

Constraint Satisfaction Problems

Part I: Complexity, Logic, Algebra

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CoCoSym: Symmetry in Computational Complexity

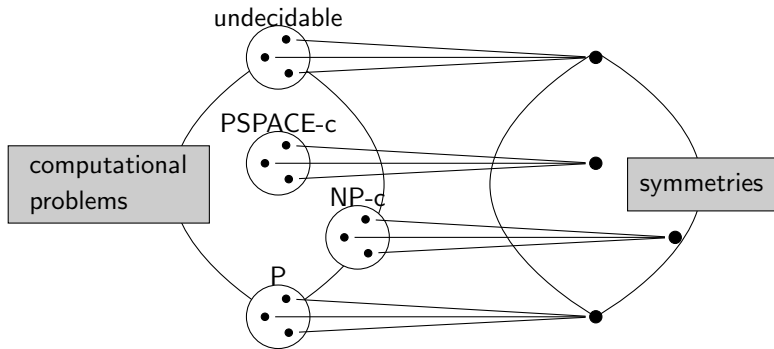
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... there will also be three more focused topics, providing examples of (...) interactions between logic, algebra, and complexity

- ▶ Part I: logic, algebra, and complexity in
Constraint Satisfaction Problems (CSPs)
over fixed finite templates
- ▶ Part II: analysis, probability, and topology in
(a variant of) CSP

In CSP: complexity captured by symmetry

CoolFunc: computational problems \rightarrow objects capturing symmetry
 kernel of CoolFunc = polynomial time reducibility



CSPs over fixed finite templates

- ▶ tiny portion of problems on the left
- ▶ kernel \subsetneq polynomial time reducibility

CSP

Fix $\mathbb{A} = (A; R, S, \dots)$ relational structure

Definition ($\text{CSP}(\mathbb{A})$)

Input: pp-sentence ϕ , eg. $(\exists x_1 \exists x_2 \dots) R(x_1, x_3) \wedge S(x_5, x_2) \wedge \dots$

Answer Yes: ϕ satisfied in \mathbb{A}

Answer No: ϕ not satisfied in \mathbb{A}

Search version: Find a satisfying assignment.

Search looks harder, but it's not [Bulatov, Jeavons, Krokhin'05]

Fact: Always in NP.

$\mathbb{K}_3 = (A; R)$ where

- ▶ $A = \{\textit{lilac}, \textit{mauve}, \textit{cyclamen}\}$
- ▶ $R =$ (binary) inequality relation on A

Input of $\text{CSP}(\mathbb{K}_3)$ is, e.g.

$$(\exists x_1 \exists x_2 \dots \exists x_4) R(x_1, x_2) \wedge R(x_1, x_3) \wedge R(x_1, x_4) \wedge R(x_2, x_3) \wedge R(x_2, x_4)$$

Viewpoint

- ▶ variables = vertices
- ▶ clauses (constraints) = edges

$\text{CSP}(\mathbb{K}_3)$ is the 3-coloring problem for graphs

Fact: It is NP-hard (7-coloring NP-hard, 2-coloring in P)

- ▶ $3NAE_2 = (\{0, 1\}; 3NAE_2)$ where
 $3NAE_2 = \text{all but } \{(0, 0, 0), (1, 1, 1)\}$
 $CSP(3NAE_2) = \text{positive not-all-equal 3-SAT}$
 $= \text{2-coloring problem for 3-uniform hypergraphs}$
- ▶ $3NAE_4 = (\{0, 1, 2, 3\}; 3NAE_4)$, where $3NAE_4$ still ternary
 $CSP(3NAE_4) = \text{4-coloring problem for 3-uniform hypergraphs}$
- ▶ $1IN3 = (\{0, 1\}; 1in3)$ where
 $1in3 = \{(0, 0, 1), (0, 1, 0), (1, 0, 0)\}$
 $CSP(1IN3) = \text{positive 1-in-3 SAT}$

Fact: All NP-hard

$3\text{LIN}_5 = (\mathbb{Z}_5; L_{0000}, L_{0001}, \dots, L_{4444})$ where e.g.

$$L_{1234} = \{(x, y, z) \in \mathbb{Z}_5^3 : 1x + 2y + 3z = 4\}$$

(note: relations are affine subspaces of \mathbb{Z}_5^3)

$\text{CSP}(3\text{LIN}_5) =$ solving systems of linear equations in \mathbb{Z}_5

