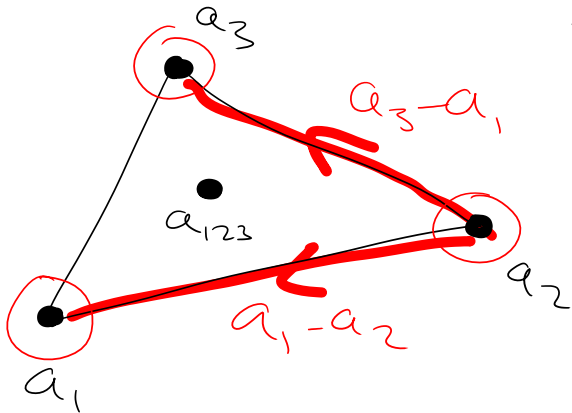


# Hermite finite elements

Degrees of freedom are not only function value at some points but also values of derivatives in certain directions at some points

Example  $T = \text{triangle}$   $P_T = P_3(T)$



- values at vertices & barycentre of element
- derivatives at vertices (either in coordinate direction or along edge)

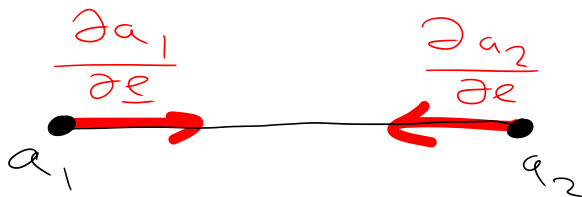
$$\Sigma_T = \{p(a_1), p(a_2), p(a_3), p(a_{123}), \nabla p(a_1), \nabla p(a_2), \nabla p(a_3)\}$$

$$\Sigma'_T = \{p(a_1), p(a_2), p(a_3), p(a_{123}), \nabla p(a_i) \cdot (a_j - a_i), j \neq i, i=1, \dots, 3\}$$

$\hookrightarrow$  Basis equivalent but different advantages/disadvantages

Degrees of freedom corresponding to an edge uniquely determine a cubic function on this edge

$$\Rightarrow X_h \subset C(\bar{\Omega}) \quad (\Rightarrow X_h \subset H^1(\Omega))$$



Can also define finite elements in such a way that

$$X_h \subset C^1(\bar{\Omega}) \Rightarrow X_h \subset H^2(\Omega);$$

for example, for biharmonic equation.

## General definition of finite element

Definition A finite element in  $\mathbb{R}^n$  is a triple  $(T, P, \Sigma)$  where

- 1)  $T$  is a bounded closed subset of  $\mathbb{R}^n$  with non-empty interior and Lipschitz continuous boundary
- 2)  $P$  (or  $P_T$ ) is a finite dimensional space of real functions on  $T$ ;  $N = \dim P$
- 3)  $\Sigma$  set of  $N$  linear forms  $\phi_i, i=1, \dots, N$ , defined on  $P$  such that the set is  $P$ -unisolvent; i.e.,  
 $\forall \alpha_1, \dots, \alpha_N \in \mathbb{R} \quad \exists! p \in P : \phi_i(p) = \alpha_i, i=1, \dots, N$

Unisolvence  $\Rightarrow$   $\left\{ \begin{array}{l} \phi_1, \dots, \phi_N \text{ are linearly independent} \\ \text{Here } \exists \text{ functions } p_i \in P, i=1, \dots, N : \phi_j(p_i) = \delta_{ij}, i, j=1, \dots, N \end{array} \right.$

$$\Rightarrow p = \sum_{i=1}^N \phi_i(p) p_i \quad \forall p \in P.$$

Linear forms  $\phi_1, \dots, \phi_N$  - degrees of freedom of the finite element  
Functions  $p_1, \dots, p_N$  - basis functions of the finite element

## Remarks

- $P$ -unisolvence of  $\Sigma$  is equivalent to fact that  $\phi_1, \dots, \phi_N$  form a basis in dual space of  $P$   
 $\Rightarrow$  basis  $\{p_i\}_{i=1}^N$  and  $\{\phi_i\}_{i=1}^N$  are dual basis in algebraic sense.
- To verify that  $\Sigma$  is  $P$ -unisolvent there are two basic ways:
  - Construct basis functions of  $P$  satisfying  $\phi_j(p_i) = \delta_{ij}$
  - Show that  $\phi_i(p) = 0, i=1, \dots, N \Rightarrow p=0$  for any  $p \in P$

