

Mal'tsev terms & compact representations

6th CWC
26.09.24 - Calfasch

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Local consistency: only small, local and necessary changes,
does not waste resources \Rightarrow *conservative*

Linear equations: costly, ineffective (Gaussian elimination),
constantly invents something new that never works out
(more effective algorithms) \Rightarrow *socialist*

Fun fact: Finite-domain CSP solved by a combination
of local consistency and linear equations (Bulatov, Zhuk, 2017)

Tomáš Nagy
AAA105

„Neoliberalism and local consistency”

Mal'tsev terms,
compact representations
& socialism

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The dialectical materialism of linear equations

Example: solving linear equations over \mathbb{Z}_3

-) row echelon form \Leftrightarrow basis of solution space

$$\begin{pmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 2 & 0 \end{pmatrix} \bar{x} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} \Leftrightarrow \bar{x} \in V := \begin{pmatrix} 2 \\ 1 \\ 0 \\ 0 \end{pmatrix} + \left\langle \begin{pmatrix} -1 \\ -2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} \right\rangle$$

-) adding an equation \Leftrightarrow intersecting spaces

$$\begin{pmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 2 & 0 \\ 1 & 0 & 0 & 1 \end{pmatrix} \bar{x} = \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} \Leftrightarrow \bar{x} \in V \cap W \quad W = \left\langle \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 0 \\ 1 \end{pmatrix} \right\rangle$$

-) Gauss elimination \Leftrightarrow find basis of intersection

$$\begin{pmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 2 \end{pmatrix} \bar{x} = \begin{pmatrix} 0 \\ 0 \\ 2 \end{pmatrix} \Leftrightarrow \bar{x} \in V \cap W = \begin{pmatrix} 0 \\ 0 \\ 2 \\ 0 \end{pmatrix} + \left\langle \begin{pmatrix} -1 \\ -1 \\ -2 \\ 1 \end{pmatrix} \right\rangle$$

The dialectical materialism of linear equations

Example: solving linear equations over $\mathbb{Z}_3 \approx \text{CSP}(\mathbb{Z}_3^{\text{rel}})$

$$\mathbb{Z}_3^{\text{rel}} := (\mathbb{Z}_3, \{0\}, \{1\}, \{2\}, R_+) \quad R_+ = \{(x, y, z) \mid z \equiv x + y \pmod{3}\}$$

Solve $R_+(x_1, x_2, x_4) \wedge (x_2 = 2) \wedge R_+(x_4, x_4, x_3) \wedge \dots$

by iteratively computing canonical generating sets of solution set of first n constraints.

(closure under $x-y+z$)

How far can this idea be pushed?

- BD '06 : Mal'tsev
- D'05 : maj.-min
- IMM/VW '10 : few subpowers

Outline

- 1) What are **Mal'tsev constraints**?
- 2) What are the 'canonical generating sets'?'
compact representations
- 3) **The algorithm**
- 4-) **Beyond CSP**



Bulatov, Dalman

2006 A simple algorithm
for Mal'tsev
constraints

Mal'tsev operation

$d: A^3 \rightarrow A$ is Mal'tsev
if $d(yxx) \approx d(xxy) \approx y$

Mal'cev
Malcev
Maltsev
МАЛТЬЦЕВ

An algebra \underline{A} / clone \mathcal{C} is Mal'tsev if $\text{Cl}(\underline{A})/\mathcal{C}$ contains
a Mal'tsev operation.

Examples

→ ring $(A; +, 0, -, \cdot)$

$$d(xyz) = x - y + z$$

→ group $(A; \cdot, 1, {}^{-1})$

$$d(xyz) = x \cdot y^{-1} z$$

→ BA $(A, \wedge, \vee, 0, 1, \neg)$

$$d(xyz) = (x \wedge y \wedge z) \vee (x \wedge \neg y \wedge \neg z) \vee (\neg x \wedge y \wedge z)$$

→ minority

$$m(xyy) \approx m(yxy) = m(xyy) = x$$

→ semilattice (A, \wedge)

×

Mal'tsev operation

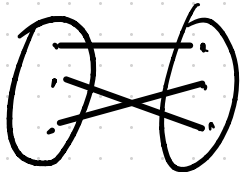
$d: A^3 \rightarrow A$ is Mal'tsev
if $d(yxx) \approx d(xxy) \approx y$

