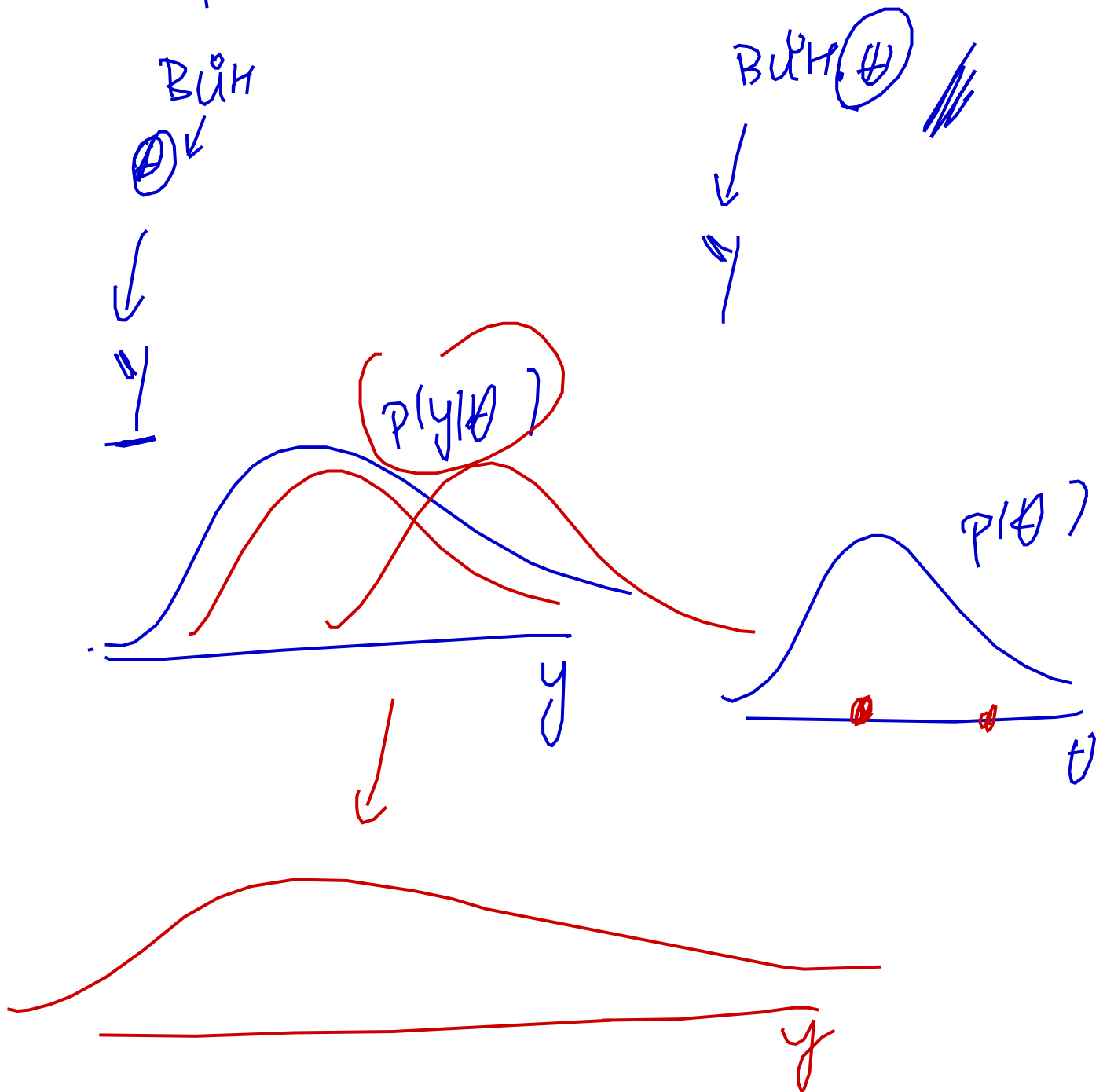


# Bayes factor

Bayes model:  $P(y|\theta), P(\theta)$

$$P(y, \theta) = P(y|\theta) \cdot P(\theta)$$



unobserved models  $M_1, \dots, M_k$

$$P_k(y|\theta_k) \rightarrow P_k(y) \equiv P(y|M_k)$$
$$P_k(\theta_k)$$

každý model  $\rightarrow$  má svou představu,  
jde o různé

$P(M_1), \dots, P(M_r)$ : aprior. prsh.  
jednotl. modelů

$\rightarrow$  Bayes. věta

$$P(M_k | y) \propto P(y | M_k), P(M_k)$$

---

Bayes factor

$$BF(M_k, M_e) = \frac{P(y | M_k)}{P(y | M_e)}$$

$$P_k(y) = \int P(y | \theta_k) p(\theta_k) d\theta_k =$$

$$= \mathbb{E}_{p(\theta_k)} P(y | \theta_k)$$

co delat. pokud  $p(\theta_k) \propto 1$

$\mathbb{E}_w$  nemusí existovat

Weakly informative, např.

$$\tau = \text{invert. např. } p(\tau) = \text{Gamma}(\epsilon, \epsilon) \\ \epsilon \rightarrow 0$$

# PO A posteriori prediktivni vzorec

MODEL:  $P(y|\theta), P(\theta)$

$$\rightarrow \underline{P(y)} = \int P(y|\theta) p(\theta) d\theta$$

$y_{\text{nov}} \sim P(y)$

předp.  $y \perp y_{\text{nov}}$  za podm.  $\theta$

$$P(y_{\text{nov}}|y) = \int P(y_{\text{nov}}, \theta | y) d\theta =$$

$$= \int P(y_{\text{nov}} | \theta, y) P(\theta | y) d\theta =$$

$$= \int \underbrace{P(y_{\text{nov}} | \theta)}_{\text{v\u011bhodu modelu}} P(\theta | y) d\theta$$