Definition Assume the functionals from  $\Sigma$  are defined on a larger space  $Q \supset P$ . We define a projection  $\Pi: Q \rightarrow P$  by

$$\Pi v = \sum_{i=1}^N \phi_i(v) p_i, \quad v \in Q$$

$\Pi$  is called the  $P$ -interpolation of function  $v$   
(sometimes use  $\Pi_T$  for a specific finite element)

Since  $\Sigma$  is  $P$ -unisolvant the  $P$ -interpolation of  $v$  can be equivalently defined by

$$\Pi v \in P, \quad \phi_i(\Pi v) = \phi_i(v), \quad i=1, \dots, N.$$

### Remarks

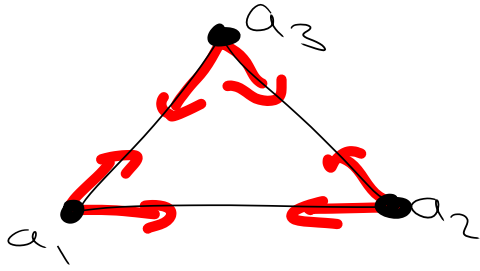
- If the linear forms in  $\Sigma$  represent function values the we speak about Lagrange interpolation ( $\mathcal{D}(\Pi) = Q = C(\tau)$ )
- If the forms in  $\Sigma$  represent both function values and values of derivatives, we speak about Hermite interpolation ( $\mathcal{D}(\Pi) = Q = C^s(\tau), s > 0$ )
- $\Pi$  is a projection;  $\therefore$

$$\Pi p = p \quad \forall p \in P.$$

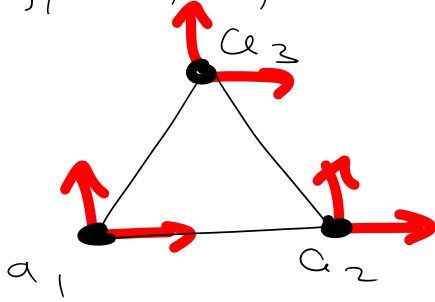
Definition Two finite elements  $(T, P, \Sigma)$  and  $(\tilde{T}, \tilde{P}, \tilde{\Sigma})$  are equal if  $T = \tilde{T}$ ,  $P = \tilde{P}$ , and  $\Pi_T = \Pi_{\tilde{T}}$   
(For example, Hermite - different Dof but same projector)

Example - Reduced cubic Hermite  $n$ -simplex (Fig 8.2)

$$\Sigma = \{ p(a_i), i=1, \dots, n+1; \nabla p(a_i) \cdot (a_j - a_i), i=1, \dots, n+1 \}$$



$$\Sigma' = \{ p(a_i), i=1, \dots, n+1; \frac{\partial p}{\partial x_k}(a_i), i=1, \dots, n+1, k=1, \dots, n \}$$



Denote by  $\Pi$  and  $\Pi'$  the respective interpolation operators. Then,  $\mathcal{D}(\Pi) = \mathcal{D}(\Pi') = C^1(T)$

For any function  $v \in C^1(T)$  we have that

$$(\Pi v)(a_i) = v(a_i) \quad i=1, \dots, n+1$$

$$\nabla(\Pi v)(a_i) \cdot (a_j - a_i) = \nabla v(a_i) \cdot (a_j - a_i) \quad i, j=1, \dots, n+1$$

$$\Rightarrow \nabla(\Pi v)(a_i) = \nabla v(a_i) \quad i=1, \dots, n+1$$

since  $\{a_j - a_i\}_{i \neq j}$  are linearly independent

$$(\Pi' v)(a_i) = \nabla v(a_i), \quad i=1, \dots, n+1$$

$$\frac{\partial(\Pi' v)}{\partial x_k}(a_i) = \frac{\partial v}{\partial x_k}(a_i), \quad i=1, \dots, n+1, k=1, \dots, n$$

$$\Rightarrow (\Pi v)(a_i) = (\Pi' v)(a_i), \quad i=1, \dots, n+1$$

$$\nabla(\Pi v)(a_i) = \nabla(\Pi' v)(a_i), \quad i=1, \dots, n+1$$

$$\Rightarrow \Pi v = \Pi' v \Rightarrow \Pi \equiv \Pi' \text{ and } (T, P, \Sigma) \text{ \& } (T, P, \Sigma') \text{ are equal. } \square$$

