## XII. 5 Symmetric operators and the Cayley transform

Definition. Let $S$ be a symmetric (not necessarily densely defined) operator on $H$. Denote by $C_{S}$ the operator

$$
C_{S}=(S-i I)(S+i I)^{-1}
$$

Then $C_{S}$ is an operator on $H$, which is called the Cayley transform of the operator $S$.
Theorem 27 (properties of $C_{S}$ ). Let $S$ be a symmetric operator on $H$ and let $C_{S}$ be its Cayley transform. Then
(a) $C_{S}$ is a linear isometry of $D\left(C_{S}\right)=R(S+i I)$ onto $R\left(C_{S}\right)=R(S-i I)$.
(b) $I-C_{S}=2 i(S+i I)^{-1}$; in particular, the operator $I-C_{S}$ is one-to-one and $R\left(I-C_{S}\right)=$ $D(S)$.
(c) $S=i\left(I+C_{S}\right)\left(I-C_{S}\right)^{-1}$.
(d) $C_{S}$ is closed $\Leftrightarrow S$ is closed $\Leftrightarrow D\left(C_{S}\right)$ is closed $\Leftrightarrow R\left(C_{S}\right)$ is closed.

Lemma 28 (on an isometric operator). Let $U$ be any operator on $H$, which is an isometry of $D(U)$ onto $R(U)$. Then
(a) $\langle U x, U y\rangle=\langle x, y\rangle$ for any $x, y \in D(U)$. In particular: $U$ is unitary if and only if $D(U)=R(U)=H$.
(b) $\operatorname{Ker}(I-U)=D(U) \cap(R(I-U))^{\perp}$. In particular, if $R(I-U)$ is dense in $H$, then $I-U$ is one-to-one.

Theorem 29 (range of the Cayley transform). Let $U$ be an operator on $H$, which is an isometry of $D(U)$ onto $R(U)$. Suppose that $I-U$ is one-to-one. Then the operator $S=i(I+U)(I-U)^{-1}$ is symmetric and $C_{S}=U$. Further, $S$ is densely defined if and only if $R(I-U)$ is dense.

Theorem 30 (Cayley transform for selfadjoint operators).
(a) Let $S$ be a symmetric operator on $H$. Then $S$ is selfadjoint if and only if $C_{S}$ is a unitary operator.
(b) Let $U$ be a unitary operator na $H$ such that $I-U$ is one-to-one. Then the operator $S=i(I+U)(I-U)^{-1}$ is selfadjoint and $C_{S}=U$.

## Remarks.

(1) Let $S$ and $T$ be symmetric operators on $H$. Then $S \subset T$ if and only if $C_{S} \subset C_{T}$.
(2) Let $S$ be a densely defined closed symmetric operator on $H$. The codimensions of the subspaces $D\left(C_{S}\right)$ and $R\left(C_{S}\right)$ (i.e., the dimensions of their orthogonal complements) are called the deficiency indices of the operator $S$. Then:

- $S$ is selfadjoint if and only if both deficiency indices are zero.
- $S$ is a maximal symmetric operator if and only if at least one of the deficiency indices is zero.
- $S$ has a selfadjoint extension if and only if both deficiency indices are the same (i.e., if and only if there exists a linear isometry of $\left(D\left(C_{S}\right)\right)^{\perp}$ onto $\left.\left(R\left(C_{S}\right)\right)^{\perp}\right)$.
(3) Let $S$ be a closed symmetric operator on $H$, not necessarily densely defined. Also in this case one may define the deficiency indices. Moreover:
- If $D\left(C_{S}\right)=H$ or $R\left(C_{S}\right)=H$, then $S$ is densely defined.

Hence, also in this case the first of the above equivalences holds. It easily follows that in the second assertion $\Leftarrow$ holds and in the third assertion $\Rightarrow$ holds. The validity of the converse implications seems not to be clear.

