

# A welcome conservative talk

Libor Barto

McMaster University  
and  
Charles University

Algebra & CSP workshop, Toronto, August 2011

**A** ... fixed finite idempotent algebra

## Definition (CSP(**A**) - Constraint Satisfaction Problem over **A**)

### INSTANCE:

$V$  ... set of variables

$\mathcal{C}$  ... set of constraints

**constraint** ... pair  $(\mathbf{x}, R)$ , where

$\mathbf{x} = (x_1, \dots, x_k) \in V^k$  (**scope**)    assume  $x_1, \dots, x_k$  distinct  
 $R \leq \mathbf{A}^k$  (**constraint relation**)

**QUESTION:** Does there exist a solution?

**solution** ... mapping  $f : V \rightarrow A$  such that  $f(\mathbf{x}) \in R$   
for each  $(\mathbf{x}, R) \in \mathcal{C}$

# Conservative CSPs

$\mathbf{A}$  is **conservative**, if  $B \leq \mathbf{A}$  for every  $B \subseteq A$

## Theorem (Bulatov)

*Let  $\mathbf{A}$  be conservative. If  $\mathbf{A}$  is Taylor, then  $\text{CSP}(\mathbf{A})$  is tractable.  
(And otherwise  $\text{CSP}(\mathbf{A})$  is NP-complete. )*

Proof is long, complicated case analysis

2 new proofs

- (a) using absorption, Prague strategies and one new algebraic result about conservative algebras  $\mathbf{B}$   
(today)
- (b) using Bulatov's colors and Maróti's retraction trick [Bulatov](#)  
(tomorrow)

## Algorithm (simplified):

- ▶ Make the instance  $(2, 3)$ -minimal (old stuff)
- ▶ Find (using walking) a 1-minimal subinstance going through minimal absorbing subuniverses (old stuff)
- ▶ Use “Rectangularity theorem” (the only new stuff) to either find a solution, or shrink the instance

## Outline:

- ▶ Consistency notions ( $(k, l)$ -minimality)
- ▶ Walking and Prague strategies
- ▶ Absorption, finding nice MASes
- ▶ Rectangularity theorem – baby case
- ▶ Algorithm for binary constraints, simplified
- ▶ Algorithm for binary constraints, real
- ▶ Rectangularity theorem

## Definition (1-minimality)

An instance of CSP( $\mathbf{A}$ ) is **1-minimal**, if

- ▶ for every  $x \in V$  there is a unique constraint with scope  $(x)$   
...  $((x), S_x)$
- ▶ for every  $((x_1, \dots, x_k), R) \in \mathcal{C}$  and every  $i$ , the projection of  $R$  to the  $i$ -th coordinate is equal to  $S_{x_i}$   
i.e.  $R$  is subdirect in  $S_{x_1} \times \dots \times S_{x_k}$

## Definition (1-minimality)

An instance of  $\text{CSP}(\mathbf{A})$  is **1-minimal**, if

- ▶  $\forall x \in V$  unique  $((x), S_x) \in \mathcal{C}$
- ▶  $\forall ((x_1, \dots, x_k), R) \in \mathcal{C} \Rightarrow R \leq_S S_{x_1} \times \dots \times S_{x_k}$

## Definition ((2,3)-minimality, standard definition)

A 1-minimal instance of  $\text{CSP}(\mathbf{A})$  is **(2,3)-minimal**, if

- ▶ for every  $x_1 \neq x_2 \in V$  there is a unique constraint with scope  $(x_1, x_2) \dots ((x_1, x_2), S_{x_1, x_2})$  (let  $S_{x,x} = \{(a, a) : a \in S_x\}$ )
- ▶ for every  $(\mathbf{x}, R) \in \mathcal{C}$  whose scope contains  $x_1, x_2$ , the projection of  $R$  to the corresponding coordinates is equal to  $S_{x_1, x_2}$
- ▶ every triple of variables is within a scope of some constraint

## Definition (1-minimality)

An instance of  $\text{CSP}(\mathbf{A})$  is **1-minimal**, if

- ▶  $\forall x \in V$  unique  $((x), S_x) \in \mathcal{C}$
- ▶  $\forall ((x_1, \dots, x_k), R) \in \mathcal{C} \Rightarrow R \leq_S S_{x_1} \times \dots \times S_{x_k}$

