Numerical Solution of ODEs

Exercise Class

10th October 2023

Cat & Mouse

We consider an ordinary differential equation system modeling a cat chasing a mouse (in two dimensions). The mouse moves from an initial position (1,0) to its hole at (0,0) with constant velocity v_m . We can model its position $\mathbf{y}(t) = (y_1(t), y_2(t))$ at time t as

$$\boldsymbol{y}(t) = \begin{pmatrix} 1 - v_m t \\ 0 \end{pmatrix}, \qquad t \in \left[0, \frac{1}{v_m}\right].$$

The cat moves from an initial position $\tilde{\boldsymbol{x}} \in \mathbb{R}^2$, $\tilde{x}_2 > 0$, with constant velocity $v_c > 0$ towards the mouses' *current position*. The position of the cat at time t is denoted by $\boldsymbol{x}(t) = (x_1(t), x_2(t))$. To calculate the cat's position we note that at time t the mouse moves in the direction of the vector $\boldsymbol{y}(t) - \boldsymbol{x}(t)$; i.e., towards the mouse. The change in position of the cat with respect to time is given by

$$\frac{\mathrm{d}x_1}{\mathrm{d}t} = f(t)(y_1(t) - x_1(t)) = f(t)(1 - v_m - x_1)$$
$$\frac{\mathrm{d}x_2}{\mathrm{d}t} = f(t)(y_2(t) - x_2(t)) = -f(t)x_2$$

for a function f(t) dependent on t. We can then calculate the velocity of the cat as

$$\left(\left(\frac{\mathrm{d}x_1}{\mathrm{d}t}\right)^2 + \left(\frac{\mathrm{d}x_2}{\mathrm{d}t}\right)^2\right).$$

However, we know the cat has fixed velocity v_c ; therefore,

$$v_c^2 = (f(t))^2 \left((1 - v_m t - x_1)^2 + x_2^2 \right)$$

$$\implies \qquad f(t) = v_c \left((1 - v_m t - x_1)^2 + x_2^2 \right)^{-1/2}$$

Hence, we derive the ODE system

$$\begin{pmatrix} \frac{\mathrm{d}x_1}{\mathrm{d}t} \\ \frac{\mathrm{d}x_2}{\mathrm{d}t} \end{pmatrix} = \frac{v_c}{\left((1 - v_m t - x_1)^2 + x_2^2\right)^{1/2}} \begin{pmatrix} 1 - v_m t - x_1 \\ -x_2 \end{pmatrix}$$

Exercises

- 1. Play with the cat & mouse simulation $catmouse.m/run_catmouse.m$
 - (a) Try various starting positions \tilde{x} for the cat and velocities v_m, v_c .
 - (b) Is there any strange behaviour occuring? When does it occur and why?
 - (c) Study and use run_catmousevents.m to see how ode23 can be used to detect an event the cat catching the mouse $(|\boldsymbol{x} \boldsymbol{y}| = 0)$.
- 2. Does the cat & mouse simulation work in one dimension; i.e., $\tilde{x}_2 = 0$? Solve analytically when/if the cat catches the mouse in this situation for *all* possible starting positions of the cat.
- 3. The built-in MATLAB simulation ballode simulates a bouncing ball:

$$x^{\prime\prime} = -g \qquad \equiv \qquad \begin{cases} x_1^{\prime} = x_2 \\ x_2^{\prime} = -g \end{cases}$$

where $g = -9.8 \text{ m/s}^2$ is the Earth's gravity, with attenuation of the velocity on hitting the ground (90%). Copy this script and create a variant to handle dynamical friction:

$$x'' = -g - ax'$$

where a > 0 represents friction.

4. Use blowupex.m to investigate the blow-up behaviour of the ODE:

$$\begin{aligned} x'(t) &= x^2 \\ x(0) &= 1 \end{aligned}$$

- (a) Plot, using dirfield.m from last week, the direction field over the intervals $t \in [-1, 1]$ and $x \in [-2, 2]$.
- (b) Study the solutions, when computing using ode23, over the time intervals $t \in [0, 0.99]$, $t \in [0, 1]$, and $t \in [0, 2]$.
- 5. Use collapseex.m to investigate the collapse behaviour of the ODE:

$$x'(t) = -x^{-1/2},$$

 $x(0) = 1$

- (a) Plot, using dirfield.m from last week, the direction field over the intervals $t \in [-1, 1]$ and $x \in [.01, 2]$.
- (b) Study the solutions, when computing using ode23, over the time intervals $t \in [0, 2/3]$ and $t \in [0, 1]$.