i -th output is connected to the j -th input, then either a) $V'_i \xleftarrow{f} V_j$ and $\epsilon_i = \epsilon_j = -$ or b) $V'_i \xrightarrow{f} V_j$ and $\epsilon_i = \epsilon_j = +$

universal rule for

ϵ_i : if the orientation of the arc coincides with the orientation of the morph. F then $\epsilon = -$, otherwise $\epsilon = +$

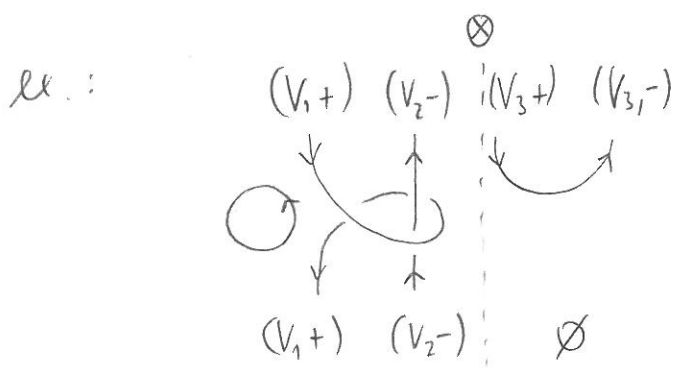
(i) if i -th output is connected to the j -th output and the orientation is $i \rightarrow j$, then $\epsilon_i = +, \epsilon_j = -$
 (ii) if i -th input is connected to the j -th input and the orientation is $i \rightarrow j$, then $\epsilon_i = -, \epsilon_j = +$
 circular components are labelled by endomorphisms in \mathcal{C}
 modulo "trace equivalence" $\text{fg} \sim \text{gt}$.
 Why the trace equivalence? see 7.9.5 (15,5)

Composition of morphs \equiv write the tangles one above the other and compress with $\mathbb{R}^2 \times \{0,1\}$: (10)



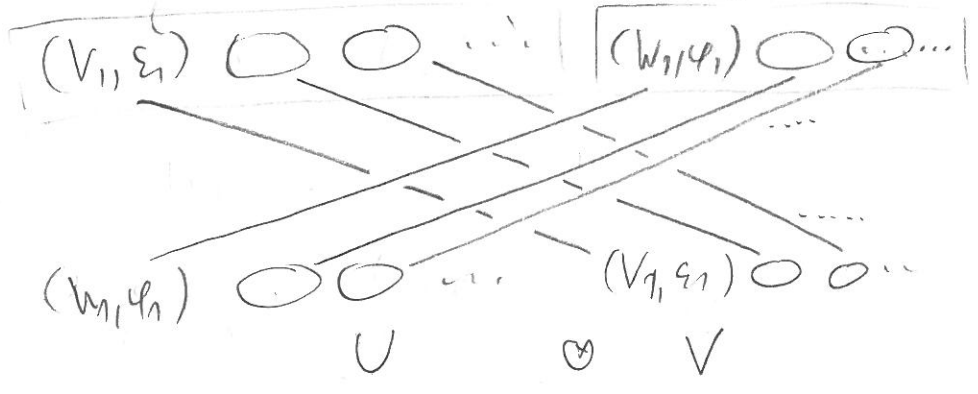
monoidal $\mathcal{A} \cdot \otimes : \text{Tan}_{\mathcal{E}} \times \text{Tan}_{\mathcal{E}} \rightarrow \text{Tan}_{\mathcal{E}}$

\equiv write the sequences and tangles one next to the other



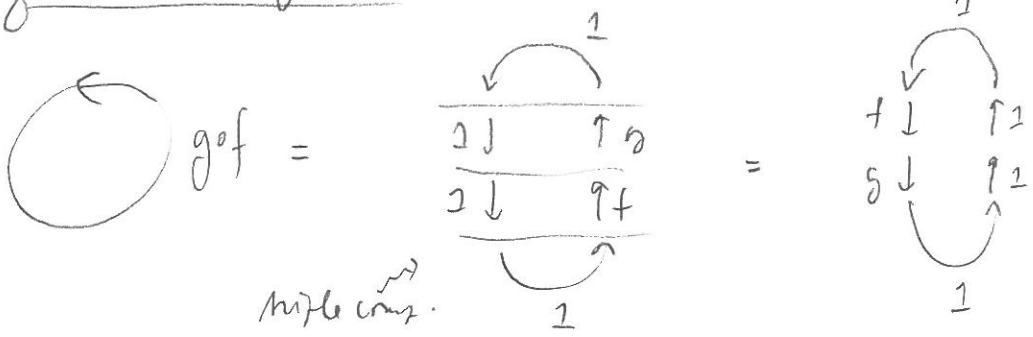
monoidal unit $I =$ the empty tangle

braiding $\mathcal{A} \cdot \equiv$ mod. Manj. Cov: $U \otimes V \rightarrow V \otimes U$



orientation is uniquely determined by ϵ 's and φ 's

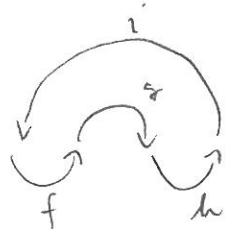
Why trace equivalence?



