

High Performance Mixed Precision Numerical Linear Algebra

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Charles University

SimRace 2021, IPFEN
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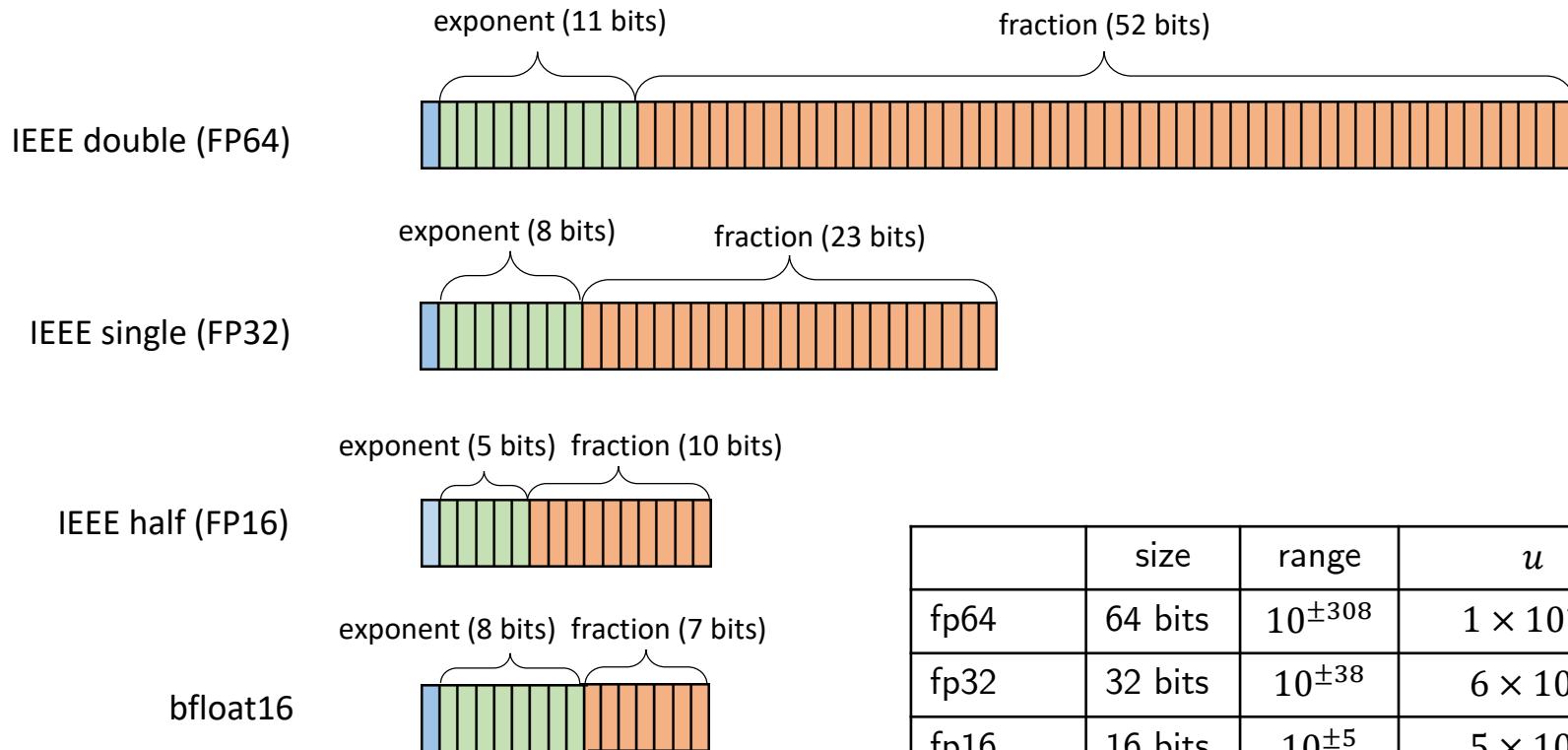


FACULTY
OF MATHEMATICS
AND PHYSICS
Charles University

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Floating Point Formats

$$(-1)^{\text{sign}} \times 2^{(\text{exponent}-\text{offset})} \times 1.\text{fraction}$$



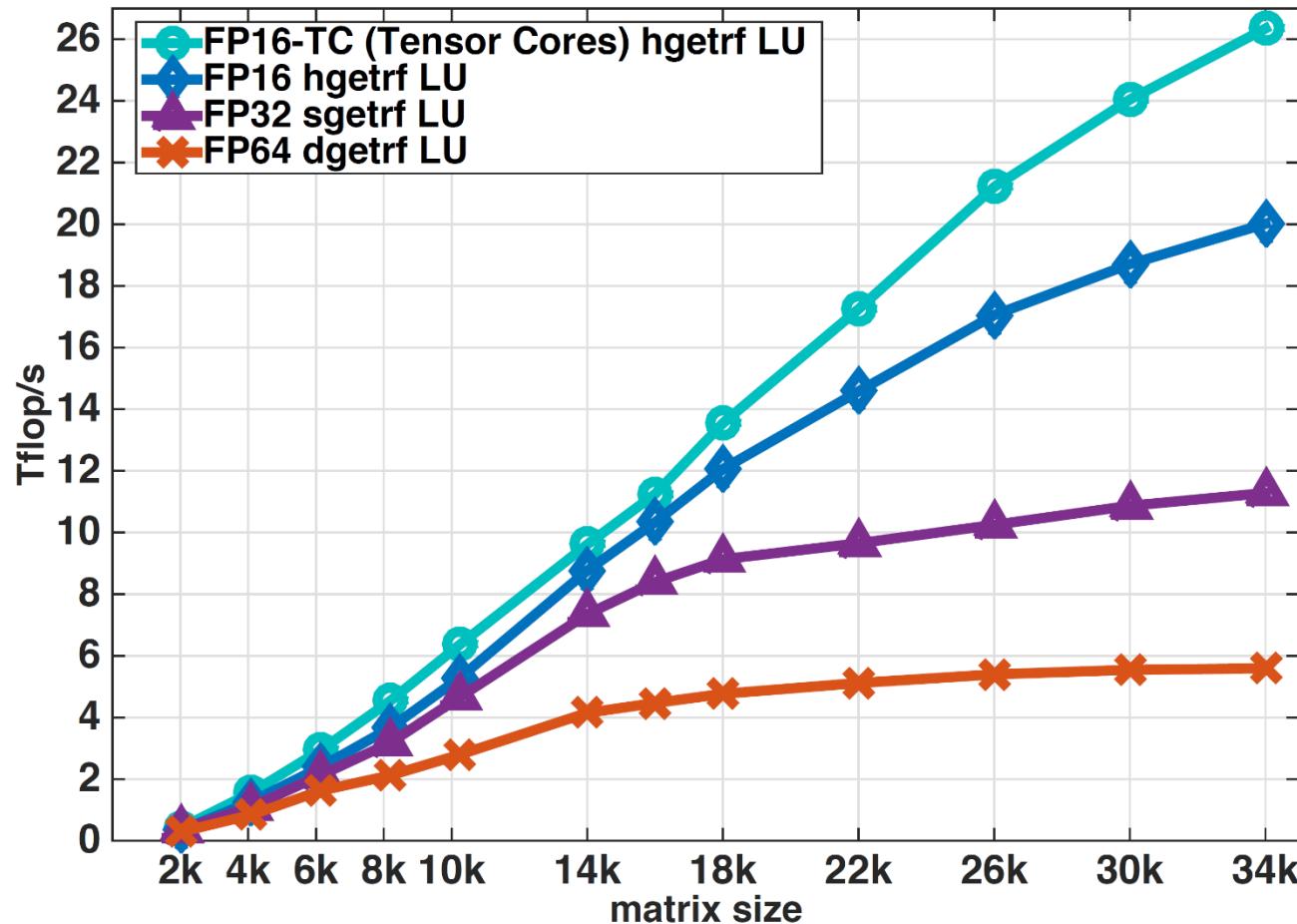
	size	range	u
fp64	64 bits	$10^{\pm 308}$	1×10^{-16}
fp32	32 bits	$10^{\pm 38}$	6×10^{-8}
fp16	16 bits	$10^{\pm 5}$	5×10^{-4}
bfloat16	16 bits	$10^{\pm 38}$	4×10^{-3}