## Definition ((2,3)-minimality, essentially the same)

A 1-minimal instance of  $\text{CSP}(\mathbf{A})$  is **(2,3)-minimal**, if

- ▶ for every  $x_1 \neq x_2 \in V$  there is a unique constraint with scope  $(x_1, x_2) \dots ((x_1, x_2), S_{x_1, x_2})$  (let  $S_{x, x} = \{(a, a) : a \in S_x\}$ )
- ▶ for every  $(\mathbf{x}, R) \in \mathcal{C}$  whose scope contains  $x_1, x_2$ , the projection of  $R$  to the corresponding coordinates is equal to  $S_{x_1, x_2}$
- ▶ for every  $x_1, x_2, x_3 \in V$  and every  $(a, b) \in S_{x_1, x_2}$  there exists  $c$  such that  $(a, c) \in S_{x_1, x_3}$  and  $(b, c) \in S_{x_2, x_3}$

## Walking in 2-minimal instances

If  $R \subseteq A^2$  and  $B \subseteq A$ , let  $R^+[B] = \{c \in A : \exists b \in B (b, c) \in R\}$

Let  $x, y \in V$  and  $\emptyset \neq B \leq \mathbf{S}_x$ ,  $\emptyset \neq C \leq \mathbf{S}_y$ . We write

$$(x, B) \leq_1 (y, C) \quad \text{iff} \quad S_{x,y}^+[B] = C$$

$\leq \dots$  the transitive closure of  $\leq_1 \Rightarrow$  qoset **QOSET**

Write  $(x, B) \sim (y, C)$ , if  $(x, B) \leq (y, C) \leq (x, B)$

**Definition** (Prague strategy, for 2-minimal instances)

A 2-minimal instance is a **Prague strategy**, if  
 $(x, B) \sim (y, C)$  implies  $(x, B) \leq_1 (y, C)$

In general, Prague strategy = 1-minimal instance + ...

Our definition suffices for instances with at most binary constraints

**Fact**

*Every (2, 3)-minimal instance is a Prague strategy.*



# Absorption

## Definition

$B$  is an **absorbing subuniverse** of  $\mathbf{T}$ , if  $\mathbf{T}$  has a term  $t$  such that for every coordinate  $i$

$$t(B, B, \dots, B, T, B, B, \dots, B) \subseteq B \quad (T \text{ is at the } i\text{-th coordinate})$$

Notation:  $B \triangleleft \mathbf{T}$ .

## Definition

$B$  is a **minimal absorbing subuniverse** of  $\mathbf{T}$  if  $B \triangleleft \mathbf{T}$  and  $\mathbf{B}$  has no proper absorbing subuniverses. Notation:  $B \triangleleft\triangleleft \mathbf{T}$ .

## Fact

*If  $P$  is a Prague strategy,  $B_x \triangleleft \mathbf{S}_x$  and the restriction of  $P$  to  $B$ 's is 1-minimal, then this restriction is a Prague strategy.*

# Subalgorithm

## Fact

*Let  $P$  be a Prague strategy over  $\mathbf{A}$ . There exist  $E_x \ll \mathbf{S}_x$ ,  $x \in V$  such that the restriction of  $P$  to  $E$ 's is a Prague strategy. Moreover, there is a  $P$ -time algorithm for finding such  $E$ 's.*

## Proof.

- ▶ Consider subset  $\text{AbsQoset}$  of  $\text{QOSET}$  formed by all pairs  $(x, B)$  such that  $B$  is a proper absorbing subuniverse of  $\mathbf{S}_x$  (fact: it is an upset)
- ▶ Find a maximal component  $\{(x, R_x) : x \in W\}$  of  $\text{AbsQoset}$  (where  $W \subseteq V$ ). Define  $R_x = S_x$  for  $x \in V - W$
- ▶ The restriction of  $P$  to  $R$ 's is 1-minimal (because  $P$  is a Prague strategy)
- ▶ This restriction is a Prague strategy (from the previous fact)
- ▶ Restrict and repeat