Fact: In P

Symmetry

polymorphism of \mathbb{A} : mapping $f : A^n \rightarrow A$
compatible with every relation

compatible with R : f applied component-wise to tuples in R
is a tuple in R

Example: $f(x_1, \dots, x_4) = 2x_1 + 3x_2 + 3x_3 + 3x_4 \quad f : \mathbb{Z}_5^4 \rightarrow \mathbb{Z}_5$
is compatible with each L_{abcd}
because $f(\mathbf{v}_1, \dots, \mathbf{v}_4)$ is an affine combination of these
vectors (as $2 + 3 + 3 + 3 = 1$)
and L_{abcd} is an affine subspace

$\text{Pol}(\mathbb{A})$: the set of all polymorphisms (it is a “clone”)
= set of (multivariable) symmetries of \mathbb{A}

Jeavons'98: On the algebraic structure of combinatorial problems

Theorem

*Complexity of $\text{CSP}(\mathbb{A})$ is determined by $\text{Pol}(\mathbb{A})$:
If $\text{Pol}(\mathbb{A}) \subseteq \text{Pol}(\mathbb{B})$ then $\text{CSP}(\mathbb{B})$ reduces to $\text{CSP}(\mathbb{A})$.*

Proof.

If $\text{Pol}(\mathbb{A}) \subseteq \text{Pol}(\mathbb{B})$, then relations in \mathbb{B} can be defined from relations in \mathbb{A} by a pp-formula.

[Geiger'69, Bondarčuk, Kalužnin, Kotov, Romov'69]

This gives a computational reduction of $\text{CSP}(\mathbb{B})$ to $\text{CSP}(\mathbb{A})$. \square

So: $\text{CSP}(3\text{LIN}_5)$ is in P because 3LIN_5 has a lot of polymorphs
 $\text{CSP}(1\text{IN}3)$ is NP-complete because $1\text{IN}3$ has few

System of functional equations is, e.g.

$$f(g(x, y), z) = g(x, h(y, z))$$

$$m(y, x, x) = m(y, y, y)$$

$$m(x, x, y) = m(y, y, y)$$

Satisfied in \mathcal{M} , where \mathcal{M} is a set of functions:
symbols can be interpreted in \mathcal{M} so that
each equality is (universally) satisfied

Example: The above system is satisfied in $\text{Pol}(3\mathbb{L}\text{IN}_5)$:

- ▶ take $f(x, y) = g(x, y) = h(x, y) = x$
(note: projections are always polymorphisms)
- ▶ take $m(x, y, z) = x - y + z$

Bulatov, Jeavons, Krokhin'05: Classifying the complexity of constraints using finite algebras + Bodirsky'08: PhD thesis

Theorem

*Complexity of $\text{CSP}(\mathbb{A})$ is determined by systems of functional equations satisfied in $\text{Pol}(\mathbb{A})$:
If each system satisfied in $\text{Pol}(\mathbb{A})$ is satisfied in $\text{Pol}(\mathbb{B})$,
then $\text{CSP}(\mathbb{B})$ reduces to $\text{CSP}(\mathbb{A})$.*

Proof.

Previous theorem, pp-definitions \rightarrow pp-interpretations,
the HSP theorem [Birkhoff'35] □

So: $\text{CSP}(\text{3LIN}_5)$ is in P because
 $\text{Pol}(\text{3LIN}_5)$ satisfies strong systems of functional equations.

Barto, Opršal, Pinsker'18: The wonderland of reflections

minor condition = system of functional equations, each of the form
 $symbol(variables) = symbol(variables)$,
e.g. $m(y, x, x) = m(y, y, y)$, $m(x, x, y) = m(y, y, y)$

Theorem

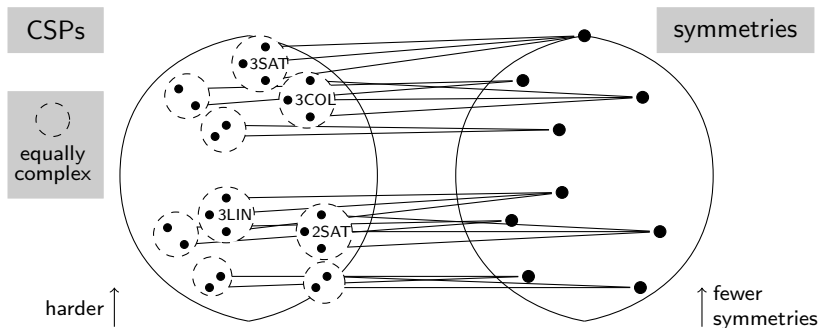
*Complexity of $CSP(\mathbb{A})$ determined by
minor conditions satisfied in $Pol(\mathbb{A})$:*

*If each minor condition satisfied in $Pol(\mathbb{A})$ is satisfied in $Pol(\mathbb{B})$,
then $CSP(\mathbb{B})$ reduces to $CSP(\mathbb{A})$.*

Proof.