multiple comp. in Trace

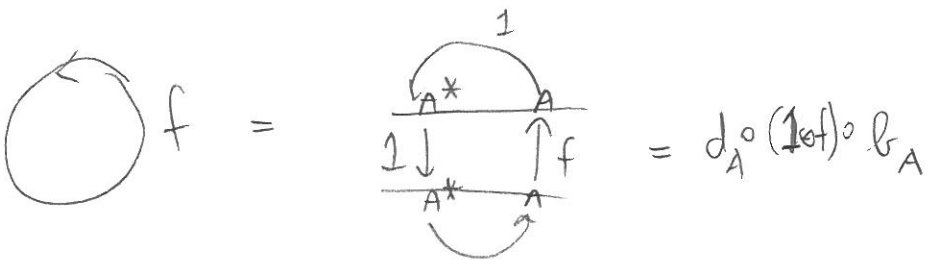
or e.g. writing the bottom map left doesn't make sense:
LHS: $f \circ \text{id}$, RHS: $\text{id} \circ f$

also e.g.



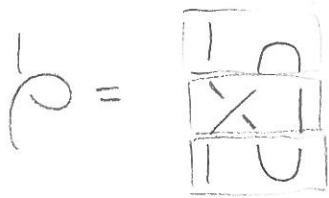
What order to choose?

Why the name "trace equivalence"?

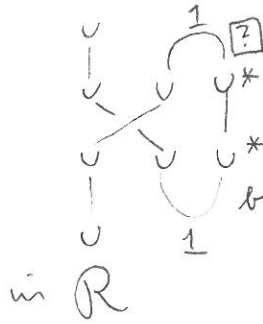


in vector spaces: $d_A^0 (1 \otimes f) \circ b_A = \sum_{i=1}^{\dim A} e^i (f(e_i)) = \text{Tr } f$

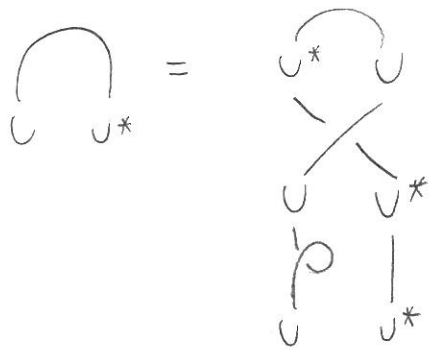
What is $\tilde{d}_{U^*} : U \otimes U^* \rightarrow 1$? (recall $d : U^* \otimes U \rightarrow 1$) (15/5)



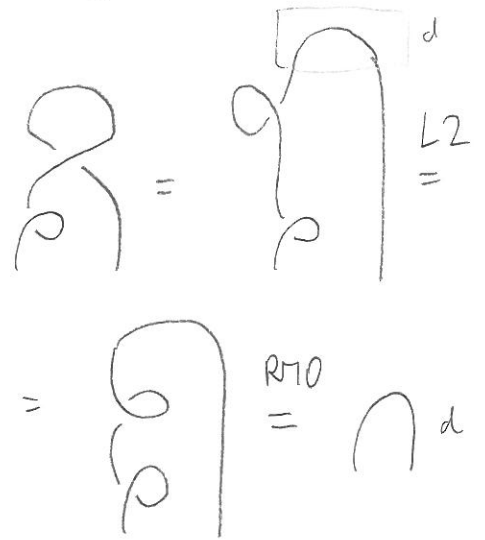
in Tan



Express $\begin{matrix} 1 \\ \cup \\ U \\ \cup \\ U^* \end{matrix}$ in Tan using $\begin{matrix} 1 \\ \cup \\ U^* \\ \cup \\ U \end{matrix}^d$:



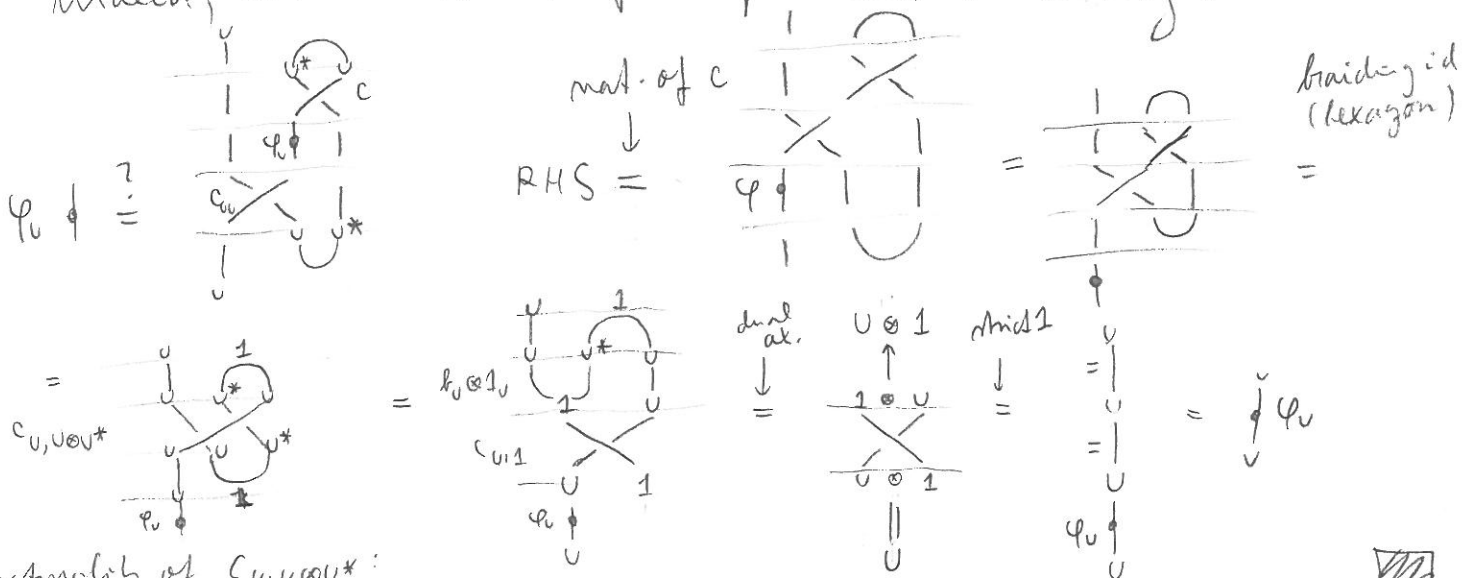
indeed:



Thus we define $\tilde{d}_{U^*} := d_{U^*} c_{U^*} (\varphi_U \otimes 1_{U^*})$

Then Schur 1 says that in R, $\varphi_U = (1 \otimes \tilde{d}_{U^*})(c \otimes 1)(1 \otimes t)$

indeed, this can be verified from axioms directly:



naturality of $c_{U, U \otimes U^*}$:

$$\begin{array}{ccc}
 U = U \otimes 1 & \xrightarrow{1_U \otimes \eta_U} & U \otimes U \otimes U^* \\
 c_{U, 1} \downarrow & & \downarrow c_{U, U \otimes U^*} \\
 1 \otimes U & \xrightarrow{1_U \otimes 1_U} & U \otimes U^* \otimes U
 \end{array}$$



There is still more structure, but first we prove:

(11)

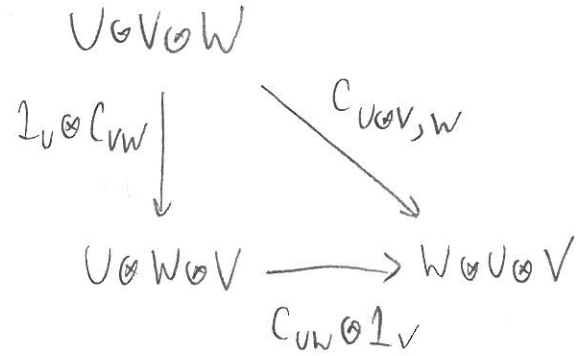
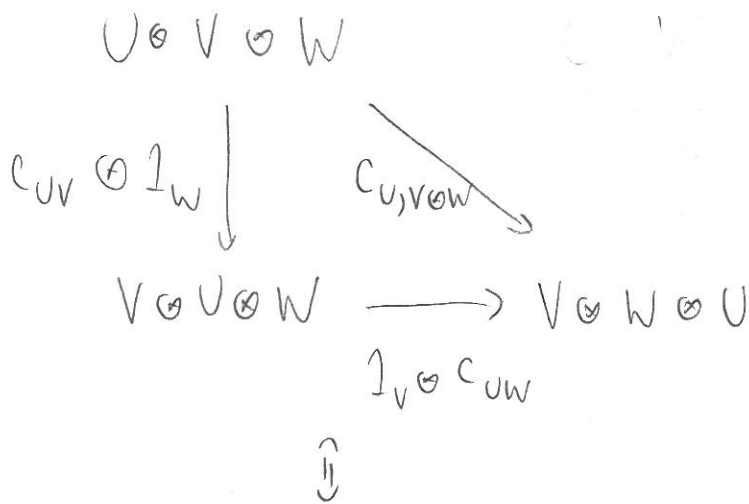
Thm \mathcal{Tan}_g is a braided (monoidal) category
strict (a.k.a. Artale cat.)

