# Introduction to Integer Linear Programming 

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Computational Aspects of Optimization

## Content

(1) Motivation and applications
(2) Formulation and properties
(3) Cutting plane method

## Knapsack problem

Values $a_{1}=4, a_{2}=6, a_{3}=7$, costs $c_{1}=4, c_{2}=5, c_{3}=11$, budget $b=10$ :

$$
\begin{aligned}
\max & \sum_{i=1}^{3} c_{i} x_{i} \\
\text { s.t. } & \sum_{i=1}^{3} a_{i} x_{i} \leq 10 \\
& x_{i} \in\{0,1\}
\end{aligned}
$$

Consider $=$ instead of $\leq, 0 \leq x_{i} \leq 1$ and rounding instead of $x_{i} \in\{0,1\}$, heuristic (ratio $c_{i} / a_{i}$ ) ...

## Why is integrality so important?

Real (mixed-)integer programming problems (not always linear)

- Portfolio optimization - integer number of assets, fixed transaction costs
- Scheduling - integer (binary) decision variables to assign a job to a machine
- Vehicle Routing Problems (VRP) - binary decision variables which identify a successor of a node on the route

In general - modelling of logical relations, e.g.

- at least two constraints from three are fulfilled,
- if we buy this asset than the fixed transaction costs increase,
- ...


## Facility Location Problem

- $i$ warehouses (facilities, branches), $j$ customers,
- $x_{i j}$ - sent (delivered, served) quantity,
- $y_{i}$-a warehouse is built,
- $c_{i j}$ - unit supplying costs,
- $f_{i}$ - fixed costs of building the warehouse,
- $K_{i}$ - warehouse capacity,
- $D_{j}$ - demand.

$$
\begin{aligned}
\min _{x_{i j}, y_{i}} & \sum_{i=1}^{n} \sum_{j=1}^{m} c_{i j} x_{i j}+\sum_{i} f_{i} y_{i} \\
\text { s.t. } & \sum_{j=1}^{m} x_{i j} \leq K_{i} y_{i}, i=1, \ldots, n \\
& \sum_{i=1}^{n} x_{i j}=D_{j}, j=1, \ldots, m \\
& x_{i j} \geq 0, \quad y_{i} \in\{0,1\}
\end{aligned}
$$

## Scheduling to Minimize the Makespan

- i machines, $j$ jobs,
- y-machine makespan,
- $x_{i j}$ - assignment variable,
- $t_{i j}$ - time necessary to process job $j$ on machine $i$.

$$
\begin{array}{rl}
\min _{x_{i j}, y} & y \\
\text { s.t. } & \sum_{i=1}^{m} x_{i j}=1, j=1, \ldots, n \\
& \sum_{j=1}^{n} t_{i j} x_{i j} \leq y, i=1, \ldots, m  \tag{1}\\
& x_{i j} \in\{0,1\}, \quad y \geq 0
\end{array}
$$

## Lot Sizing Problem

## Uncapacitated single item LSP

- $x_{t}$ - production at period $t$,
- $y_{t}$ - on/off decision at period $t$,
- $s_{t}$ - inventory at the end of period $t\left(s_{0} \geq 0\right.$ fixed),
- $D_{t}$ - (predicted) expected demand at period $t$,
- $p_{t}$ - unit production costs at period $t$,
- $f_{t}$ - setup costs at period $t$,
- $h_{t}$ - inventory costs at period $t$,
- $M$ - a large constant.

$$
\begin{align*}
\min _{x_{t}, y_{t}, s_{t}} & \sum_{t=1}^{T}\left(p_{t} x_{t}+f_{t} y_{t}+h_{t} s_{t}\right) \\
\text { s.t. } & s_{t-1}+x_{t}-D_{t}=s_{t}, t=1, \ldots, T,  \tag{2}\\
& x_{t} \leq M y_{t}, \\
& x_{t}, s_{t} \geq 0, y_{t} \in\{0,1\} .
\end{align*}
$$

ASS. Wagner-Whitin costs $p_{t+1} \leq p_{t}+h_{t}$.