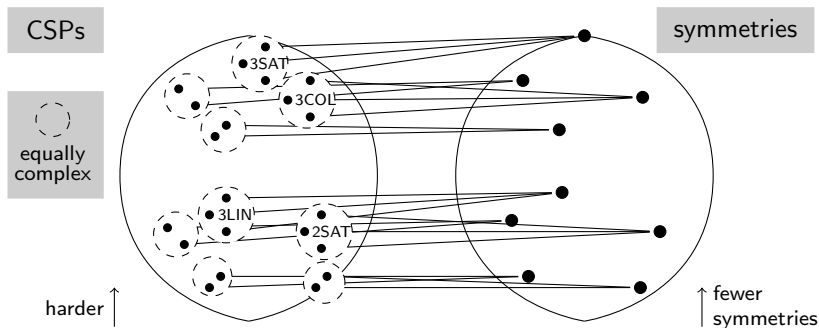
pp-interpretation \rightarrow pp-construction,
version of the HSP theorem.





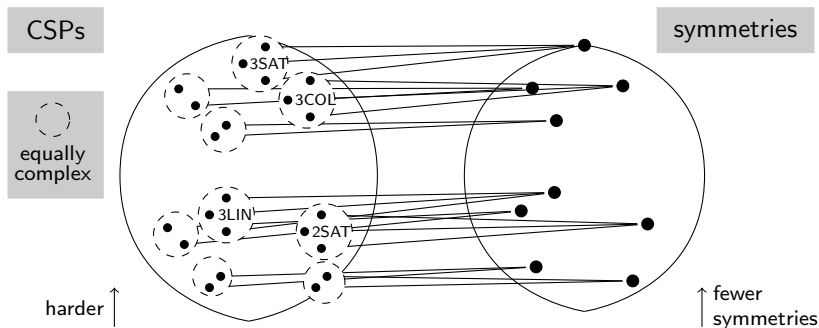
- (1) polymorphisms
- (2) systems of functional equations satisfied by polymorphisms
- (3) minor conditions satisfied by polymorphisms

Where are the borderlines between complexity classes?