## Fact

*Let  $P$  be a Prague strategy over  $\mathbf{A}$ . There exist  $E_x \ll \mathbf{S}_x$ ,  $x \in V$  such that the restriction of  $P$  to  $E$ 's is a Prague strategy.*

*(We will only need that the restriction is 1-minimal.)*

*Moreover, there is a  $P$ -time algorithm for finding such  $E$ 's.*

- ▶ Works for Prague strategies over arbitrary idempotent algebra (not necessarily conservative, not necessarily Taylor)
- ▶ Proves that NU implies width (2, 3)

Fact (Inspiration: Bulatov's original proof)

Let

- ▶  $\mathbf{T}_1, \mathbf{T}_2$  be conservative Taylor algebras
- ▶  $R \leq_S \mathbf{T}_1 \times \mathbf{T}_2$ ,
- ▶  $B_1 \ll \mathbf{T}_1, B_2 \ll \mathbf{T}_2$
- ▶  $R \cap (B_1 \times B_2) \neq \emptyset$
- ▶  $\exists a_1 \in T_1 - B_1 \exists b_2 \in B_2 (a_1, b_2) \in R$

Then  $B_1 \times B_2 \subseteq R$ .

# Proof of the baby case

## Proof.

- ▶ Draw a potato picture. “linked” below means connected on the picture.
- ▶ Let  $S = R \cap (B_1 \times B_2)$
- ▶  $S \leq_S B_1 \times B_2$  (as the projection of  $S$  to the first coordinate absorbs  $B_1$ )
- ▶ Let  $C =$  all elements not  $R$ -linked to  $a_1$
- ▶ If  $C = \emptyset$ , then
  - ▶  $S$  is linked (use the fact that connectivity is absorbed)
  - ▶  $S = B_1 \times B_2$  (using Absorption Theorem)
- ▶ If  $C \neq \emptyset$ , then  $C \triangleleft \mathbf{B}_1$  (using conservativity)



# Algorithm for binary constraints, simplified

Assume that

- ▶ We can solve instances over smaller domains in P-time
- ▶ All constraints are at most binary

The algorithm:

1. Find an equivalent  $(2, 3)$ -minimal instance  $P$
2. **Assume that every  $S_x$  has a proper absorbing subuniverse**
3. Find  $\{E_x : x \in V\}$  such that  $E_x \ll S_x$  and the restriction of  $P$  to  $E$ 's is 1-minimal (use the subalgorithm)
4. Find a partition  $V = V_1 \cup \dots \cup V_l$  such that  $(x, E_x) \sim (y, E_y)$  whenever  $x, y$  are in the same  $V_i$  (strands)
5. Using inductive assumption, find partial solutions  $f_i : V_i \rightarrow A$ .
  - ▶ If some  $f_i$  does not exist, then we can delete  $E_x$  from  $S_x$ ,  $x \in V_i$  and start again
  - ▶ If all  $f_i$  exist, then  $\cup f_i$  is a solution by Rectangularity theorem, baby case

# Algorithm for binary constraints

1. Find an equivalent (2, 3)-minimal instance  $P$
2. Consider the subqoset  $\text{NafaQoset}$  of  $\text{QOSET}$  formed by  $(x, B)$  such that  $\mathbf{B}$  has a proper absorbing subuniverse
3. If  $\text{NafaQoset}$  is nonempty
  - ▶ Find a maximal component  $\{(x, D_x) : x \in W\}$  of  $\text{NafaQoset}$
  - ▶ Let  $Q$  be the restriction of  $P$  to  $D$ 's
  - ▶ Find  $E$ 's for the instance  $Q$  as before
  - ▶ Solve in strands as before, if impossible, delete  $E_x$  and go to 1.
  - ▶ Delete  $D_x - E_x$ ,  $x \in W$  and go to 1.
4. If  $\text{NafaQoset}$  is empty, then we are Mal'tsev (use WNU)

For general constraints:

- ▶ The algorithm is the same
- ▶ The proof of correctness requires Rectangularity Theorem in full generality:

# Rectangularity theorem

## Theorem

Let

- ▶  $\mathbf{T}_1, \mathbf{T}_2, \dots, \mathbf{T}_n$  be conservative Taylor algebras
- ▶  $R \leq_S \mathbf{T}_1 \times \mathbf{T}_2 \times \dots \times \mathbf{T}_n$ ,
- ▶  $B_1 \triangleleft \mathbf{T}_1, B_2 \triangleleft \mathbf{T}_2, \dots, B_n \triangleleft \mathbf{T}_n$
- ▶  $R \cap (B_1 \times B_2 \times \dots \times B_n) \neq \emptyset$

Define

- ▶  $i \sim j$  if  $R|_{i,j}^+[B_i] = B_j$  and  $R|_{j,i}^+[B_j] = B_i$ , where  $R|_{i,j}$  is the projection of  $R$  to coordinates  $i, j$

Then a tuple  $\mathbf{a} = (a_1, \dots, a_n) \in B_1 \times \dots \times B_n$  belongs to  $R$  whenever  $a_K \in R_K$  for every  $\sim$ -class  $K$ .



# A note on binary constraints

Using (Hell, Rafiey or Kazda) and  $(SD(\wedge) \Rightarrow BW)$ :

## Theorem

*Let  $\mathbb{A}$  be a conservative relational structure (i.e. containing all unary relations) with at most binary relations.  
If  $\text{Pol}(\mathbb{A})$  is Taylor then  $\text{CSP}(\mathbb{A})$  has width  $(2, 3)$ .*

## A conversation

**CS guy:** Hi, I have this conservative tractable relational structure  $\mathbb{A}$ . Give me the P-time algorithm for solving CSP over  $\mathbb{A}$ !

**me:** Hi, first you have to give me a list of all absorbing subuniverses of all subalgebras of  $\text{Pol}(\mathbb{A})$ .

**CS guy:** ?????????????? ok, how do I find them?

**me:** I don't know. I don't know whether it's decidable that a given set is an absorbing subuniverse of  $\text{Pol}(\mathbb{A})$  for a given set  $\mathbb{A}$  of relations on  $A$  (or of a given algebra)...

**CS guy:** So you proved that a P-time algorithm exists without providing the algorithm????

**me:** Yes.

**CS guy:** I don't like it. And I don't like you.

**me:** I love it. And I don't like you too.

**CS guy:** See you.

**me:** See you.

# Decidability of absorption

## Problem

*Is the following problem decidable? Input is a finite algebra  $\mathbf{A}$  and a subset  $B$ . Question is whether  $B \triangleleft \mathbf{A}$ .*

Affirmative answer would generalize Maróti's result that NU is decidable

Special cases:  $|B| = 1$ ,  $\mathbf{A}$  is conservative,  $\mathbf{A}$  is Taylor,  $\mathbf{A}$  is  $SD(\wedge)$ ,  $\mathbf{A}$  is Mal'tsev

## Problem

*Is the following problem decidable? Input is a finite relational structure  $\mathbb{A}$  and a subset  $B$ . Question is whether  $B \triangleleft \text{Pol}(\mathbb{A})$ .*

Affirmative answer would generalize the result that NU is decidable

Recent progress: decidable in  $SD(\wedge)$  case (see Jakub Bulín's talk)

## More problems

Dichotomy holds for any  $\mathbf{B}$  in HSP of a conservative algebra...

### Problem

*Characterize algebras which are in  $\text{HSP}(\mathbf{A})$  for some  $\mathbf{A}$  conservative.*

Recall that for a binary conservative relational structure  $\mathbb{A}$ ,  
 $\text{Pol}(\mathbb{A})$  is Taylor  $\Rightarrow \text{Pol}(\mathbb{A})$  is  $\text{SD}(\wedge)$ ...

Also if  $\mathbb{A}$  contains a single binary relation, then  
 $\text{Pol}(\mathbb{A})$  has Mal'tsev  $\Rightarrow \text{Pol}(\Gamma)$  has majority (Kazda + ?)

### Problem

*Take two important properties  $\text{Prop}_1$ ,  $\text{Prop}_2$  of finite algebras (like omitting types, Mal'tsev, FS...).*

*Is it true that for every conservative relational structure  $\mathbb{A}$  with (i) at most binary relations (ii) at most one binary relation,  $\text{Pol}(\mathbb{A})$  has  $\text{Prop}_1 \Rightarrow \text{Pol}(\mathbb{A})$  has  $\text{Prop}_2$ ?*