## Lot Sizing Problem

## Capacitated single item LSP

- $x_{t}$ - production at period $t$,
- $y_{t}$ - on/off decision at period $t$,
- $s_{t}$ - inventory at the end of period $t\left(s_{0} \geq 0\right.$ fixed),
- $D_{t}$ - (predicted) expected demand at period $t$.
- $p_{t}$ - unit production costs at period $t$,
- $f_{t}$ - setup costs at period $t$,
- $h_{t}$ - inventory costs at period $t$,
- $C_{t}$ - production capacity at period $t$.

$$
\begin{align*}
\min _{x_{t}, y_{t}, s_{t}} & \sum_{t=1}^{T}\left(p_{t} x_{t}+f_{t} y_{t}+h_{t} s_{t}\right) \\
\text { s.t. } & s_{t-1}+x_{t}-D_{t}=s_{t}, t=1, \ldots, T,  \tag{3}\\
& x_{t} \leq C_{t} y_{t} \\
& x_{t}, s_{t} \geq 0, y_{t} \in\{0,1\} .
\end{align*}
$$

ASS. Wagner-Whitin costs $p_{t+1} \leq p_{t}+h_{t}$.

## Unit Commitment Problem

- $i=1, \ldots, n$ units (power plants), $t=1, \ldots, T$ periods,
- $y_{i t}$ - on/off decision for unit $i$ at period $t$,
- $x_{i t}$ - production level for unit $i$ at period $t$,
- $D_{t}$ - (predicted) expected demand at period $t$,
- $p_{i}^{\text {min }}, p_{i}^{\text {max }}$ - minimal/maximal production capacity of unit $i$,
- $c_{i t}$ - variable production costs,
- $f_{i t}$ - (fixed) start-up costs.

$$
\begin{align*}
\min _{x_{i t}, y_{i t}} & \sum_{i=1}^{n} \sum_{t=1}^{T}\left(c_{i t} x_{i t}+f_{i t} y_{i t}\right) \\
\text { s.t. } & \sum_{i=1}^{n} x_{i t} \geq D_{t}, t=1, \ldots, T  \tag{4}\\
& p_{i}^{\min } y_{i t} \leq x_{i t} \leq p_{i}^{\max } y_{i t} \\
& x_{i t} \geq 0, y_{i t} \in\{0,1\}
\end{align*}
$$

## Content

## (1) Motivation and applications

(2) Formulation and properties

## (3) Cutting plane method

## Integer linear programming

$$
\begin{align*}
\min c^{\top} x &  \tag{5}\\
A x & \geq b,  \tag{6}\\
x & \in \mathbb{Z}_{+}^{n} . \tag{7}
\end{align*}
$$

Assumption: all coefficients are integer (rational before multiplying by a proper constant).

Set of feasible solution and its relaxation

$$
\begin{align*}
S & =\left\{x \in \mathbb{Z}_{+}^{n}: A x \geq b\right\}  \tag{8}\\
P & =\left\{x \in \mathbb{R}_{+}^{n}: A x \geq b\right\} \tag{9}
\end{align*}
$$

Obviously $S \subseteq P$. Not so trivial that $S \subseteq \operatorname{conv}(S) \subseteq P$.

## ILP - irrational data

Škoda (2010):

$$
\begin{align*}
\max & \sqrt{2} x-y \\
\text { s.t. } & \sqrt{2} x-y \leq 0,  \tag{10}\\
& x \geq 1, \\
& x, y \in \mathbb{N} .
\end{align*}
$$

The objective value is bounded (from above), but there is no optimal solution.

For any feasible solution with the objective value $z=\sqrt{2} x^{*}-\left\lceil\sqrt{2} x^{*}\right\rceil$ we can construct a solution with a higher objective value...

## ILP - irrational data

Let $z=\sqrt{2} x^{*}-\left\lceil\sqrt{2} x^{*}\right\rceil$ be the optimal solution. Since $-1<z<0$, we can find $k \in \mathbb{N}$ such that $k z<-1$ and $(k-1) z>-1$. By setting $\epsilon=-1-k z$ we get that $-1<z<-\epsilon=1+k z<0$. Then

$$
\begin{align*}
& \sqrt{2} k x^{*}-\left\lceil\sqrt{2} k x^{*}\right\rceil \\
& =k z+k\left\lceil\sqrt{2} x^{*}\right\rceil-\left\lceil\sqrt{2} k x^{*}\right\rceil \\
& =-1-\epsilon+k\left\lceil\sqrt{2} x^{*}\right\rceil-\left\lceil\sqrt{2} k x^{*}\right\rceil  \tag{11}\\
& =k\left\lceil\sqrt{2} x^{*}\right\rceil-1-\epsilon-\left\lceil\left\lceil\sqrt{2} k x^{*}\right\rceil-1-\epsilon\right\rceil \\
& =-\epsilon>z .
\end{align*}
$$

( $k\left\lceil\sqrt{2} x^{*}\right\rceil-1$ is integral)
Thus, we have obtained a solution with a higher objective value which is a contradiction.