Examples (polymorphisms)

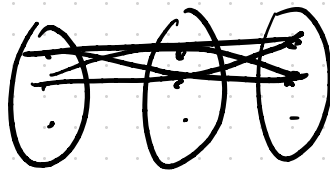
1) $\mathbb{Z}_3^{\text{rel}} \rightsquigarrow x - y + z \in \text{Pol}(\mathbb{Z}_3^{\text{rel}})$

[A^{rel} for every ab group]

2) $A = (\{0, 1, 2\}, (\pi)_{\pi \in S_3}, (R_{01}))$ $R_{01} = \{(xyz) \in \{0, 1\}^3 \mid x + y = z \pmod{2}\}$



$\pi = (2, 3)$



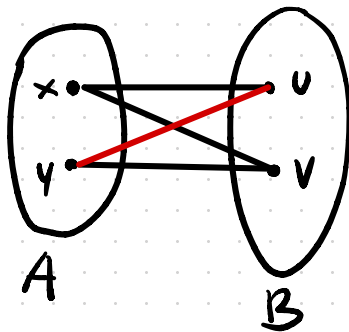
R

$d(xyz) = \begin{cases} x + y & \text{if } |\{xyz\}| = 3 \\ m(xyz) & \text{else} \end{cases}$
 $\in \text{Pol}(A)$

The parallelogram property

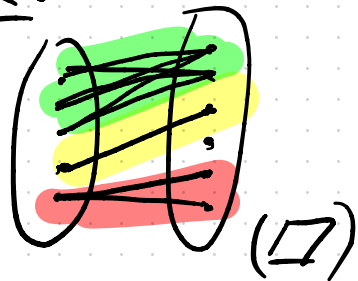
$R \subseteq A \times B$ has the parallelogram property (\square)

iff
$$\begin{cases} (x, u) \in R \\ (x, v) \in R \\ (y, v) \in R \end{cases} \Rightarrow (y, u) \in R$$

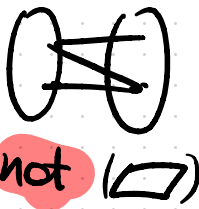


$R \subseteq A_1 \times A_2 \times \dots \times A_n$ has parallelogram property iff $R \subseteq \prod_{i \in I} A_i \times \prod_{j \in I} A_j$ has (\square) $\forall I \subseteq [n]$

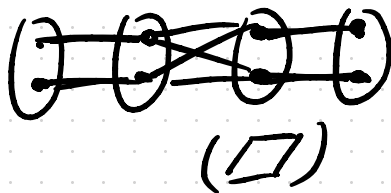
Ex.



$x_1 \leq x_2$



$x_1 + x_2 + x_3 + x_4 = 0$



The parallelogram property

☉ $R \leq A^n$ A Mal'tsev $\Rightarrow R$ has (\square)

$$\begin{pmatrix} x \\ u \end{pmatrix}, \begin{pmatrix} x \\ v \end{pmatrix}, \begin{pmatrix} y \\ v \end{pmatrix} \in R \Rightarrow \begin{pmatrix} d(x \times y) \\ d(u \vee v) \end{pmatrix} = \begin{pmatrix} y \\ u \end{pmatrix} \in R$$

Theorem (Mal'tsev '54)

For finite A : A Mal'tsev $\Leftrightarrow \forall R \leq A^n$ R has (\square)

Proof (\Leftarrow) $\text{Clo}^3(A) = \text{Sg} \left(\begin{matrix} \pi_1^1 \\ x \end{matrix}, \begin{matrix} \pi_1^2 \\ y \end{matrix}, \begin{matrix} \pi_1^3 \\ z \end{matrix} \right) \leq A^{A^3}$

$$R = \text{Sg} \left(\begin{pmatrix} y \\ x \end{pmatrix}, \begin{pmatrix} x \\ x \end{pmatrix}, \begin{pmatrix} x \\ y \end{pmatrix} \right) \leq (A^{A^3})^2 \text{ has } (\square) \Rightarrow \begin{pmatrix} y \\ y \end{pmatrix} \in R$$

$$\Rightarrow \exists d \in (\text{Clo}(A)) : \begin{pmatrix} y \\ y \end{pmatrix} = d \left(\begin{pmatrix} y \\ x \end{pmatrix} \times \begin{pmatrix} x \\ x \end{pmatrix} \times \begin{pmatrix} x \\ y \end{pmatrix} \right) \quad \square$$