Hardware Support for Multiprecision Computation

Use of low precision in machine learning has driven emergence of low-precision capabilities in hardware:

- AMD Radeon Instinct MI25 GPU, 2017:
 - single: 12.3 TFLOPS, half: 24.6 TFLOPS
- NVIDIA Tesla P100, 2016: native ISA support for 16-bit FP arithmetic
- NVIDIA Tesla V100, 2017: tensor cores for half precision;
 - 4x4 matrix multiply in one clock cycle
 - double: 7 TFLOPS, half+tensor: 112 TFLOPS (**16x!**)
- NVIDIA A100, 2020: tensor cores with multiple supported precisions: FP16, FP64, Binary, INT4, INT8, bfloat16
- Intel AI processors (Nervana, Xeon)
- Google's Tensor processing unit (TPU): as low as 8-bit arithmetic, bfloat16
- Future exascale supercomputers: (~2021) Expected extensive support for reduced-precision arithmetic (32/16/8-bit)

Performance of LU factorization on an NVIDIA V100 GPU



Mixed Precision Capabilities on Supercomputers

From TOP500:

June 2021

	Accelerator/CP Family	Count	System Share (%)	Rmax (GFlops)	Rpeak (GFlops)	Cores
1	NVIDIA Volta	97	19.4	626,503,420	1,049,977,600	11,875,056
2	NVIDIA Ampere	26	5.2	351,252,600	505,841,268	3,435,116
3	NVIDIA Pascal	9	1.8	57,876,640	85,807,525	1,141,300

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June 2019

	Accelerator/CP Family	Count	System Share (%)	Rmax (GFlops)	Rpeak (GFlops)	Cores
1	NVIDIA Pascal	61	12.2	106,025,166	179,951,012	2,738,356
3	NVIDIA Volta	12	2.4	224,559,400	360,593,742	4,488,720

HPL-AI Benchmark

- Highlights confluence of HPC+AI workloads
 - Like HPL, solves dense $Ax=b$, results still to double precision accuracy
 - Achieves this via **mixed-precision** iterative refinement
 - may be implemented in a way that takes advantage of the current and upcoming devices for accelerating AI workloads

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 - may be implemented in a way that takes advantage of the current and upcoming devices for accelerating AI workloads
- HPL-AI Results (June 2021):
 1. Fugaku: **2 EXAFLOP/s** (vs. 442 PETAFLOP/s on HPL; **4.5x**)
 2. Summit: **1.15 EXAFLOP/s** (vs. 149 PETAFLOP/s on HPL; **7.7x**)
- More information: <https://icl.bitbucket.io/hpl-ai/>
- Reference implementation: <https://bitbucket.org/icl/hpl-ai/src/>

Mixed precision in NLA

- **BLAS**: cuBLAS, MAGMA, [Agullo et al. 2009], [Abdelfattah et al., 2019], [Haidar et al., 2018]
- **Iterative refinement**:
 - Long history: [Wilkinson, 1963], [Moler, 1967], [Stewart, 1973], ...
 - More recently: [Langou et al., 2006], [C., Higham, 2017], [C., Higham, 2018], [C., Higham, Pranesh, 2020], [Amestoy et al., 2021]
- **Matrix factorizations**: [Haidar et al., 2017], [Haidar et al., 2018], [Haidar et al., 2020], [Abdelfattah et al., 2020]
- **Eigenvalue problems**: [Dongarra, 1982], [Dongarra, 1983], [Tisseur, 2001], [Davies et al., 2001], [Petschow et al., 2014], [Alvermann et al., 2019]
- **Sparse direct solvers**: [Buttari et al., 2008]
- **Orthogonalization**: [Yamazaki et al., 2015]
- **Multigrid**: [Tamstorf et al., 2020], [Richter et al., 2014], [Sumiyoshi et al., 2014], [Ljungkvist, Kronbichler, 2017, 2019]
- **(Preconditioned) Krylov subspace methods**: [Emans, van der Meer, 2012], [Yamagishi, Matsumura, 2016], [C., Gergelits, Yamazaki, 2021], [Clark, 2019], [Anzt et al., 2019], [Clark et al., 2010], [Gratton et al., 2020], [Arioli, Duff, 2009], [Hogg, Scott, 2010]

Challenges of low precision

- Do error bounds still apply?
 - Error bound with constant nu provides no information if $nu > 1$
 - One solution: probabilistic approach [Higham, Mary, 2019], [Higham, Mary, 2020]

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- Larger unit roundoff
 - Lose something small when storing: $fl(x) = x(1 + \delta)$, $|\delta| \leq u$
 - Lose something small when computing: $fl(x \text{ op } y) = (x \text{ op } y)(1 + \delta)$, $|\delta| \leq u$

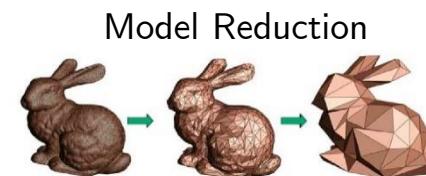
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Does it matter?