## Example

Consider set $S$ given by

$$
\begin{aligned}
7 x_{1}+2 x_{2} & \geq 5, \\
7 x_{1}+x_{2} & \leq 28, \\
-4 x_{1}+14 x_{2} & \leq 35, \\
x_{1}, x_{2} & \in \mathbb{Z}_{+} .
\end{aligned}
$$

## Set of feasible solutions, its relaxation and convex envelope



Škoda (2010)

## Integer linear programming problem

Problem

$$
\begin{equation*}
\min c^{\top} x: x \in S \tag{12}
\end{equation*}
$$

is equivalent to

$$
\begin{equation*}
\min c^{T} x: x \in \operatorname{conv}(S) \tag{13}
\end{equation*}
$$

$\operatorname{conv}(S)$ is very difficult to construct - many constraints ("strong cuts") are necessary (there are some important exceptions).

LP-relaxation:

$$
\begin{equation*}
\min c^{T} x: x \in P \tag{14}
\end{equation*}
$$

## Mixed-integer linear programming

Often both integer and continuous decision variables appear:

$$
\begin{array}{ll}
\min & c^{T} x+d^{T} y \\
\text { s.t. } & A x+B y \geq b \\
& x \in \mathbb{Z}_{+}^{n}, y \in \mathbb{R}_{+}^{n^{\prime}}
\end{array}
$$

(WE DO NOT CONSIDER IN INTRODUCTION)

## Basic algorithms

We consider:

- Cutting Plane Method
- Branch-and-Bound

There are methods which combine the previous alg., e.g. Branch-and-Cut (add cuts to reduce the problem for B\&B).

## Content

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## Cutting plane method - Gomory cuts

1. Solve LP-relaxation using (primal or dual) SIMPLEX algorithm.

- If the solution is integral - END, we have found an optimal solution,
- otherwise continue with the next step.

2. Add a Gomory cut (...) and solve the resulting problem using DUAL SIMPLEX alg.

## Example

$$
\begin{align*}
\min 4 x_{1}+5 x_{2} &  \tag{15}\\
x_{1}+4 x_{2} & \geq 5  \tag{16}\\
3 x_{1}+2 x_{2} & \geq 7 \\
x_{1}, x_{2} & \in \mathbb{Z}_{+}^{n} .
\end{align*}
$$

Dual simplex for LP-relaxation ...

After two iterations of the dual SIMPLEX algorithm ...

|  |  |  | 4 | 5 | 0 | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | $x_{1}$ | $x_{2}$ | $x_{3}$ | $x_{4}$ |
| 5 | $x_{2}$ | $8 / 10$ | 0 | 1 | $-3 / 10$ | $1 / 10$ |
| 4 | $x_{1}$ | $18 / 10$ | 1 | 0 | $2 / 10$ | $-4 / 10$ |
|  |  | $112 / 10$ | 0 | 0 | $-7 / 10$ | $-11 / 10$ |

## Gomory cuts

There is a row in simplex table, which corresponds to a non-integral solution $x_{i}$ in the form:

$$
\begin{equation*}
x_{i}+\sum_{j \in N} w_{i j} x_{j}=d_{i} \tag{19}
\end{equation*}
$$

where $N$ denotes the set of non-basic variables; $d_{i}$ is non-integral. We denote

$$
\begin{align*}
w_{i j} & =\left\lfloor w_{i j}\right\rfloor+f_{i j}  \tag{20}\\
d_{i} & =\left\lfloor d_{i}\right\rfloor+f_{i} \tag{21}
\end{align*}
$$

i.e. $0 \leq f_{i j}, f_{i}<1$.

$$
\begin{equation*}
\sum_{j \in N} f_{i j} x_{j} \geq f_{i} \tag{22}
\end{equation*}
$$

or rather $-\sum_{j \in N} f_{i j} x_{j}+s=-f_{i}, s \geq 0$.

## Gomory cuts

General properties of cuts (including Gomory ones):

- Property 1: Current (non-integral) solution becomes infeasible (it is cut).
- Property 2: No feasible integral solution becomes infeasible (it is not cut).


