

Algorithms that decide absorption

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What is absorption?

Definition (Libor Barto, Marcin Kozik)

Let $\mathbf{B} \leq \mathbf{A}$ be algebras. We say that \mathbf{B} **absorbs** \mathbf{A} if there exists a term t in \mathbf{A} such that for any $b_1, \dots, b_n \in B, a \in A$ we have:

$$\begin{aligned}t(a, a, a, \dots, a) &= a \\t(a, b_2, b_3, \dots, b_{n-1}, b_n) &\in B \\t(b_1, a, b_3, \dots, b_{n-1}, b_n) &\in B \\&\vdots \\t(b_1, b_2, b_3, \dots, b_{n-1}, a) &\in B\end{aligned}$$

Notation for absorption: $\mathbf{B} \triangleleft \mathbf{A}$.

Ok, but what *is* absorption?

- If 0 is the minimal element of a semilattice (L, \wedge) , then $\{0\}$ absorbs L ; absorption term is $t(x_1, x_2) = x_1 \wedge x_2$.
- If \mathbf{A} is an algebra with a majority term m , then every singleton is an absorbing subalgebra; absorption term is m .
- $\mathbf{A} \trianglelefteq \mathbf{A}$ always.
- \mathbf{A} has an NU term iff $\{a\} \trianglelefteq \mathbf{A}$ for every $a \in A$.
- If \mathbf{A} is an abelian group, then \mathbf{A} has no proper absorbing subalgebra.

What is absorption good for?

A “connected” and $\mathbf{B} \trianglelefteq \mathbf{A} \Rightarrow \mathbf{B}$ “connected”.

Major recent results using absorption:

- $\text{CSP}(\mathbb{A})$ is solvable by local consistency checking iff **A** is $SD(\wedge)$ (Barto, Kozik).
- If **A** is finitely related and CD, then **A** has an NU operation. (Barto and Zhuk independently)
- If **A** is finitely related and CM, then **A** has a cube term. (Barto)
- If **A** has an NU operation, then $\text{CSP}(\mathbb{A})$ has bounded pathwidth duality and lies in NL (Barto, Kozik, Willard).
- A new proof of: **A** finite + solvable + Taylor \Rightarrow **A** has a Maltsev term (Stanovský).

- Problem: Given $\mathbf{B} \leq \mathbf{A}$, can we decide if $\mathbf{B} \trianglelefteq \mathbf{A}$?
- Libor Barto, Jakub Bulín: Yes, if \mathbf{A} is given by a finite set of relations.
- What about if \mathbf{A} is given by a finitely many operations instead?
- Miklós Maróti: We can decide whether a finite algebra $\mathbf{A} = (A, f_1, \dots, f_n)$ has an NU term.

- Weaker notion of absorption inspired by Kozik's terms for congruence distributivity.
- Let $\mathbf{B} \leq \mathbf{A}$. Then $\mathbf{B} \trianglelefteq_J \mathbf{A}$ if there exist idempotent terms d_0, d_1, \dots, d_n such that:

$$\forall i = 1, \dots, n, d_i(B, A, B) \subset B$$

$$d_1(x, x, y) = x$$

$$d_i(x, y, y) = d_{i+1}(x, x, y)$$

$$d_n(x, y, y) = y.$$

- If \mathbf{A} is finitely related, then $\mathbf{B} \trianglelefteq_J \mathbf{A}$ implies $\mathbf{B} \trianglelefteq \mathbf{A}$ (Barto, Bulín).

Jónsson is not enough

- Look at $(\{0, 1\}, \rightarrow)$.
- $\{0\} \trianglelefteq_J \{0, 1\}$ as witnessed by the Jónsson absorbing terms:

$$d_1(x, y, z) = (y \rightarrow (z \rightarrow x)) \rightarrow x,$$

$$d_2(x, y, z) = (x \rightarrow (y \rightarrow z)) \rightarrow z,$$

- However, $\{0\}$ does not absorb $\{0, 1\}$.
- How to see that: Look at relations $\{0, 1\}^n \setminus \{0\}^n$.

- We call (C, D) a **B-blocker** if
 - $\emptyset \neq C \leq D \leq \mathbf{A}$,
 - $D \cap B \neq \emptyset$,
 - $C \cap B = \emptyset$,
 - $\{(x_1, \dots, x_n) \in D^n : \exists i, x_i \in C\} \leq \mathbf{A}^n$ for every $n \in \mathbb{N}$.
- If $\mathbf{B} \trianglelefteq \mathbf{A}$, then there is no **B-blocker**.

Good and bad news about blockers

- Given idempotent \mathbf{A} with finitely many operations, we can test if there are no \mathbf{B} -blockers.
- However, we can have no blockers and no absorption: Consider $\mathbf{A} = (\mathbb{Z}_2, m)$, where $m(x, y, z) = x + y + z \pmod{2}$.

Putting it all together



Theorem

Let \mathbf{A} be a finite idempotent algebra, $\mathbf{B} \leq \mathbf{A}$. Then $\mathbf{B} \trianglelefteq \mathbf{A}$ iff there is no \mathbf{B} -blocker and $\mathbf{B} \trianglelefteq_J \mathbf{A}$.

Corollary

We can decide $\mathbf{B} \trianglelefteq \mathbf{A}$ algorithmically.

Warning

- Decision problems come in two basic flavors: \mathbf{A} can be given by tables of its basic operations, or by a set of invariant relations.
- The complexity of deciding something for \mathbf{A} and for \mathbb{A} can be different!
- If we have basic operations, we can generate subalgebras quickly, but have trouble deciding if a given operation belongs into the clone of \mathbf{A} .
- If we have relations, it is the other way around.

Idempotent algorithms

- Given \mathbf{A} by basic operations, we can decide if $\mathbf{B} \trianglelefteq_J \mathbf{A}$ in polynomial time.
- For deciding B -blockers, we have one algorithm running in time $O(|\mathbf{A}|3^{|\mathbf{A}|})$ and another running in time $O(|\mathbf{A}| \prod_i s_i)$ where s_i is the arity of the i -th basic operation of \mathbf{A} .
- Given $\mathbf{B} \leq \mathbf{A}$, deciding existence of a \mathbf{B} -blocker is NP-complete. (reduction from 3-SAT).
- Good news: Deciding if a given \mathbf{A} has some blocker for some \mathbf{B} can be done in polynomial time.

Algorithm for relational structures

- If \mathbf{A} is given by a relational structure, all we need is to decide $\mathbf{B} \trianglelefteq_J \mathbf{A}$.
- Best known general algorithm: Time roughly $|\mathbb{A}||A|^{|\mathbb{A}|^3}$.
- The issue: How to get 3-generated subalgebras of \mathbf{A}^3 quickly.
- Special cases can be much easier:
- If we can solve $\text{CSP}(\mathbb{A})$ in P then deciding \trianglelefteq_J is in P, too.
- Note: Deciding NU for relational structures is in P.

- If \mathbf{A} is not idempotent, we would also like to decide absorption.
- Problem with taking the idempotent reduct: We might lose the generators of the clone of \mathbf{A} .
- Imitating some of Dmitriy Zhuk's ideas gives us an algorithm anyway.
- Deciding $\mathbf{B} \trianglelefteq_J \mathbf{A}$ can be done in time $O(|\mathbf{A}|^{|\mathbf{A}|+3})$, deciding existence of a B -blocker is (roughly) doubly exponential in this way.

Thank you for your attention.