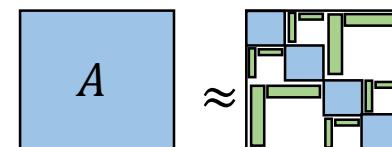
Inexact computations

- In real computations we have many sources of inexactness
 - Imperfect data, measurement error
 - Modeling error, discretization error
 - Intentional approximation to improve performance
 - Reduced models, Low-rank representations, sparsification, randomization



[Schilders, van der Vorst, Rommes, 2008]

Low-rank (hierarchical) approximation



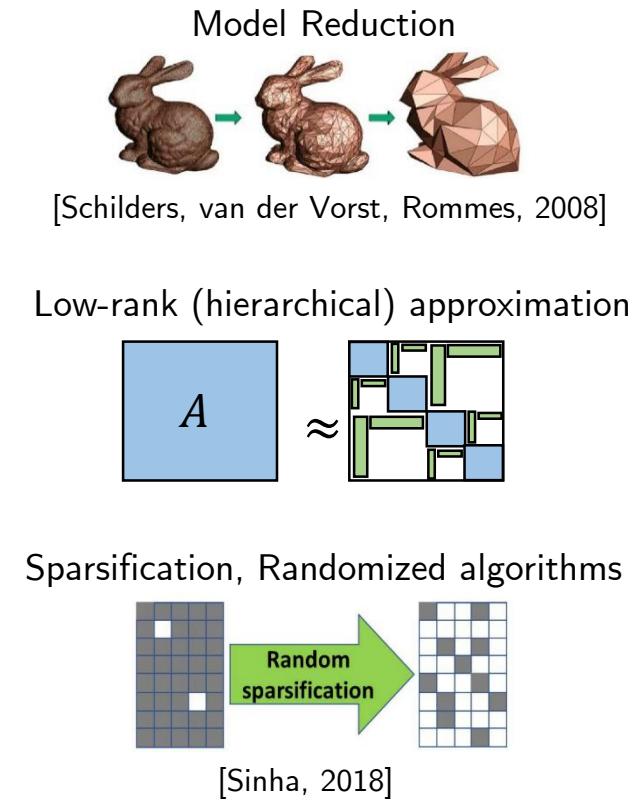
Sparsification, Randomized algorithms



[Sinha, 2018]

Inexact computations

- In real computations we have many sources of inexactness
 - Imperfect data, measurement error
 - Modeling error, discretization error
 - Intentional approximation to improve performance
 - Reduced models, Low-rank representations, sparsification, randomization
- Given that we are already working with so much inexactness, does it matter if we use lower precision?
 - Analysis of accuracy in techniques that use intentional approximation **almost always** assume that roundoff error is small enough to be ignored
 - Is this true? Is it true even if we use low precision?



Example: Randomized Algorithms

- Given $m \times n$ A , want truncated SVD with parameter k

$$\begin{matrix} A \\ \approx \\ \widehat{U} \end{matrix} \quad \begin{matrix} \widehat{\Sigma} \\ \widehat{V}^T \end{matrix}$$

Example: Randomized Algorithms

- Given $m \times n A$, want truncated SVD with parameter k

$$A \approx \widehat{U} \widehat{\Sigma} \widehat{V}^T$$

- Randomized SVD:

$$\begin{array}{c} A \quad \Omega \\ \downarrow \\ A = Y = Q R \end{array} \quad \longrightarrow \quad \begin{array}{c} Q^T \quad A \\ \downarrow \\ Q^T A = B \end{array} \quad = \quad \begin{array}{c} \widetilde{U} \quad \widehat{\Sigma} \quad \widehat{V}^T \\ \downarrow \\ \widehat{U} = Q \widetilde{U} \end{array}$$

Assuming exact arithmetic:

If Q satisfies $\|A - QQ^T A\| \leq \varepsilon$, then $\|A - \widehat{U}\widehat{\Sigma}\widehat{V}^T\| \leq \varepsilon$

What happens in finite precision?

Let's try different types of randsvd matrices from the MATLAB gallery:

```
A = gallery('randsvd',[100,40],1e6,mode); k=15;
```

$[U, S, V] = \text{svd}(A)$: non-randomized SVD, exact arithmetic

$[\hat{U}, \hat{S}, \hat{V}] = \text{rsvd}(A)$: randomized SVD, exact arithmetic

$[\hat{U}_d, \hat{S}_d, \hat{V}_d] = \text{rsvd}(A)$: randomized SVD, double precision

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Mode 3: Geometrically distributed singular values

$$\|A - USV^T\|_2 = 4.92\text{e-}03$$

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Mode 1: one large singular value

$$\|A - USV^T\|_2 = 1.00\text{e-}06$$

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Use of low precision leads to an order magnitude loss of accuracy! Roundoff error can't be ignored!

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Error bound no longer holds!

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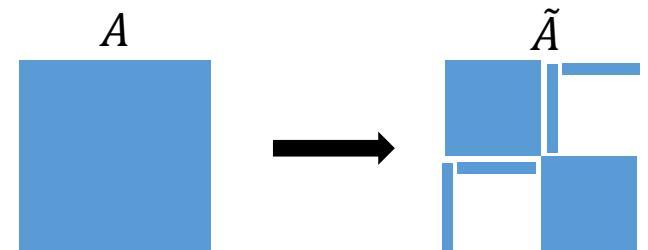
$$\|\hat{A} - \hat{U}_h\hat{S}_h\hat{V}_h^T\|_2 = 1.11e-05$$

$$\|A - Q_h Q_h^T A\|_2 = 3.59e-06$$

Use of low precision leads to an order magnitude loss of accuracy! Roundoff error can't be ignored!

Example: Low-Rank Approximation

- Block low-rank approximation and hierarchical matrix representations arise in a variety of applications
- Work on mixed and low precision in block low-rank computations
- [Higham, Mary, 2019]: block low-rank LU factorization preconditioner that exploits numerically low-rank structure of the error for LU computed in low precision
- [Higham, Mary, 2019]: Interplay of roundoff error and approximation error in solving block low-rank linear systems using LU
- [Buttari, et al., 2020]: block low-rank single precision coarse grid solves in multigrid
- [Amestoy et al., 2021]: Mixed precision low rank approximation and application to block low-rank LU factorization

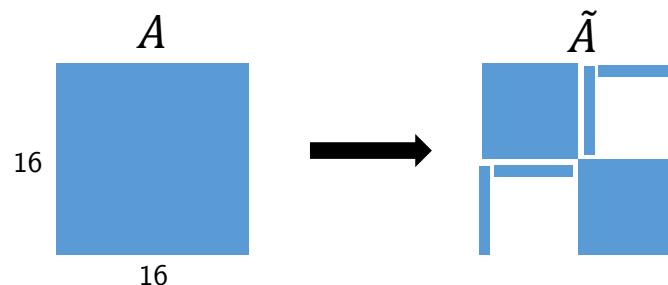


Example: Low-Rank Approximation

Inverse multiquadratic kernel:

$$A(i,j) = \frac{1}{\sqrt{1 + 0.1\|x - y\|^2}}, \quad x, y \in \mathbb{R}^2$$

A is SPD. Low-rank approximation of A should also be SPD!