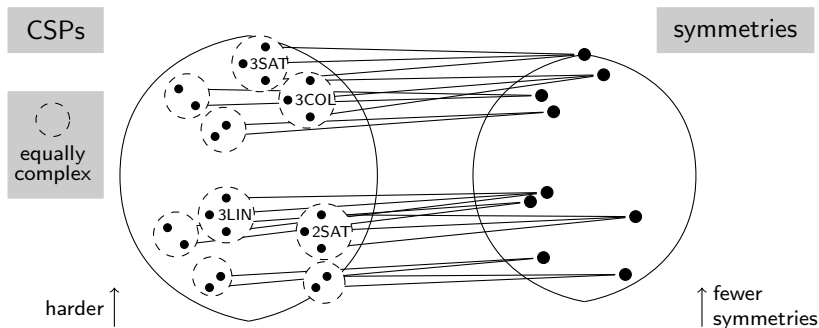
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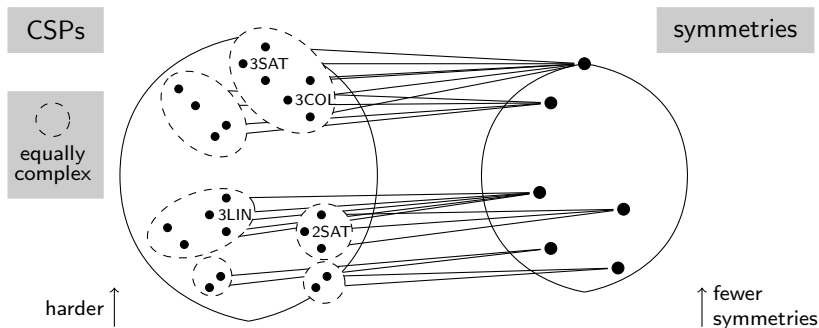
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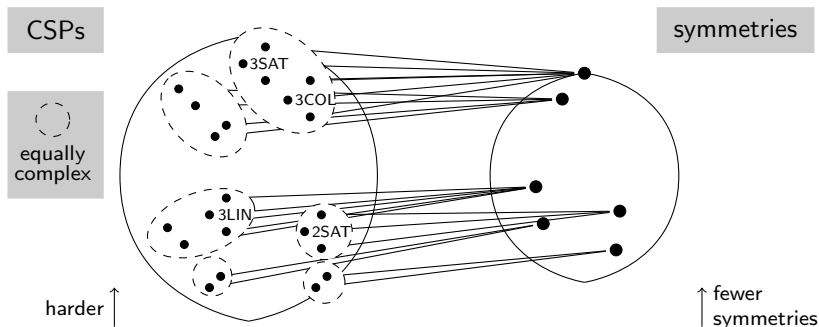
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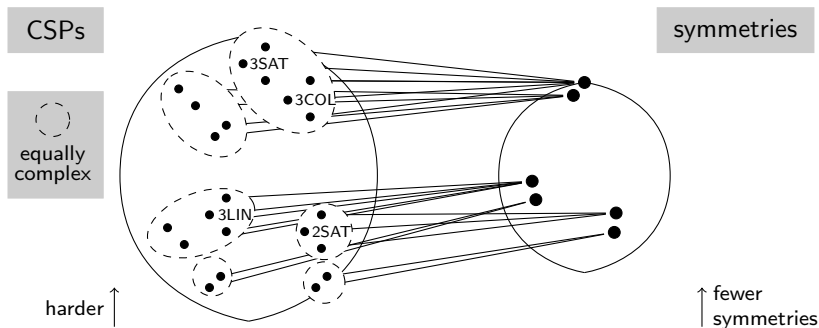
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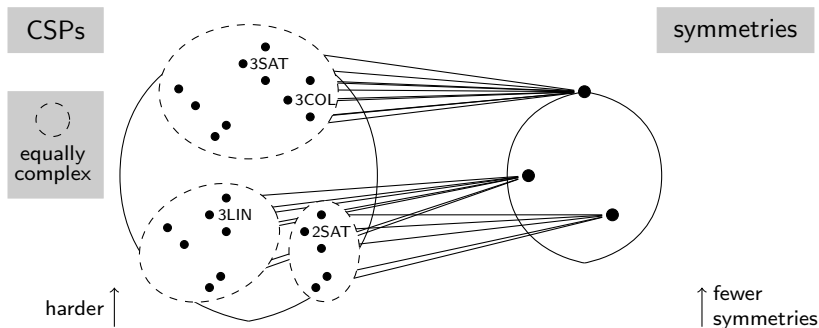
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Where are the borderlines between complexity classes?

Minor condition is **trivial**:

satisfied in every $\text{Pol}(\mathbb{A})$

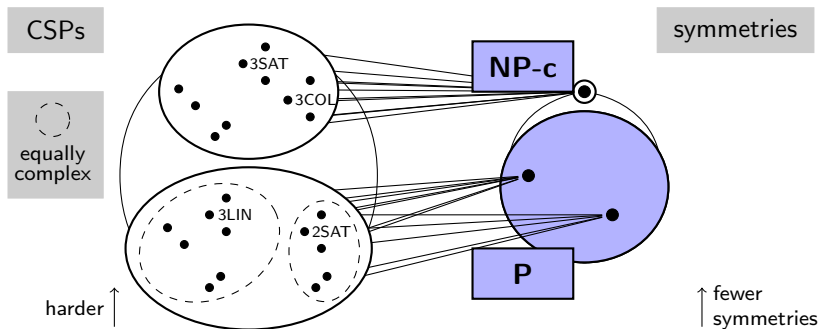
= satisfied in \mathcal{P} , the set of projections on $\{0, 1\}$

Corollary

*If $\text{Pol}(\mathbb{A})$ satisfies only trivial minor conditions,
then $\text{CSP}(\mathbb{A})$ is NP-hard.*

Theorem ([Bulatov'17], [Zhuk'17])

*If $\text{Pol}(\mathbb{A})$ satisfies some non-trivial minor condition,
then $\text{CSP}(\mathbb{A})$ is in P.*



- ▶ only trivial minor conditions \Rightarrow NP-complete
- ▶ some nontrivial minor condition \Rightarrow P

Further steps?