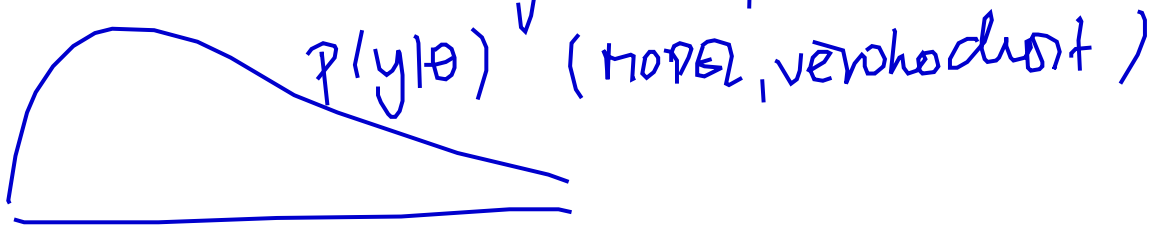
SPROVUB:

$$P(y) = \int P(y|\theta) \underline{p(\theta)} d\theta = E_{P(\theta)} P(y|\theta)$$

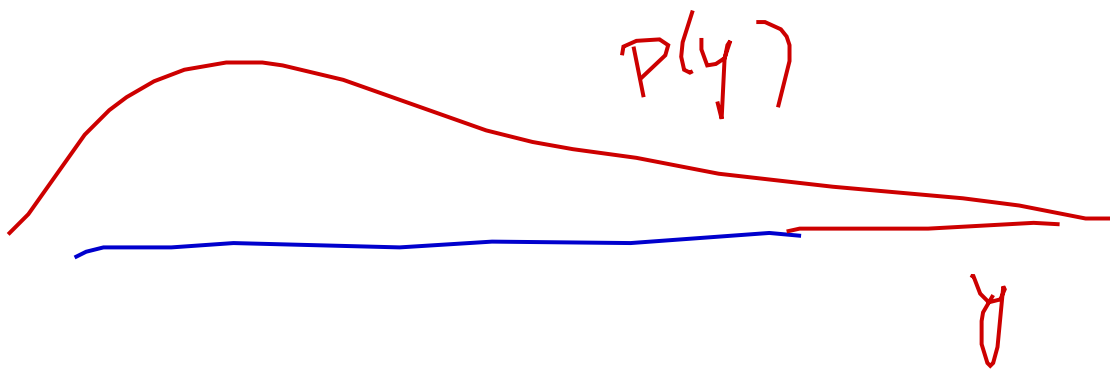
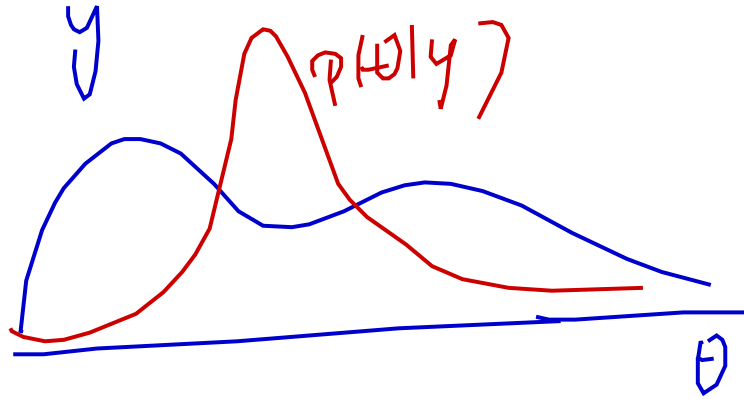
$$P(y_{\text{nov}}|y) = \int P(y_{\text{nov}}|\theta) \underline{P(\theta|y)} d\theta$$

$$= E_{P(\theta|y)} P(y_{\text{nov}}|\theta)$$

↓  
važený průměr věrohodnosti,  
kde  $v_i$  = a poster. w. del.

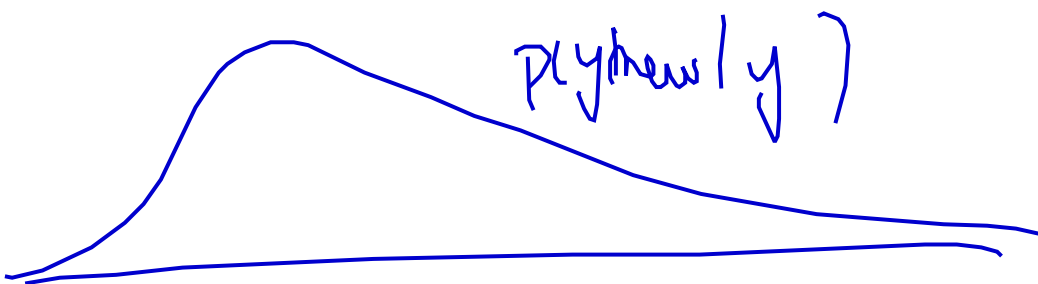


aprior:



DATA

→  $p(\theta|y)$



↑  
vhodne' le predikovan'  $y_{new}$

$$KL(Q_2, Q_1) = E_{Q_1} \log \frac{q_1(y)}{q_2(y)}$$

---

$Q_1 \equiv Q \equiv$  skutečné rozdíl. dat  
 $\equiv P(y)$

$Q_2 \equiv P(y|\theta)$  (včetně klasických modelů)