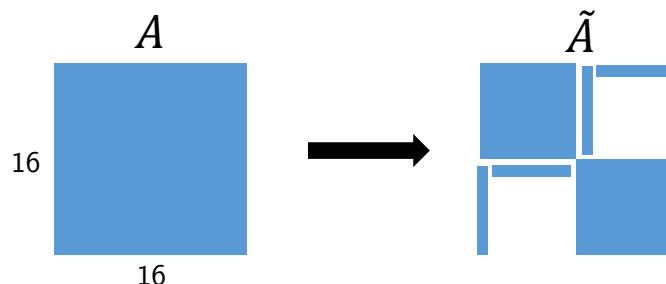


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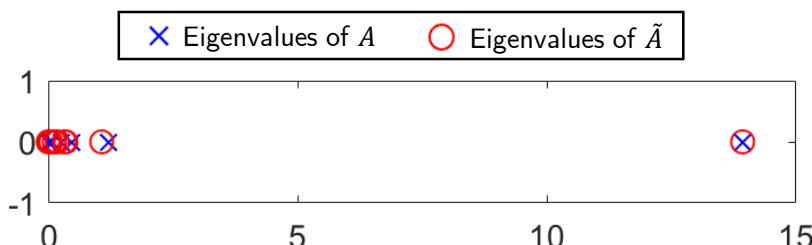
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Exact arithmetic SVD:

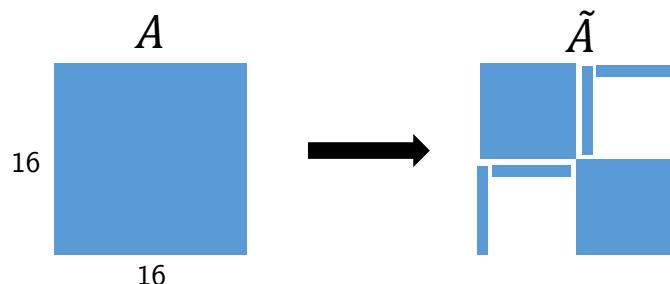


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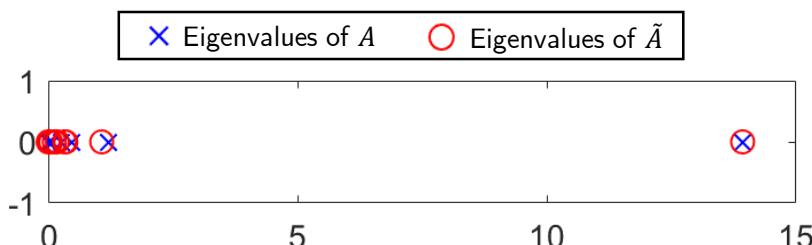
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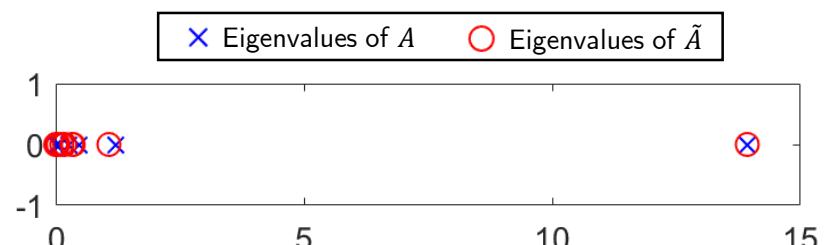
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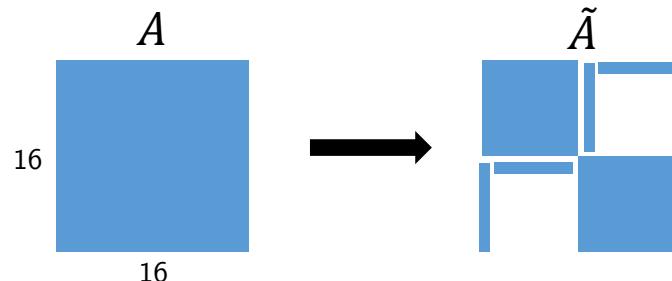
Half precision SVD:



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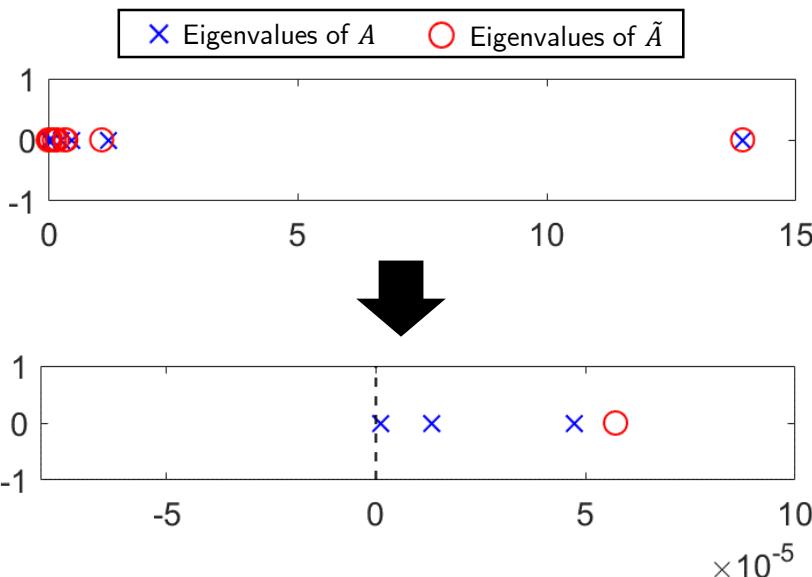
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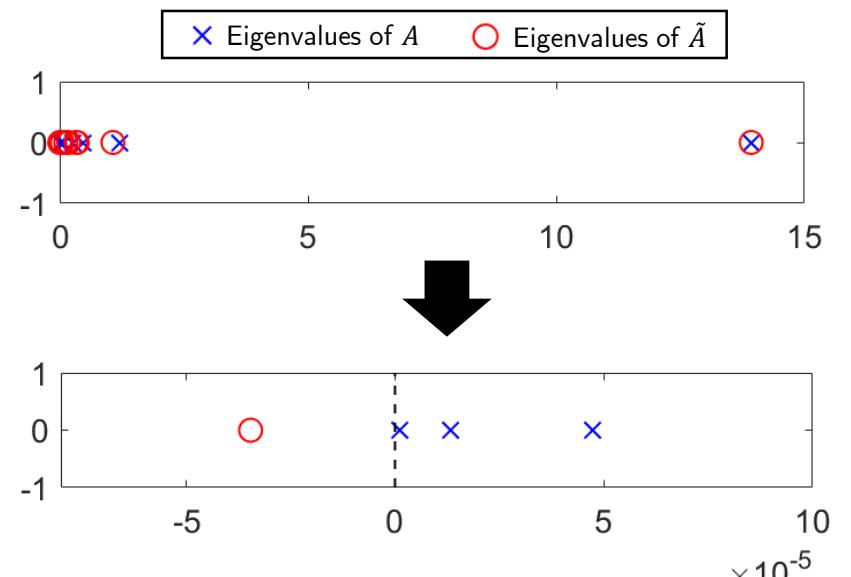


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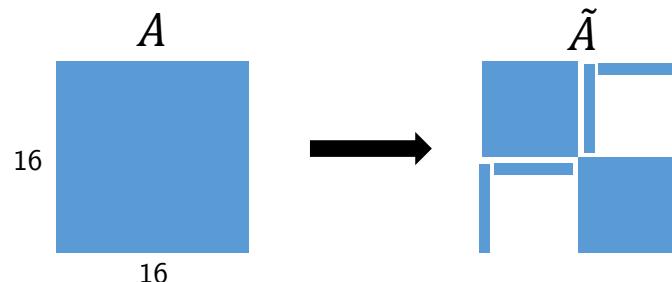