(Barto,) Bulín, Krokhin, Opršal: Algebraic approach to promise constraint satisfaction

Definition (MinorCond(N, \mathcal{M}))

Input: minor condition \mathbf{X} with symbols of arity N

Answer Yes: \mathbf{X} is trivial (=satisfied in \mathcal{P})

Answer No: \mathbf{X} not satisfied in \mathcal{M}

Theorem

Let $\mathcal{M} = \text{Pol}(\mathbb{A})$. The following computational problems are equivalent for a large enough N .

- (i) CSP(\mathbb{A})
- (ii) MinorCond(N, \mathcal{M})

Consequence: 3rd step

Proof: direct, simple, known

Given input of CSP(3NAE_2), eg.

$$(\exists a, b, c, d) R(c, a, b) \wedge R(a, d, c)$$

transform it to a minor condition, eg.

$$f_1(x_1, x_0, x_0, x_0, x_1, x_1) = g_c(x_0, x_1)$$

$$f_1(x_0, x_1, x_0, x_1, x_0, x_1) = g_a(x_0, x_1)$$

$$f_1(x_0, x_0, x_1, x_1, x_1, x_0) = g_b(x_0, x_1)$$

$$f_2(x_1, x_0, x_0, x_0, x_1, x_1) = g_a(x_0, x_1)$$

$$f_2(x_0, x_1, x_0, x_1, x_0, x_1) = g_d(x_0, x_1)$$

$$f_2(x_0, x_0, x_1, x_1, x_1, x_0) = g_c(x_0, x_1)$$

“Yes input \rightarrow Yes input”: easy

“No input \rightarrow No input”: for contrapositive use $y \mapsto g_y(0, 1)$.

Given a minor condition, e.g.

$$f(x_1, x_2, x_1, x_3) = g(x_1, x_2, x_3)$$

$$h(x_3, x_1) = g(x_1, x_2, x_3)$$

- ▶ introduce variables f_{a_1, a_2, a_3, a_4} one for each $(a_1, \dots, a_4) \in A^4$, h_{a_1, a_2} , and g_{a_1, a_2, a_3} .
- ▶ so evaluation of f 's \leftrightarrow function $f : A^4 \rightarrow A$
- ▶ express that f, g, h are polymorphisms (by constraints)
- ▶ merge variables to enforce the equations

The proof only uses **bipartite minor conditions**:

- ▶ Two disjoint set of symbols *LHS*, *RHS*.
- ▶ Each equation of the form

$$f(\text{variables}) = g(x_1, x_2, \dots, x_N)$$

where $f \in LHS$ and $g \in RHS$

Remarks

How to show that $\mathcal{M} = \text{Pol}(\mathbb{A})$ satisfies only trivial minor conditions?

Theorem

The following are equivalent

- ▶ \mathcal{M} satisfies only trivial minor conditions
- ▶ There is a mapping $\xi : \mathcal{M} \rightarrow \mathbb{N}$
 - ▶ if f is of arity n , then $\xi(f) \in \{1, 2, \dots, n\}$
(**think**: an important coordinate of f)
 - ▶ ξ behaves nicely with minors, eg. if

$$f(x_3, x_2, x_1, x_2, x_2, x_1) = g(x_1, x_2, x_3)$$

and $\xi(f) = 5$, then $\xi(g) = 2$.

How to devise algorithms if $\mathcal{M} = \text{Pol}(\mathbb{A})$ satisfies some nontrivial minor condition?

Theorem

The following are equivalent.

- ▶ \mathcal{M} satisfies some nontrivial minor condition
- ▶ \mathcal{M} satisfies, for some $n \geq 2$, the minor condition

$$c(x_1, x_2, \dots, x_n) = c(x_2, \dots, x_n, x_1)$$

[Barto, Kozik'12]

- ▶ ...
- ▶ ...zillion other characterizations ...
- ▶ ...

General problem: Given a structure \mathfrak{A} and 1st order sentence ϕ (the same language), decide whether \mathfrak{A} satisfies ϕ .

CSP

- ▶ fix a finite relational structure
- ▶ restrict to primitive positive (pp-) sentences

Another problem: Given a structure \mathfrak{A} and 1st order sentence ϕ (different language), decide whether symbols in ϕ can be interpreted in \mathfrak{A} so that \mathfrak{A} satisfies ϕ .

Our case: solving functional equations over an algebra

- ▶ fix a finite algebraic structure
- ▶ restrict to universally quantified conjunction of (special) equations
- ▶ take a promise version