Let  $(T, P, \Sigma)$  and  $(\hat{T}, \hat{P}, \hat{\Sigma})$  are any two Lagrange  $n$ -simplices of order  $k$ ; i.e.,

$$T = n\text{-simplex}, P = P_k(T), \Sigma = \{p(z) : z \in L_k(T)\}$$

$$\hat{T} = n\text{-simplex}, \hat{P} = P_k(\hat{T}), \hat{\Sigma} = \{p(\hat{z}) : \hat{z} \in L_k(\hat{T})\}$$

There exists a mapping  $F: \mathbb{R}^n \rightarrow \mathbb{R}^n$  satisfying

$$F(\hat{x}) = B\hat{x} + b, B \in \mathbb{R}^{n \times n}, b \in \mathbb{R}^n, B \text{ is non-singular } \textcircled{*}$$

and  $F(\hat{T}) = T$  (will prove existence later).

A mapping satisfying  $\textcircled{*}$  is called an invertible affine mapping.

We observe that

$$\{p: T \rightarrow \mathbb{R} : p = \hat{p} \circ F^{-1}, \hat{p} \in \hat{P}\} = P$$

$$\{p(F(\hat{z})) : \hat{z} \in L_k(\hat{T})\} = \Sigma$$

$$\text{Denote } \Sigma = \{\phi_i\}_{i=1}^N, \hat{\Sigma} = \{\hat{\phi}_i\}_{i=1}^N$$

$$\begin{aligned} \text{This means that } \phi_i(p) &= p(z_i) & z_i &\in L_k(T) \\ \hat{\phi}_i(\hat{p}) &= \hat{p}(\hat{z}_i) & \hat{z}_i &\in L_k(\hat{T}) \end{aligned}$$

For appropriate number of points, we have that

$$F(\hat{z}_i) = z_i, i=1, \dots, N. \text{ Thus,}$$

$$\phi_i(p) = \hat{\phi}_i(p \circ F), i=1, \dots, N$$

(equivalent)

Definition Two finite elements  $(\hat{T}, \hat{P}, \hat{\Sigma})$  and  $(T, P, \Sigma)$  are affine-equivalent if there exists an invertible affine mapping  $F: \mathbb{R}^n \rightarrow \mathbb{R}^n$  such that

$$T = F(\hat{T})$$

$$P = \{ p: T \rightarrow \mathbb{R} : p = \hat{p} \circ F^{-1}, \hat{p} \in \hat{P} \}$$

$$\Sigma = \{ \phi: \phi(p) = \hat{\phi}(p \circ F), \hat{\phi} \in \hat{\Sigma} \}$$

Remark If  $(\hat{T}, \hat{P}, \hat{\Sigma})$  is a finite element and  $(T, P, \Sigma)$  is affine equivalent to it, then  $(T, P, \Sigma)$  is also a finite element. (can generate finite elements by simply using one fixed finite element  $(\hat{T}, \hat{P}, \hat{\Sigma})$  called the reference element.)

For example, for rectangle ( $n=2$ ) or order to define the reference rectangle  $(\hat{T}, \hat{P}, \hat{\Sigma})$  ( $\hat{T} = [0, 1]^2$  for example) and using an affine mapping we can obtain a finite element for any  $T$  which is a parallelogram.

We can also consider more general mappings  $F$ ; e.g. for arbitrary convex quadrilaterals or elements with curved boundaries.

Remark To verify unisolvence of  $(T, P, \Sigma)$  sufficient to investigate an affine-equivalent finite element  $(\hat{T}, \hat{P}, \hat{\Sigma})$ , where  $\hat{T}$  has a simple geometry.