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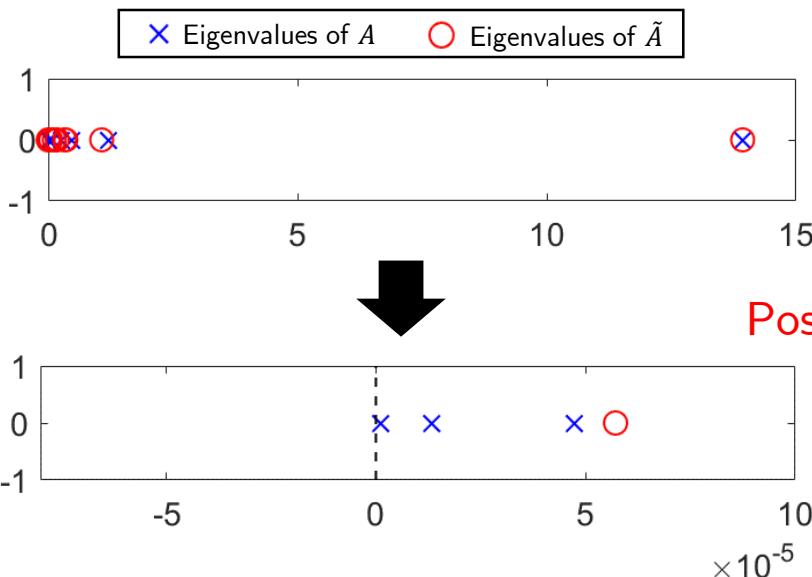
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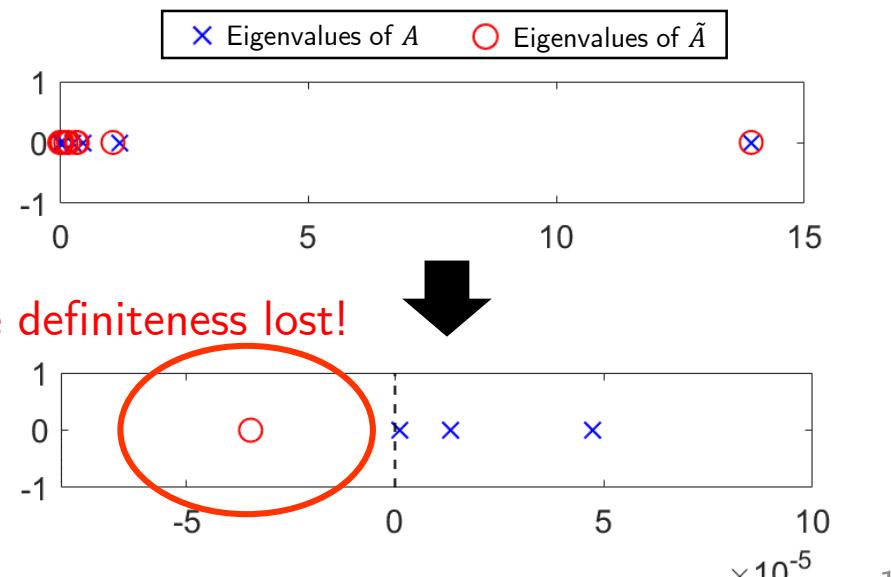
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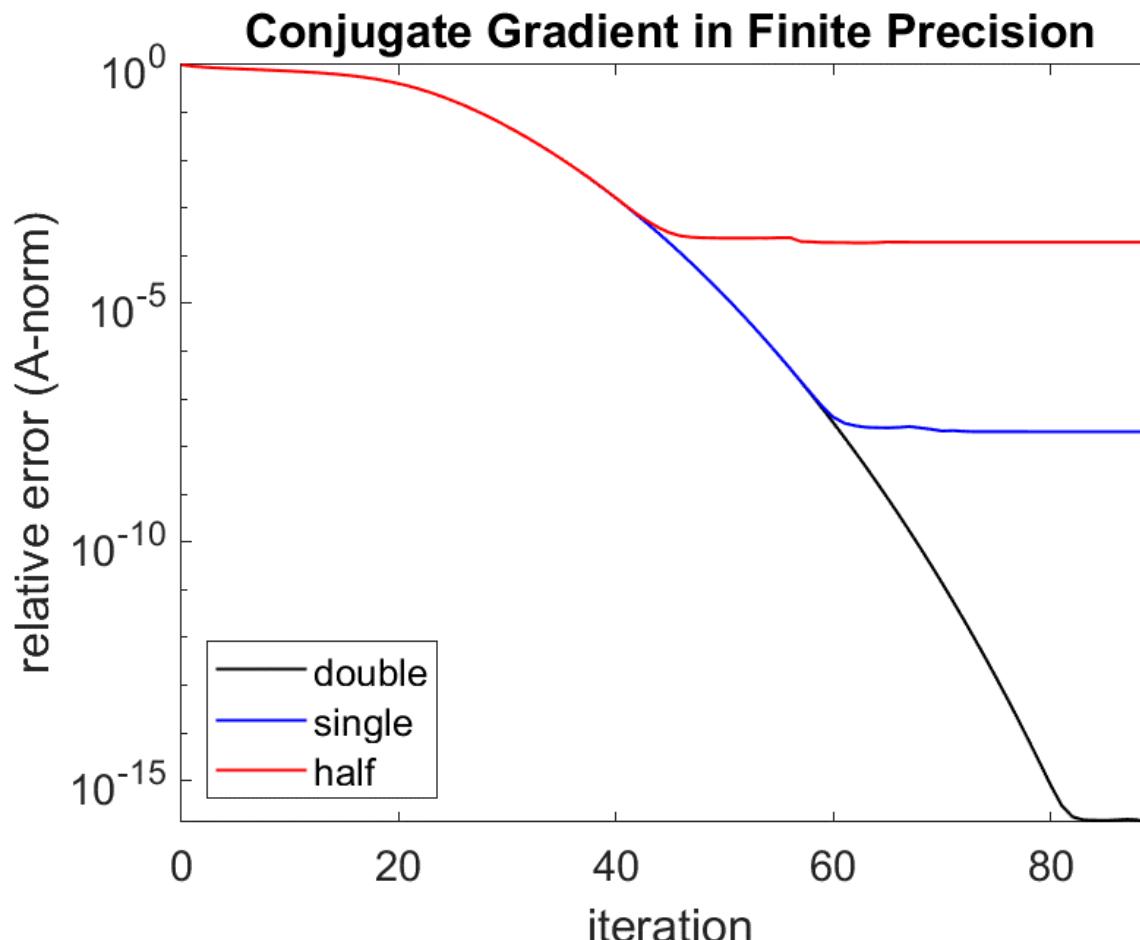
Half precision SVD:



Positive definiteness lost!