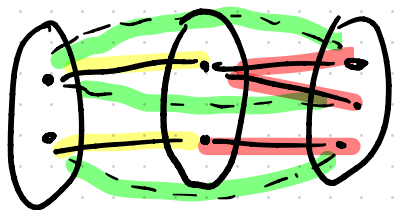
The parallelogram property

Theorem (Mal'tsev '54)

For finite \underline{A} : \underline{A} Mal'tsev $\Leftrightarrow \forall R \leq \underline{A}^n$ R has (\square)

If $\alpha, \beta \in \text{Con}(\underline{A})$

$\gamma = \alpha \circ \beta \leq \underline{A}^2$, reflexive



γ has $(\square) \Rightarrow \gamma \in \text{Con}(\underline{A})$

Ex.: \underline{G} group $N, M \trianglelefteq \underline{G} \Rightarrow NM = MN \trianglelefteq \underline{G}$

Original formulation

$V = \text{HSP}(\underline{A})$ has Mal'tsev term

\Leftrightarrow

$\forall \underline{B} \in V, \forall \alpha, \beta \in \text{Con}(\underline{B})$:

$$\alpha \circ \beta = \beta \circ \alpha = \alpha \vee \beta$$

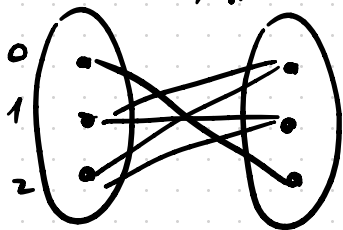
The parallelogram property

Theorem (Mal'tsev '54)

For finite A : \underline{A} Mal'tsev $\Leftrightarrow \forall R \subseteq A^n$ R has (\square)

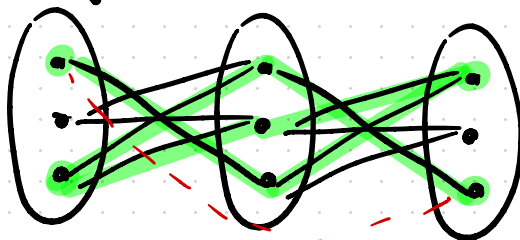
Remark:

$R(x, y)$



has (\square)

$Q(x, y) = \exists z R(x, z) \wedge R(z, y)$



has no (\square)

$(0, 0) \in Q$
 $(2, 0) \in Q$
 $(2, 2) \in Q$

$(1, 2) \in Q$

$(\{0, 1, 2\}, R)$ has no Mal'tsev polymorphism!

Question: How hard is checking if $\text{Po}(A)$ is Mal'tsev?

Outline

- 1) What are **Mal'tsev constraints?** ✓
- 2) What are the 'canonical generating sets'?
compact representations
- 3) **The algorithm**
- 4-) **Beyond CSP**



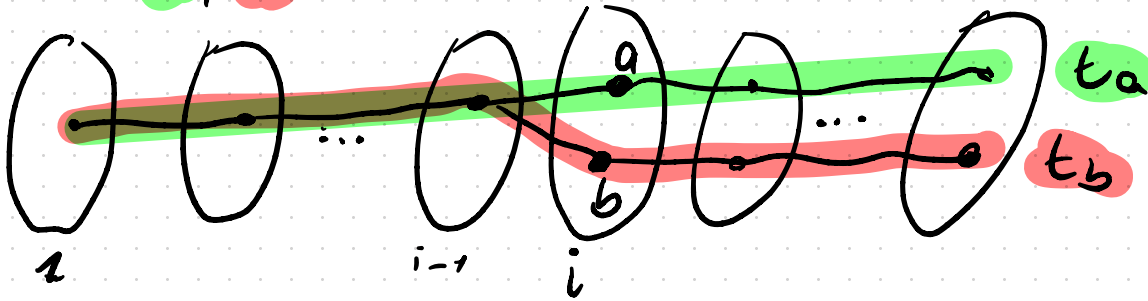
Bulatov, Dalman

2006 A simple algorithm
for Mal'tsev
constraints

Forks and Signatures

$$R \subseteq A^n$$

Def. $(i, a, b) \in [n] \times A^2$ is a fork of R
 $\exists t_a, t_b \in R$:



Signature of R = $\text{Sig}(R) = \{(i, a, b) \mid (i, a, b) \text{ fork of } R\}$

Ex. $\text{Sig}(R^+) = \{1, 2\} \times \mathbb{Z}_3^2 \cup \{3\} \times (=)$ = $\text{Sig}(\{(xyz)\} \mid y = z)$

$x + y = z$

Forks and Signatures

$$\text{Sig}(R) = \{ (i, a, b) \mid (i, a, b) \text{ fork of } R \}$$

Thm. \underline{A} Mal'tsev, $\underline{R} \leq \underline{A}^n$, $C \subseteq \underline{R}$
 s.t. $\text{Sig}(C) = \text{Sig}(\underline{R}) \Rightarrow \text{Sg}_{\underline{A}^n}(C) = \underline{R}$

Proof: Induction on n . $n=1 \Rightarrow C=R \checkmark$

$$n-1 \rightarrow n: \text{ Let } \begin{pmatrix} \bar{a} \\ \bar{b} \end{pmatrix} \in R. \stackrel{IH}{\Rightarrow} \exists \begin{pmatrix} \bar{a} \\ \bar{c} \end{pmatrix} \in \text{Sg}(C) \subseteq R$$

$$\Rightarrow (n, \bar{b}, \bar{c}) \in \text{Sig}(R) = \text{Sig}(C) \Rightarrow \exists \text{ witnesses } \begin{pmatrix} \bar{f} \\ \bar{b} \end{pmatrix}, \begin{pmatrix} \bar{f} \\ \bar{c} \end{pmatrix} \in C$$

$$d \left(\begin{pmatrix} \bar{a} \\ \bar{c} \end{pmatrix}, \begin{pmatrix} \bar{f} \\ \bar{c} \end{pmatrix}, \begin{pmatrix} \bar{f} \\ \bar{b} \end{pmatrix} \right) = \begin{pmatrix} \bar{a} \\ \bar{b} \end{pmatrix} \in \text{Sg}(C)$$

□

Compact Representations

Thm.

$$\underline{A} \text{ Mal'tsev, } \underline{R} \subseteq \underline{A}^n, C \subseteq \underline{R} \Rightarrow \text{Sg}_{\underline{A}^n}(C) = \underline{R} \\ \text{s.t. } \text{Sig}(C) = \text{Sig}(\underline{R})$$

Def. For $\underline{R} \subseteq \underline{A}^n$, $C \subseteq \underline{R}$ is a compact representation (CR)

$$\Leftrightarrow \begin{cases} \text{i) } \text{Sig}(C) = \text{Sig}(\underline{R}) \\ \text{ii) } |C| \leq 2 \cdot \text{Sig}(C) \leq 2n|\underline{A}|^2 \end{cases}$$

by the
prop

$$\text{if } \bar{a} \in \underline{R} \Rightarrow \exists \bar{c}_i, \bar{d}_i \in C$$

$$\bar{a} = d(\dots d(d(\bar{c}_1, \bar{d}_2, \bar{c}_2), \bar{d}_3, \bar{c}_3) \dots \bar{d}_n, \bar{c}_n)$$

2-fork 3-fork n-fork

Compact Representations

⇒ Given CR C of $R \subseteq A^n$

$\bar{a} \in R?$ is decidable in time $O(n^2)$.