## Gomory cuts - property 1

We express the constraints in the form

$$
\begin{align*}
x_{i}+\sum_{j \in N}\left(\left\lfloor w_{i j}\right\rfloor+f_{i j}\right) x_{j} & =\left\lfloor d_{i}\right\rfloor+f_{i}  \tag{23}\\
x_{i}+\sum_{j \in N}\left\lfloor w_{i j}\right\rfloor x_{j}-\left\lfloor d_{i}\right\rfloor & =f_{i}-\sum_{j \in N} f_{i j} x_{j} . \tag{24}
\end{align*}
$$

Current solution $x_{j}^{*}=0$ pro $j \in N$ a $x_{i}^{*}=d_{i}$ is non-integral, i.e. $0<x_{i}^{*}-\left\lfloor d_{i}\right\rfloor<1$, thus

$$
\begin{equation*}
0<x_{i}^{*}-\left\lfloor d_{i}\right\rfloor=f_{i}-\sum_{j \in N} f_{i j} x_{j}^{*} \tag{25}
\end{equation*}
$$

and

$$
\begin{equation*}
\sum_{j \in N} f_{i j} x_{j}^{*}<f_{i} \tag{26}
\end{equation*}
$$

which is a contradiction with the Gomory cut.

## Gomory cuts - property 2

Consider an arbitrary integral feasible solution and rewrite the constraint as

$$
\begin{equation*}
x_{i}+\sum_{j \in N}\left\lfloor w_{i j}\right\rfloor x_{j}-\left\lfloor d_{i}\right\rfloor=f_{i}-\sum_{j \in N} f_{i j} x_{j}, \tag{27}
\end{equation*}
$$

Left-hand side (LS) is integral, thus right-hand side (RS) is integral. Moreover, $f_{i}<1$ a $\sum_{j \in N} f_{i j} x_{j} \geq 0$, thus RS is strictly lower than 1 and at the same time it is integral, thus lower or equal to 0 , i.e. we obtain Gomory cut

$$
\begin{equation*}
f_{i}-\sum_{j \in N} f_{i j} x_{j} \leq 0 \tag{28}
\end{equation*}
$$

Thus each integral solution fulfills it.

## Cutting plane methods - steps



Škoda (2010)

## Dantzig cuts

$$
\begin{equation*}
\sum_{j \in N} x_{j} \geq 1 \tag{29}
\end{equation*}
$$

(Remind that non-basic variables are equal to zero.)

After two iterations of the dual SIMPLEX algorithm ...

|  |  |  | 4 | 5 | 0 | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | $x_{1}$ | $x_{2}$ | $x_{3}$ | $x_{4}$ |
| 5 | $x_{2}$ | $8 / 10$ | 0 | 1 | $-3 / 10$ | $1 / 10$ |
| 4 | $x_{1}$ | $18 / 10$ | 1 | 0 | $2 / 10$ | $-4 / 10$ |
|  |  | $112 / 10$ | 0 | 0 | $-7 / 10$ | $-11 / 10$ |

For example, $x_{1}$ is not integral:

$$
\begin{aligned}
x_{1}+2 / 10 x_{3}-4 / 10 x_{4} & =18 / 10 \\
x_{1}+(0+2 / 10) x_{3}+(-1+6 / 10) x_{4} & =1+8 / 10
\end{aligned}
$$

Gomory cut:

$$
2 / 10 x_{3}+6 / 10 x_{4} \geq 8 / 10 .
$$

New simplex table

|  |  |  |  | 4 | 5 | 0 | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $x_{1}$ | $x_{2}$ | $x_{3}$ | $x_{4}$ | $x_{5}$ |  |  |  |
| 5 |  |  | $x_{2}$ | $8 / 10$ | 0 | 1 | $-3 / 10$ |
| 4 | $1 / 10$ | 0 |  |  |  |  |  |
| 4 | $x_{1}$ | $18 / 10$ | 1 | 0 | $2 / 10$ | $-4 / 10$ | 0 |
| 0 | $x_{5}$ | $-8 / 10$ | 0 | 0 | $-2 / 10$ | $-6 / 10$ | 1 |
|  |  | $112 / 10$ | 0 | 0 | $-7 / 10$ | $-11 / 10$ | 0 |

Dual simplex alg. ... Gomory cut:

$$
4 / 6 x_{3}+1 / 6 x_{5} \geq 2 / 3
$$

Dual simplex alg. ... optimal solution (2, 1, 1, 1, 0, 0).

## Literature

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