Example: Iterative Methods

```
A = diag(linspace(.001,1,100));  
[V,~] = eig(A);  
b = V'*ones(n,1);
```

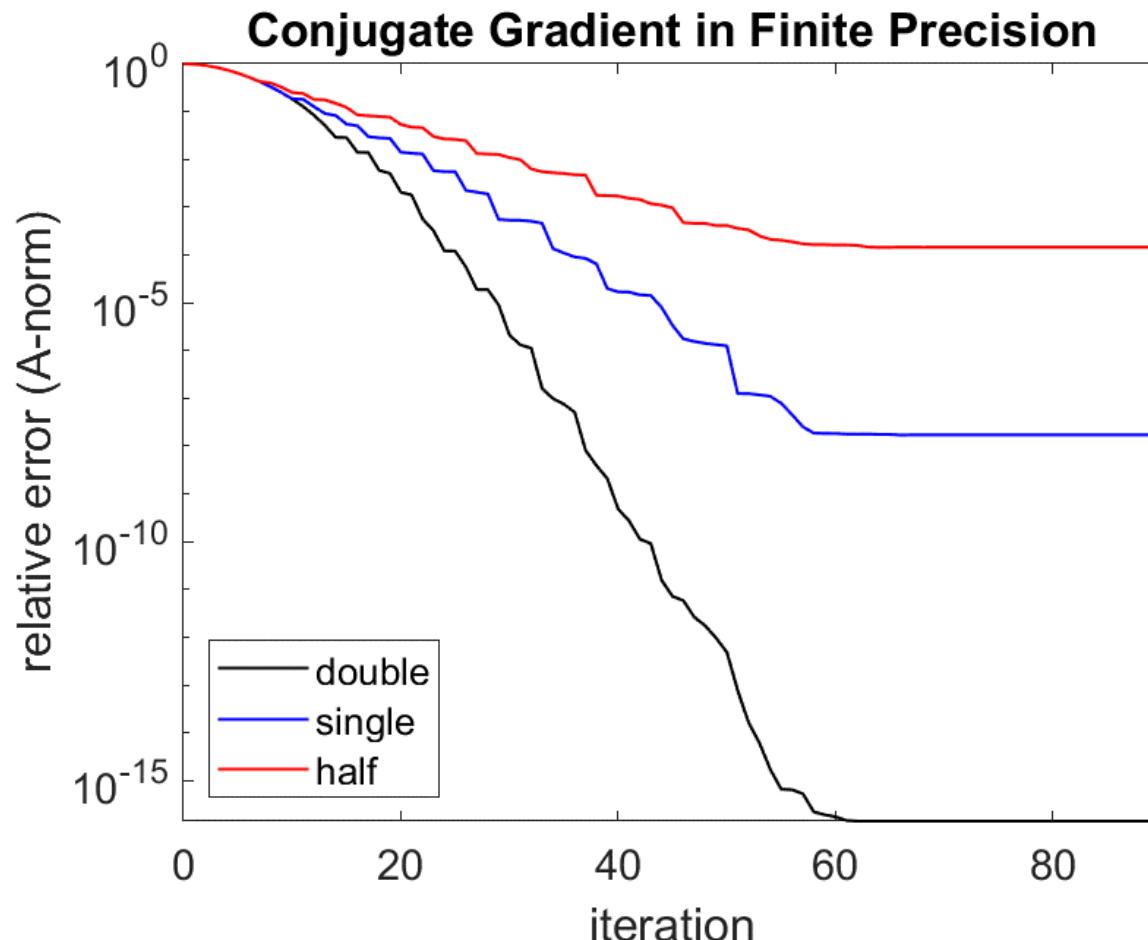


Example: Iterative Methods

$$n = 100, \lambda_1 = 10^{-3}, \lambda_n = 1$$

$$\lambda_i = \lambda_1 + \left(\frac{i-1}{n-1} \right) (\lambda_n - \lambda_1) (0.65)^{n-i}, \quad i = 2, \dots, n-1$$

```
[V, ~] = eig(A);  
b = V' * ones(n, 1);
```



Takeaway

- Low precision can have massive performance benefits but must be used with caution!
- Many opportunities for using mixed and low precision computation in scientific applications
- Need to develop a theoretical understanding of how mixed precision algorithms behave; need to revisit analyses of algorithms and techniques that ignore finite precision

Iterative Refinement for $Ax = b$

Iterative refinement: well-established method for improving an approximate solution to $Ax = b$

A is $n \times n$ and nonsingular; u is unit roundoff

Solve $Ax_0 = b$ by LU factorization (in precision $\textcolor{red}{u}_f$)

for $i = 0$: maxit

$r_i = b - Ax_i$ (in precision $\textcolor{blue}{u}_r$)

Solve $Ad_i = r_i$ (in precision $\textcolor{orange}{u}_s$)

$x_{i+1} = x_i + d_i$ (in precision $\textcolor{green}{u}$)

Iterative Refinement in 3 Precisions

- 3-precision iterative refinement [C. and Higham, 2018]

u_f = factorization precision, u = working precision, u_r = residual precision

$$u_f \geq u \geq u_r$$

u_s is the *effective precision* of the solve, with $u \leq u_s \leq u_f$

- For triangular solves with LU factors: $u_s = u_f$
- For GMRES preconditioned by LU factors, $u_s = u$ [C. and Higham, 2017]
- New analysis **generalizes** existing types of IR:

Traditional	$u_f = u, u_r = u^2$
Fixed precision	$u_f = u = u_r$
Lower precision factorization	$u_f^2 = u = u_r$

- Enables **new** types of IR: (half, single, double), (half, single, quad), (half, double, quad), etc.

IR3: Summary

Standard (LU-based) IR in three precisions ($\textcolor{brown}{u_s} = \textcolor{red}{u_f}$)

Half $\approx 10^{-4}$, Single $\approx 10^{-8}$, Double $\approx 10^{-16}$, Quad $\approx 10^{-34}$

$\textcolor{red}{u_f}$	$\textcolor{teal}{u}$	$\textcolor{blue}{u_r}$	$\max \kappa_\infty(A)$	Backward error		Forward error
				norm	comp	
H	S	S	10^4	10^{-8}	10^{-8}	$\text{cond}(A, x) \cdot 10^{-8}$
H	S	D	10^4	10^{-8}	10^{-8}	
H	D	D	10^4	10^{-16}	10^{-16}	
H	D	Q	10^4	10^{-16}	10^{-16}	
S	S	S	10^8	10^{-8}	10^{-8}	$\text{cond}(A, x) \cdot 10^{-8}$
S	S	D	10^8	10^{-8}	10^{-8}	
S	D	D	10^8	10^{-16}	10^{-16}	
S	D	Q	10^8	10^{-16}	10^{-16}	

IR3: Summary

Standard (LU-based) IR in three precisions ($\mathbf{u}_s = \mathbf{u}_f$)

Half $\approx 10^{-4}$, Single $\approx 10^{-8}$, Double $\approx 10^{-16}$, Quad $\approx 10^{-34}$

