

# Introduction to computational complexity

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COMPUTATIONAL ASPECTS OF OPTIMIZATION

# Software

General mathematical and statistical software:

- **Matlab** and (free) OPTI toolbox:  
<http://www.i2c2.aut.ac.nz/Wiki/OPTI/index.php/Main/HomePage>
- **SAS**: OR package
- **R**: suitable packages
- **Mathematica**: findminimum, minimize, ...
- ...

# Software

Modelling tools for optimization:

- **GAMS**: <http://www.gams.com>
- **AIMMS**: <http://www.aimms.com>
- **Gurobi**: <http://www.gurobi.com>
- **AMPL**: <http://ampl.com>
- **CPlex Studio**:  
<http://www-03.ibm.com/software/products/cs/ibmilogcpleoptistud>
- **MPL**: <http://www.maximalsoftware.com/mpl>
- ...

# Software

## Open Source libraries

- **COIN-OR**: <http://www.coin-or.org/>

# Software

## Solvers

- Baron (LP, NLP, MIP, MINLP, ...)
- Bonmin (NLP, MIP, MINLP, ...)
- Conopt (LP, NLP, ...)
- CPLEX (LP, MIP, MIQCP, ...)
- Dicopt (MIQCP, MINLP, ...)
- Gurobi
- Knitro (LP, MINLP, MIQCP, NLP, ...)
- Lindo (LP, MINLP, MIP, MIQCP, NLP, ...)
- Minos (LP, NLP, ...)
- Mosek (LP, MIP, MIQCP, NLP, ...)
- Xpress (LP, MIP, MIQCP, ...)
- ...

# Introduction to complexity theory

Wolsey (1998): Consider **decision problems** having YES–NO answers.

**Optimization problem**

$$\max_{x \in M} c^T x$$

can be replaced by (for some  $k$  integral)

Is there an  $x \in M$  with value  $c^T x \geq k$ ?

For a problem instance  $X$ , the **length of the input**  $L(X)$  is the length of the binary representation of a standard representation of the instance.

Instance  $X = \{c, M\}$ ,  $X = \{c, M, k\}$

# Example: Knapsack decision problem

For an instance

$$X = \left\{ \sum_{i=1}^n c_i x_i \geq k, \sum_{i=1}^n a_i x_i \leq b, x \in \{0, 1\}^n \right\},$$

the length of the input is

$$L(X) = \sum_{i=1}^n \lceil \log c_i \rceil + \sum_{i=1}^n \lceil \log a_i \rceil + \lceil \log b \rceil + \lceil \log k \rceil$$

# Running time

## Definition

- $f_A(X)$  is the **number of elementary calculations** required to run the algorithm  $A$  on the instance  $X \in P$ .
- **Running time of the algorithm  $A$**

$$f_A^*(l) = \sup_X \{f_A(X) : L(X) = l\}.$$

- An algorithm  $A$  is **polynomial** for a problem  $P$  if  $f_A^*(l) = O(l^p)$  for some  $p \in \mathbb{N}$ .



# Classes $\mathcal{NP}$ and $\mathcal{P}$

## Definition

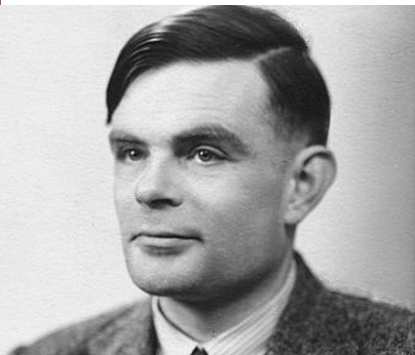
- $\mathcal{NP}$  (Nondeterministic Polynomial) is the class of decision problems with the property that: for any instance for which the answer is YES, there is a polynomial proof of the YES.
- $\mathcal{P}$  is the class of decision problems in  $\mathcal{NP}$  for which there exists a polynomial algorithm.

$\mathcal{NP}$  may be equivalently defined as the set of decision problems that can be solved in polynomial time on a non-deterministic Turing machine<sup>1</sup>.

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<sup>1</sup>NTM writes symbols one at a time on an endless tape by strictly following a set of rules. It determines what action it should perform next according to its internal state and what symbol it currently sees. It may have a set of rules that prescribes more than one action for a given situation. The machine "branches" into many copies, each of which follows one of the possible transitions leading to a "computation tree".

# Alan Turing



The Imitation Game (2014)

# Polynomial reduction and the class $\mathcal{NPC}$

## Definition

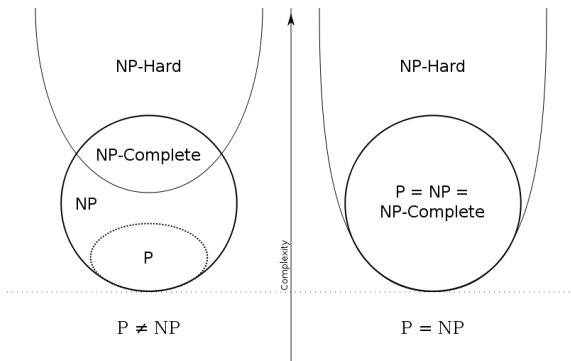
- If problems  $P, Q \in \mathcal{NP}$ , and if an instance of  $P$  can be converted in polynomial time to an instance of  $Q$ , then  $P$  is **polynomially reducible** to  $Q$ .
- $\mathcal{NPC}$ , the class of  $\mathcal{NP}$ -**complete** problems, is the subset of problems  $P \in \mathcal{NP}$  such that for all  $Q \in \mathcal{NP}$ ,  $Q$  is polynomially reducible to  $P$ .

**Proposition:** Suppose that problems  $P, Q \in \mathcal{NP}$ .

- If  $Q \in \mathcal{P}$  and  $P$  is polynomially reducible to  $Q$ , then  $P \in \mathcal{P}$ .
- If  $P \in \mathcal{NPC}$  and  $P$  is polynomially reducible to  $Q$ , then  $Q \in \mathcal{NPC}$ .

**Proposition:** If  $\mathcal{P} \cap \mathcal{NPC} \neq \emptyset$ , then  $\mathcal{P} = \mathcal{NPC}$ .

## Open question &amp; Euler diagram

Is  $\mathcal{P} = \mathcal{NP}$ ?

# $\mathcal{NP}$ -hard optimization problems

## Definition

An optimization problem for which the decision problem lies in  $\mathcal{NPC}$  is called  $\mathcal{NP}$ -hard.

# Literature

- G.L. Nemhauser, L.A. Wolsey (1989). Integer Programming. Chapter VI in Handbooks in OR & MS, Vol. 1, G.L. Nemhauser et al. Eds.
- L.A. Wolsey (1998). Integer Programming. Wiley, New York.
- L.A. Wolsey, G.L. Nemhauser (1999). Integer and Combinatorial Optimization. Wiley, New York.