PF: recall that we should verify: $\forall U, V, W \in \text{obj } \mathcal{Tan}_g$
 (definition) (a) \mathcal{Tan}_g is strict monoidal: $\otimes: \mathcal{Tan}_g \times \mathcal{Tan}_g \rightarrow \mathcal{Tan}_g$ is a functor,
 $(U \otimes V) \otimes W = U \otimes (V \otimes W)$, $U \otimes 1 = U = 1 \otimes U$, $(f \otimes g) \circ h = f \circ (g \circ h)$, $f \otimes 1 = f = 1 \otimes f$ - trivial

(a) $C_{U \otimes V, W} = (C_{U, V} \otimes 1_W)(1_U \otimes C_{V, W})$

(b) $C_{U, V \otimes W} = (1_V \otimes C_{U, W})(C_{U, V} \otimes 1_W)$

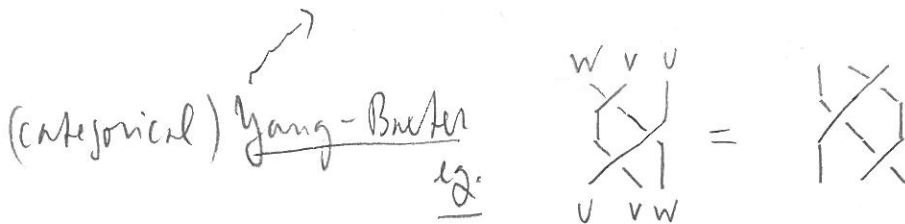
(hexagons - here it is simplified & assuming \otimes strictly ass.)



(axioms for \otimes monoidal cat. are also easy...)

digression on braided monoidal categories

it holds: $(C_{U, V} \otimes 1_W)(1_U \otimes C_{V, W})(C_{U, V \otimes W}) = (1_W \otimes C_{U, V})(C_{U, W} \otimes 1_V)(1_U \otimes C_{V, W})$



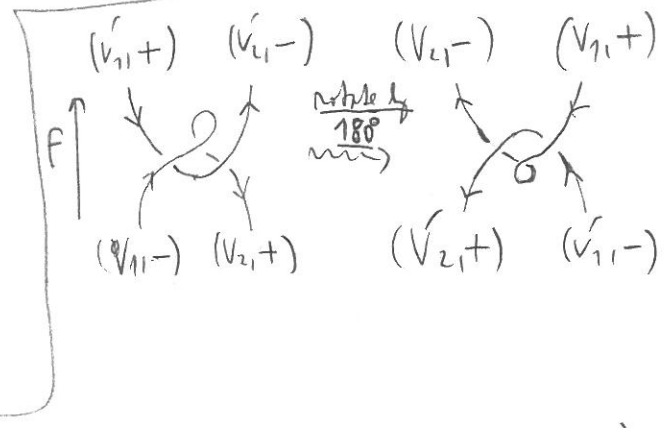
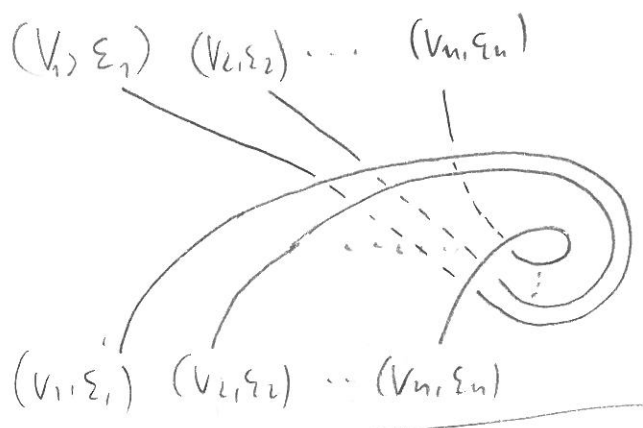
$\gamma = B.$ appears in other contexts - statistical physics, Hopf algebras, \rightarrow Brauer

another example of braided mon. cat:

vector spaces w. usual \otimes (NOT strict, but we ignore it)
 $C_{U, V}: U \otimes V \cong V \otimes U$ satisfies $C_{W, U} C_{U, V} = 1_{U, V}$ in stronger than $\gamma = B.$

