Linear SEE's with additive noise of Volterra type

P. Čoupek, B. Maslowski Charles University in Prague



ROBUST 2016 September 13, 2016

The problem

The stochastic Cauchy problem

$$dX_t = AX_t \, dt + \Phi \, dB_t \quad t \in [0, T]$$
$$X_0 = x$$

 $U, V \qquad \dots$ $A : \text{Dom}(A) \subset V \to V \qquad \dots$ $B = (B_t, t \in [0, T]) \qquad \dots$ $\Phi \in \mathcal{L}(U, V) \qquad \dots$ $x \in V \qquad \dots$

- real, separable Hilbert spaces
- generates a C_0 -semigroup of operators on V
- \sim infinite-dimensional noise in U
- . diffusion term
- .. initial condition

Typical Examples

Stochastic heat equation:

$$\begin{split} \partial_t u &= \Delta u + \eta \quad \text{ on } [0,T] \times \mathcal{O} \\ u(0,\cdot) &= f \quad \text{ on } \mathcal{O} \\ u|_{[0,T] \times \partial \mathcal{O}} &= 0 \end{split}$$

Stochastic wave equation:

$$\begin{split} \partial^2_{tt} u &= \Delta u + \eta \quad \text{ on } [0,T] \times \mathcal{O} \\ u(0,\cdot) &= f_1 \quad \text{ on } \mathcal{O} \\ \partial_t u(0,\cdot) &= f_2 \text{ on } \mathcal{O} \\ u|_{[0,T] \times \partial \mathcal{O}} &= 0 \end{split}$$

 $\mathcal{O} \subset \mathbb{R}^d$... bounded domain with smooth boundary f, f_1, f_2 ... given functions ... space-time noise process

Mild solution

Stochastic evolution equation (SEE):

$$dX_t = AX_t dt + \Phi dB_t \quad t \in [0, T]$$
$$X_0 = x$$

Mild solution:

$$X_t = S(t)x + \int_0^t S(t-r)\Phi \, dB_t \quad t \in [0,T]$$

Mild solution

Stochastic evolution equation (SEE):

$$dX_t = AX_t dt + \Phi dB_t \quad t \in [0, T]$$
$$X_0 = x$$

Mild solution:

$$X_t = S(t)x + \int_0^t S(t-r)\Phi \, dB_t \quad t \in [0,T]$$

We need to be able

- give meaning to the convolution integral
- ▶ prove that $X = (X_t, t \in [0, T])$ has measurable sample paths
- ▶ prove that X has continuous sample paths

Mild solution

Stochastic evolution equation (SEE):

$$dX_t = AX_t dt + \Phi dB_t \quad t \in [0, T]$$
$$X_0 = x$$

Mild solution:

$$X_t = S(t)x + \int_0^t S(t-r)\Phi \, dB_t \quad t \in [0,T]$$

We need to be able

- give meaning to the convolution integral
- ▶ prove that $X = (X_t, t \in [0, T])$ has measurable sample paths
- ▶ prove that X has continuous sample paths

But how to define the integral when B is neither a semimartingale, nor a Gaussian process?

Volterra processes

K ... so-called regular Volterra kernel (see poster for the definition)

Definition

A stochastic process $b = (b_t, t \in [0, T])$ is called a Volterra process if

(i) b is centered with $b_0 = 0$ (ii) b is ε -Hölder continuous for every $\varepsilon \in (0, \delta)$ for some $\delta > 0$ (iii) the covariance of b is

$$R(s,t) = \int_0^{s \wedge t} K(s,r)K(t,r)dr, \quad s,t \in [0,T].$$

Volterra processes

K ... so-called regular Volterra kernel (see poster for the definition)

Definition

A stochastic process $b = (b_t, t \in [0, T])$ is called a Volterra process if

(i) b is centered with $b_0 = 0$ (ii) b is ε -Hölder continuous for every $\varepsilon \in (0, \delta)$ for some $\delta > 0$ (iii) the covariance of b is

$$R(s,t) = \int_0^{s \wedge t} K(s,r)K(t,r)dr, \quad s,t \in [0,T].$$

Examples:

- fractional Brownian motion of $H > \frac{1}{2}$
- Rosenblatt process

The poster

Where to find the poster



How to read the poster



Thank you for your 10 minutes and please, stop by!