

Name:

Convex optimization

Homework set 3

Date due: **October 30 2019, 17:21**

Explain your reasoning in all the problems.

Problem	Pts max	Pts
1	2	
2	2	
3	2	
4	2	
5	2	
Σ	10	

Problem 1. Let $p \geq 1$.

a) Prove that the function $f(x) = x^p$ with domain \mathbb{R}_{++} is convex by calculating second derivatives.

b) There are technical problems with taking the derivative of x^p at $x = 0$. These problems could be resolved, but we ask you instead to use the definition of convexity and the convexity of f from part a) to show that the function $g(x) = x^p$ for $x \geq 0$ is convex. Note: The only difference between f and g is at the point $x = 0$.

Problem 2. Prove in detail that a function $f: \mathbb{R}^n \rightarrow \mathbb{R}$ is convex if and only if its epigraph is a convex subset of \mathbb{R}^{n+1} .

Problem 3. Prove that the function $f_2(x_1, x_2) = \ln(\exp(x_1) + \exp(x_2))$ is convex.

Problem 4. 21 dwarves are mining gold in a mine. Each dwarf has a different productivity and we would like to be able to estimate the different dwarves' productivity. However, we only have data on how much total gold was mined in a given day and which dwarves were working on that day.

Formulate the problem as a least squares problem and solve it using CVX-OPT or CVXPY.

The data is in the file `mining.csv`; the columns are days, lines denote the attendance of a given dwarf and the bottom line are the kilograms of gold mined. (Python has the module "csv" for reading .csv files, but it is OK if you hard-code the productivity table into your program.)

Explain here on paper what your model is and *send* your code and the vector of estimated dwarf productivities by the due date to Jiří to `pavluji@artax.karlin.mff.cuni.cz`

Problem 5. Let X be a system consisting of many simple pieces (molecules, people, ...). Each of these pieces can be in one of n states and switch states in some random manner. Let p_i be the fraction of the pieces that are in state i . To avoid some technicalities, assume that $p_i > 0$ for all i (notice that $\sum_{i=1}^n p_i = 1$).

For $(p_1, \dots, p_n) \in \mathbb{R}_{++}^n$ such that $\sum_{i=1}^n p_i = 1$, we define the *entropy* of the system by

$$S(p_1, \dots, p_n) = - \sum_{i=1}^n p_i \ln p_i.$$

We have some macroscopic data about the system. Under reasonable assumptions, systems tend to be in states that maximize entropy. These are the “most disorganized” states compatible with the macroscopic observations.

- a) Prove that S is a *concave* function (do not forget to discuss its domain).
- b) Assume that our system consists of Czech population and a person can be in one of 99 states, where the i -th state means “this person earns i thousand Kč per month.” In addition, we know that the average Czech monthly salary is 31 000 Kč. Use CVXOPT/CVXPY to find the numbers p_i that maximize the entropy in the above situation.

I recommend using CVXPY here. The solution in CVXOPT is more work-intensive; you will need to use the function `cvxopt.solvers.cp` and to define the function S and its gradient and Hessian on your own.

You only have to write your solution of part a) here on paper. For part b), *send* your program and the output 99-tuple $(p_i)_{i=1}^{99}$ to Jiří to `pavluji@artax.karlin.mff.cuni.cz`

You can consult with your friends when solving the homework, but you have to **write** your solutions (including Python code) **on your own** and **do not show your finished solutions** to your peers before the due date.