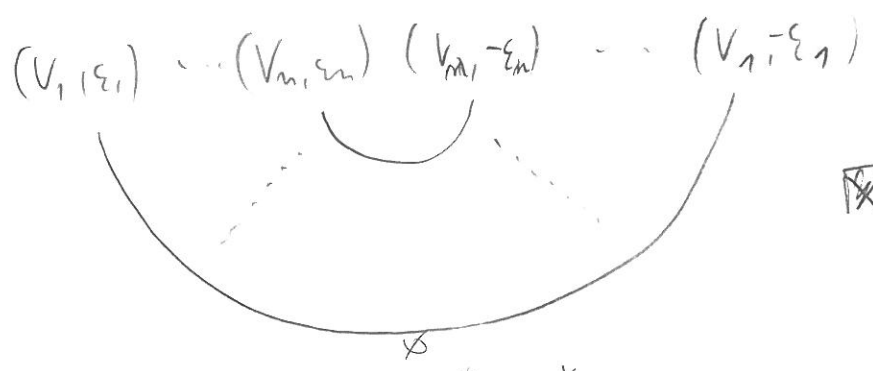
further structure in $\text{Tan}_\mathcal{C}$:

twist $\theta_U: U \rightarrow U$ natural tr. (check!)

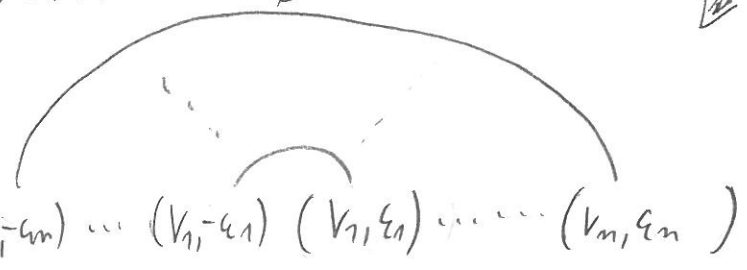


duality: $U \mapsto U^*$; $((V_1, \epsilon_1), \dots, (V_m, \epsilon_m)) \mapsto ((V_1, -\epsilon_1), \dots, (V_m, -\epsilon_m))$
 on morph.: "double mirror image" (contravariant for)

evaluation $d_V: U^* \otimes U \rightarrow 1$... unit of the monoidal cat.
 natural (check!) in $\text{Tan}_\mathcal{C}$, $1 = \emptyset$

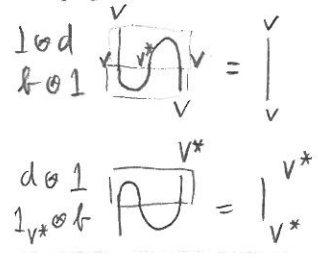


coevaluation $t_V: 1 \rightarrow U \otimes U^*$
 natural (check!) \emptyset



Thm $\text{Tan}_\mathcal{C}$ is a strict ribbon category

PF. (definition): we should verify:
 (a) $(1_V \otimes d_V)(t_V \otimes 1_V) = 1_V$
 (b) $(d_V \otimes 1_{V^*})(1_{V^*} \otimes t_V) = 1_{V^*}$



(c) $\theta_{vw} = C_{wv} C_{vw} (\theta_v \otimes \theta_w)$

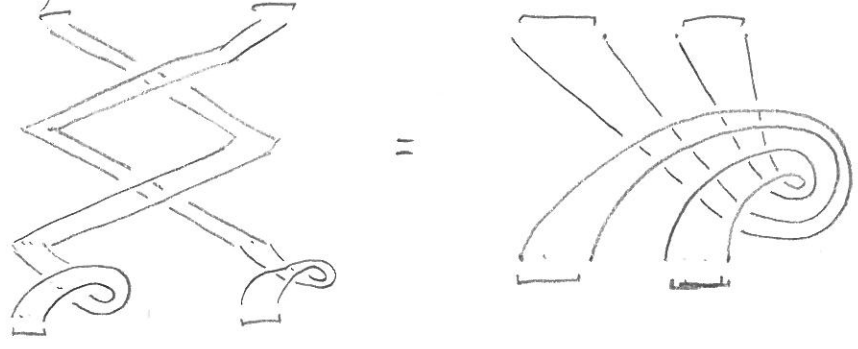


(d) $(\theta_v \otimes 1_{v^*}) k_v = (1_v \otimes \theta_{v^*}) k_v$

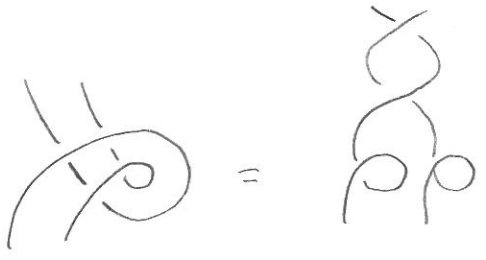


for Tangle, (a), (b) are obvious

(c)



for simplicity, we prove just:

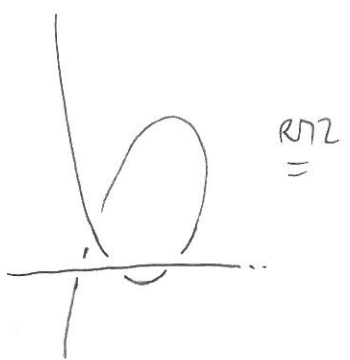
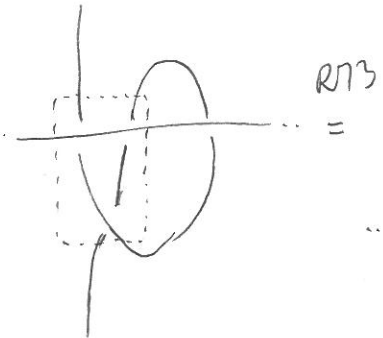


Lemma 1

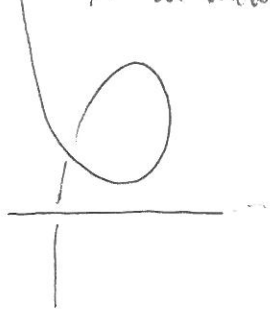


(obv. for Angles but we have framed Angles so we must avoid R11)

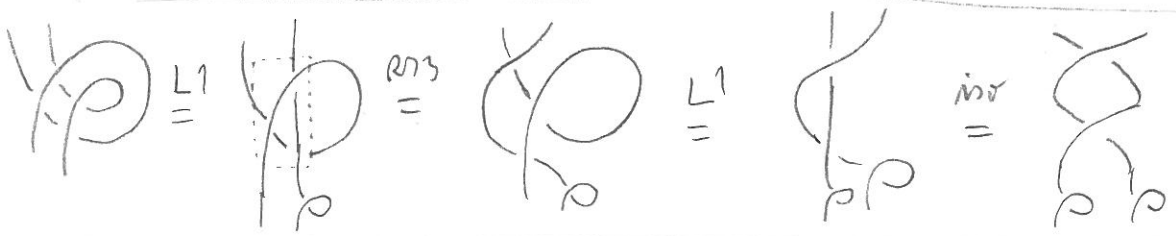
PF: LHS = R12



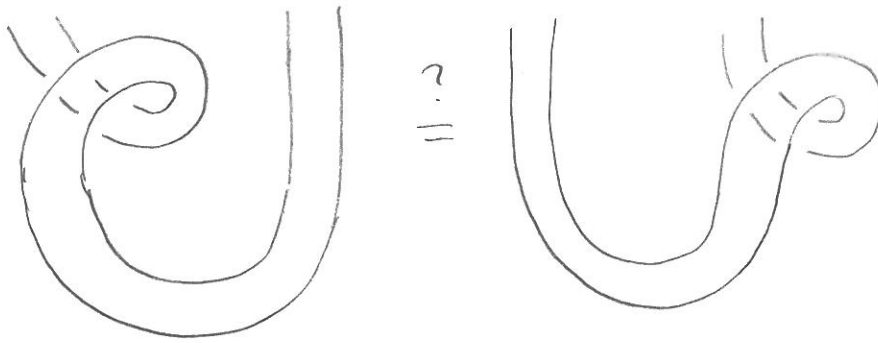
(obv. if directly instead of Angles but we want R1)



QED



(d)



(14)

(obv. by isotopy of tangles, but we want to use $R7$)

for simplicity assume only 2 strands as on the picture

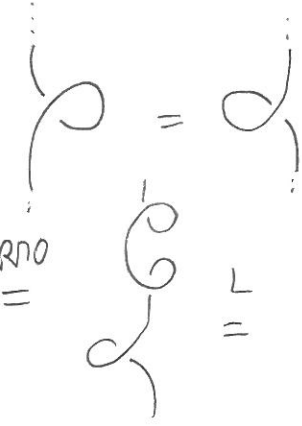
lemma 2

(fixed endpoints)

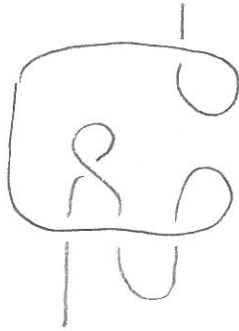
(obv. directly by isotopy of tangles, but inductive to obtain via $R7$)

PF:

RHS =



=



=

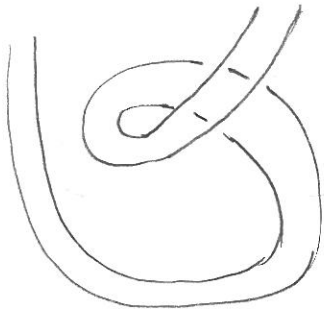


=



□

LHS =



= ?

