

# Domain of stability

Consider the pendulum with dynamical friction

$$\dot{x}_1 = x_2$$

$$\dot{x}_2 = -k \sin x_1 + \varepsilon x_2$$

with initial conditions  $x_0 \in \mathbb{R}^2$  at time  $t_0 = 0$

$$\text{Set } k=1, \varepsilon = -0.2$$

What are the steady states?

$$x_2 = 0$$

$$-k \sin x_1 + \varepsilon x_2 = 0 \Rightarrow \sin x_1 = 0$$

$$\rightarrow x_1 = n\pi, n \in \mathbb{Z}$$

Which of these A-stable? Consider  $n$  odd/even separately.

$$A = \begin{pmatrix} 0 & 1 \\ -k \cos n\pi & \varepsilon \end{pmatrix}$$

$$\det(\lambda I - A) = \lambda(\lambda - \varepsilon) + k \cos n\pi$$
$$= \lambda^2 - \lambda\varepsilon + k \cos n\pi$$

$$\Rightarrow \lambda = \frac{\varepsilon \pm \sqrt{\varepsilon^2 - 4k \cos n\pi}}{2} = -0.1 \pm \sqrt{0.01 - \cos n\pi}$$

$(\varepsilon = -0.2, k = 1)$

$n$  even ( $\cos n\pi = 1$ )

$$\lambda = -0.1 \pm \sqrt{0.99} i$$

$$\Rightarrow \max_{\lambda \in \sigma(A)} \operatorname{Re}(\lambda) = -0.1 \Rightarrow \underline{\underline{A\text{-stable}}}$$

$n$  odd ( $\cos n\pi = -1$ )

$$\lambda = -0.1 \pm \sqrt{1.01} \Rightarrow \max_{\lambda \in \sigma(A)} \operatorname{Re}(\lambda) = \sqrt{1.01} - 0.1 > 0 \Rightarrow \underline{\underline{Unstable}}$$