	\mathbf{u}_f	\mathbf{u}	\mathbf{u}_r	$\max \kappa_\infty(A)$	Backward error		Forward error
					norm	comp	
LP fact.	H	S	S	10^4	10^{-8}	10^{-8}	$\text{cond}(A, x) \cdot 10^{-8}$
	H	S	D	10^4	10^{-8}	10^{-8}	10^{-8}
LP fact.	H	D	D	10^4	10^{-16}	10^{-16}	$\text{cond}(A, x) \cdot 10^{-16}$
	H	D	Q	10^4	10^{-16}	10^{-16}	10^{-16}
LP fact.	S	S	S	10^8	10^{-8}	10^{-8}	$\text{cond}(A, x) \cdot 10^{-8}$
	S	S	D	10^8	10^{-8}	10^{-8}	10^{-8}
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	\mathbf{u}_f	\mathbf{u}		norm	comp		
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Fixed	S	S	S	10^8	10^{-8}	10^{-8}	$\text{cond}(A, x) \cdot 10^{-8}$
	S	S	D	10^8	10^{-8}	10^{-8}	10^{-8}
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Standard (LU-based) IR in three precisions ($\textcolor{brown}{u_s} = \textcolor{red}{u_f}$)

Half $\approx 10^{-4}$, Single $\approx 10^{-8}$, Double $\approx 10^{-16}$, Quad $\approx 10^{-34}$

	$\textcolor{red}{u_f}$	$\textcolor{teal}{u}$	$\textcolor{blue}{u_r}$	$\max \kappa_\infty(A)$	Backward error		Forward error
					norm	comp	
LP fact.	H	S	S	10^4	10^{-8}	10^{-8}	$\text{cond}(A, x) \cdot 10^{-8}$
	H	S	D	10^4	10^{-8}	10^{-8}	10^{-8}
LP fact.	H	D	D	10^4	10^{-16}	10^{-16}	$\text{cond}(A, x) \cdot 10^{-16}$
	H	D	Q	10^4	10^{-16}	10^{-16}	10^{-16}
Fixed	S	S	S	10^8	10^{-8}	10^{-8}	$\text{cond}(A, x) \cdot 10^{-8}$
Trad.	S	S	D	10^8	10^{-8}	10^{-8}	10^{-8}
LP fact.	S	D	D	10^8	10^{-16}	10^{-16}	$\text{cond}(A, x) \cdot 10^{-16}$
	S	D	Q	10^8	10^{-16}	10^{-16}	10^{-16}

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	$\textcolor{red}{u_f}$	$\textcolor{teal}{u}$	$\textcolor{blue}{u_r}$	$\max \kappa_\infty(A)$	Backward error		Forward error
					norm	comp	
LP fact.	H	S	S	10^4	10^{-8}	10^{-8}	$\text{cond}(A, x) \cdot 10^{-8}$
New	H	S	D	10^4	10^{-8}	10^{-8}	10^{-8}
LP fact.	H	D	D	10^4	10^{-16}	10^{-16}	$\text{cond}(A, x) \cdot 10^{-16}$
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	New	H	D	10^4	10^{-16}	10^{-16}	10^{-16}
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	New	S	D	10^8	10^{-16}	10^{-16}	10^{-16}

⇒ Benefit of IR3 vs. "LP fact.": no $\text{cond}(A, x)$ term in forward error

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New	S	D	Q	10^8	10^{-16}	10^{-16}	10^{-16}

⇒ Benefit of IR3 vs. traditional IR: As long as $\kappa_\infty(A) \leq 10^4$, can use lower precision factorization w/no loss of accuracy!

GMRES-IR: Summary

GMRES-based IR in three precisions ($\textcolor{brown}{u}_s = \textcolor{green}{u}$)

	$\textcolor{red}{u}_f$	$\textcolor{green}{u}$	$\textcolor{blue}{u}_r$	$\max \kappa_\infty(A)$	Backward error		Forward error
					norm	comp	
LU-IR	H	S	D	10^4	10^{-8}	10^{-8}	10^{-8}
GMRES-IR	H	S	D	10^8	10^{-8}	10^{-8}	10^{-8}
LU-IR	S	D	Q	10^8	10^{-16}	10^{-16}	10^{-16}
GMRES-IR	S	D	Q	10^{16}	10^{-16}	10^{-16}	10^{-16}
LU-IR	H	D	Q	10^4	10^{-16}	10^{-16}	10^{-16}
GMRES-IR	H	D	Q	10^{12}	10^{-16}	10^{-16}	10^{-16}

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	$\textcolor{red}{u}_f$	$\textcolor{green}{u}$	$\textcolor{blue}{u}_r$	$\max \kappa_\infty(A)$	Backward error		Forward error
					norm	comp	
LU-IR	H	S	D	10^4	10^{-8}	10^{-8}	10^{-8}
GMRES-IR	H	S	D	10^8	10^{-8}	10^{-8}	10^{-8}
LU-IR	S	D	Q	10^8	10^{-16}	10^{-16}	10^{-16}
GMRES-IR	S	D	Q	10^{16}	10^{-16}	10^{-16}	10^{-16}
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$$\kappa_\infty(A) \leq \textcolor{green}{u}^{-1/2} \textcolor{red}{u}_f^{-1}$$

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\Rightarrow As long as $\kappa_\infty(A) \leq 10^{12}$, can use half precision factorization and still obtain double precision accuracy!