Ex. Another ribbon category in nature (NOT STRICT) (15)

Finite dimensional vector spaces:

(becomes more complicated)

\otimes as usual the field, 1 dim v.s.
 $C_{UV} = U \otimes V \xrightarrow{\cong} V \otimes U$

symmetric braiding: $c_{UV} c_{UV} = 1_{U \otimes V}$

U^* the usual dual

$U^* \otimes U \xrightarrow{\cong} 1 = k$

$U^* \otimes U \rightarrow 1$... the evaluation $\varphi \otimes v \mapsto \varphi(v)$

$1 \rightarrow U \otimes U^*$... $1 \mapsto \sum_{i=1}^{\dim U} e_i \otimes e_i$ (dual basis)

$\theta_U: U \rightarrow U$... $\theta_U = 1_U$

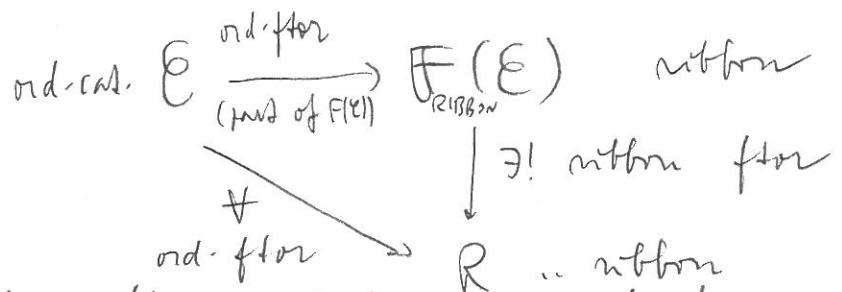
Let \mathcal{E}_0 be the category w. single obj and single mor. $\mathbb{Z}^{\frac{1}{2}}$
 Then $\text{Tan } \mathcal{E}_0$ are essentially unlabelled oriented framed tangles.

Thm (Schum1, 89) (strict?)

$\text{Tan } \mathcal{E}_0$ is equivalent as a ribbon category to the free ribbon category generated by \mathcal{E}_0 .

explanations: • unsure about strict
 • free ribbon category gen. by a cat. \mathcal{E} :

Rib Cat $\xrightarrow{\text{forget}}$ Cat
 $F \dots$ left adjoint



idea of $F(\mathcal{E}_0)$: a) structure "ops" for ribbon cat: $\otimes, 1, c, *, \text{ev}, \text{covev}$

each application of str. op. to an obj. of \mathcal{E} yields a distinct obj. in $F(\mathcal{E}_0)$
 iterate; the iterates are subject to only those relations implied by axioms of ribbon cat.

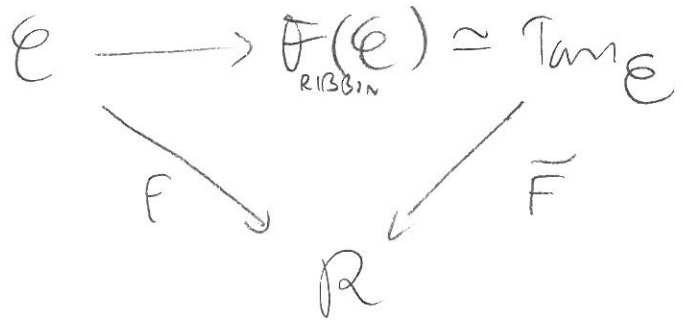
or b) every relation amongst the str. ops which holds in $F(\mathcal{E}_0)$ holds in any ribbon category!

Ex. $\text{Tan } \mathcal{E}_0 = F(\mathcal{E}_0)$ $\text{Tan}: \varphi = \psi = \frac{1}{2}$ Thus in any R: $\varphi = (1 \otimes \text{id})(c \otimes 1)(1 \otimes \psi)$

Thm (Schem 2) Let \mathcal{E} be any cat.

$\text{Tan}_{\mathcal{E}}$ is equivalent as a ~~(strict?)~~ ribbon category to the free ~~strict~~ ribbon category generated by \mathcal{E} .

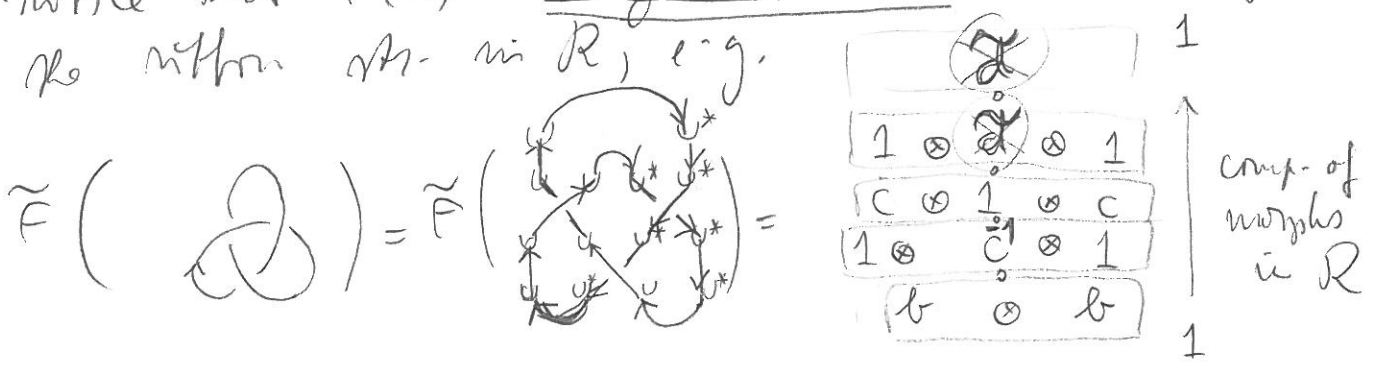
Cor. For any (ord.) fun $\mathcal{E} \xrightarrow{F} \mathcal{R}$, \mathcal{E} ord-cat, \mathcal{R} ribbon,
There is a unique ribbon functor \tilde{F} s.t.



In particular, any ribbon category yields an ^{isotopy} invariant of tangles (by choosing $\mathcal{E} = \mathcal{E}_0$)
 (isotopy class of) (up to undecorated tangles $\text{Tan}_{\mathcal{E}_0}$)

In particular, any \mathbb{Y} -link is a morphism $L \in \text{Hom}_{\text{Tan}_{\mathcal{E}_0}}(\emptyset, \emptyset)$
 Thus $\tilde{F}(L) \in \text{Hom}_{\mathcal{R}}(1, 1)$ is an isotopy invariant of L .

Notice that $\tilde{F}(L)$ is easy computable in terms of the ribbon str. in \mathcal{R} , e.g.



applications

- a) $\mathcal{R} =$ ribbon cat. of modules over a ribbon Hopf algebra (= quantum group & ...) H ,
 in particular H a quantum group (a root of?)
- b) Dehn surgery of 3-manifold - constructing the man. out of a \mathcal{E} -colored link \Rightarrow invariants of the man.

c) Kauffman bracket via Skein's Theory

(artificial ...)

def. The ribbon cat. of "skein tangles" $SkTan_{\mathbb{C}_0}$:

"idea: \mathbb{C} -linearization of $Tan_{\mathbb{C}_0}$, morphisms are factorized by the skein relations used to define K. bracket."

objects: as in $Tan_{\mathbb{C}_0}$, i.e. $(\mathbb{C}_1, \mathbb{C}_2, \dots)$ regimes of obj. of \mathbb{E} w. \mathbb{C} 's

morphs: $SkTan_{\mathbb{C}_0}(X, Y) := \text{FreeMod } Tan_{\mathbb{C}_0}(X, Y) / \mathbb{C}[a, \bar{a}]$

$$\bigcirc = 1$$

$$T \sqcup \bigcirc = -(a^2 + \bar{a}^2) T$$

$$\left(\begin{array}{c} \diagup \\ \diagdown \end{array} \right) = a \left(\begin{array}{c} \diagdown \\ \diagup \end{array} \right) + \bar{a} \left(\begin{array}{c} \diagup \\ \diagdown \end{array} \right)$$

$a \in \mathbb{C}$
fixed

claim: $SkTan_{\mathbb{C}_0}$ inherits the ribbon cat. str. from $Tan_{\mathbb{C}_0}$.

Obvious, the ftr $\tilde{F}: Tan_{\mathbb{C}_0} \rightarrow SkTan_{\mathbb{C}_0}$

reduced to $\tilde{F}(f) \in SkTan_{\mathbb{C}_0}(\emptyset, \emptyset) \cong \mathbb{C}[a, \bar{a}]$

$f \in Hom_{Tan_{\mathbb{C}_0}}(\emptyset, \emptyset)$

is the Kauffman bracket.

? modification for Jones Polynomial:

redefine the braiding (check axioms!)
possibly has to alter more structure!

$$c'_{UV} = -\bar{a}^3 c_{UV}$$

$$c'^{-1}_{UV} = -a^3 c^{-1}_{UV}$$