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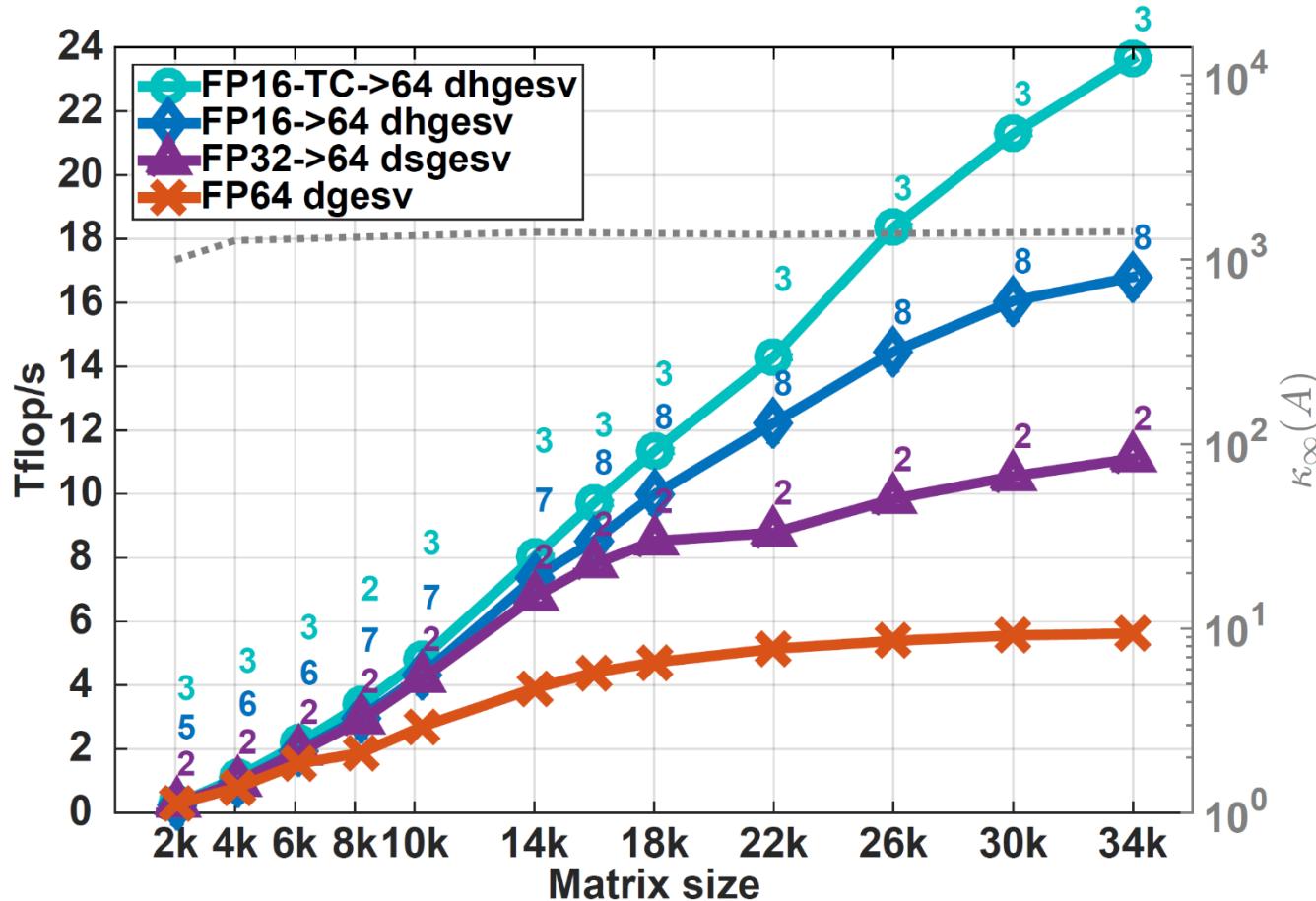
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Recent work: 5-precision GMRES-IR [Amestoy, et al., 2021]

$$\kappa_\infty(A) \leq \textcolor{green}{u}^{-1/3} \textcolor{red}{u}_f^{-2/3}$$

Performance Results (MAGMA)

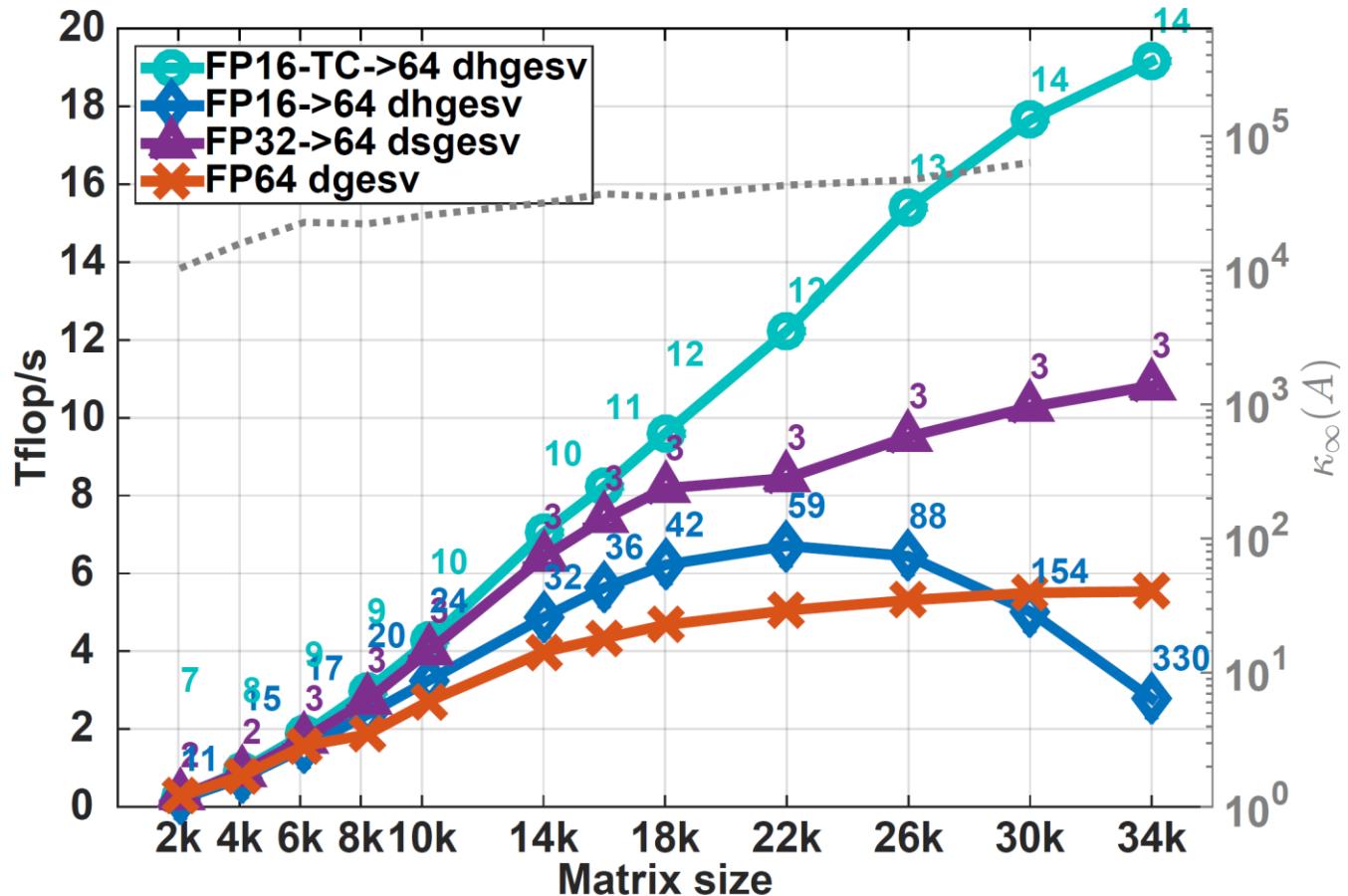
- [Haidar, Tomov, Dongarra, Higham, 2018]



(a) Matrix of type 3: positive λ with clustered singular values, $\sigma_i = (1, \dots, 1, \frac{1}{cond})$.

Performance Results (MAGMA)

- [Haidar, Tomov, Dongarra, Higham, 2018]



(b) Matrix of type 4: clustered singular values, $\sigma_i = (1, \dots, 1, \frac{1}{cond})$.

The rise of multiprecision hardware

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- Lower-precision arithmetic is faster and more energy efficient, but the potential for its use depends heavily on the particular problem and algorithm
- As numerical analysts, we must determine when and where we can exploit lower-precision hardware to improve performance

Thank you!

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