1) $\exists \bar{c}_1 \in C : c_1[1] = a[1]?$

[if NO → return NO]

2) for $i = 2, 3, \dots, n$

[$\exists \bar{d}_i, \bar{c}_i \in C$ witnessing the i -fork

$(d_1, d_2, c_2, \dots, d_{i-1}, c_{i-1})[i], a[i]$]

[if NO → return NO]

3) return YES $(\bar{a} = d_1 \dots d(\bar{c}_1, \bar{d}_2, \bar{c}_2), \dots, \bar{d}_n, \bar{c}_n)$

Compact Representations

Example

1) **affine basis** For $R = \begin{pmatrix} 1 \\ 0 \\ 1 \\ 1 \end{pmatrix} + \left\langle \begin{pmatrix} 1 \\ 0 \\ 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \end{pmatrix} \right\rangle \leq \mathbb{Z}_3^4$

$$C = \left\{ \begin{pmatrix} 1 \\ 0 \\ 1 \\ 1 \end{pmatrix} + i \begin{pmatrix} 1 \\ 0 \\ 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 1 \\ 1 \end{pmatrix} + j \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \end{pmatrix} \mid i, j \in \mathbb{Z}_3 \right\} \text{ is a CR of } R.$$

2) For a group \underline{G} , $H \leq \underline{G}^n$

"**strong generating sets**"
of \underline{H}

(\leadsto) compact representation
of $H \leq \underline{G}^n$

(Schreier-Sims ~70ies)

Outline

- 1) What are **Mal'tsev constraints?** ✓
- 2) What are the 'canonical generating sets'?
compact representations ✓
- 3) **The algorithm**
- 4-) **Beyond CSP**



Bulatov, Dalman

2006 A simple algorithm
for Mal'tsev
constraints

The algorithm for Mal'tsev CSPs

$A = (A; R_1, \dots, R_n)$ $d(x, y, z) \in \text{Pol}(A)$ Mal'tsev
 $\underline{A} := (A, d(x, y, z))$

recall: want to solve $\text{CSP}(A)$

$\exists \bar{x}: R_1(\dots) \wedge R_2(\dots) \wedge \dots \wedge R_n(\dots)$

CR —————

by iteratively computing compact representations, solving:

Intersect(\underline{A})

Input: CR's C_1, C_2 of $R_i = S_{\mathcal{G}}(C_i) \subseteq \underline{A}^n$

Output: CR of $R_1 \wedge R_2$
(or \emptyset if $R_1 \wedge R_2 = \emptyset$)

The algorithm for Mal'tsev CSPs [Zeb's CSP notes]

Algorithm 4 $\text{Nonempty}(R, i_1, \dots, i_k, \mathbb{S})$, p a Mal'tsev term, R a compact representation of $\mathbb{R} \leq A_1 \times \dots \times A_n$, $\mathbb{S} \leq A_{i_1} \times \dots \times A_{i_k}$.

- 1: Set $R' \leftarrow R$.
- 2: **while** $\pi_{i_1, \dots, i_k}(R')$ is not closed under p and $R' \cap \mathbb{S} = \emptyset$ **do**
- 3: Pick $t_1, t_2, t_3 \in R'$ with $\pi_{i_1, \dots, i_k}(p(t_1, t_2, t_3)) \notin \pi_{i_1, \dots, i_k}(R')$.
- 4: Set $R' \leftarrow R' \cup \{p(t_1, t_2, t_3)\}$.
- 5: **if** $R' \cap \mathbb{S} \neq \emptyset$ **then**
- 6: **return** any element of $R' \cap \mathbb{S}$.
- 7: **else**
- 8: **return** \emptyset .

exhaustively compute
 $R' = \pi_{i_1, \dots, i_k}(\mathbb{R})$

return $\bar{a} \in R \cap \mathbb{S}$ or \emptyset

$\text{poly}(|\mathbb{R}|, |\mathbb{A}|^k)$

The algorithm for Mal'tsev CSPs [Zeb's CSP notes]

Algorithm 4 Nonempty(R, i_1, \dots, i_k, S), p a Mal'cev term, R a compact representation of $\mathbb{R} \leq \mathbb{A}_1 \times \dots \times \mathbb{A}_n$, $S \leq \mathbb{A}_{i_1} \times \dots \times \mathbb{A}_{i_k}$.

$\text{poly}(|R|, |A|^k)$
 $\rightsquigarrow \bar{a} \in R \cap S$ or \emptyset

Algorithm 5 Fix-values(R, a_1, \dots, a_m), p a Mal'cev term, R a compact representation of $\mathbb{R} \leq \mathbb{A}_1 \times \dots \times \mathbb{A}_n$.

- 1: Set $R_0 \leftarrow R$.
- 2: for j from 1 to m do
- 3: if $(j, a_j, a_j) \notin \text{Sig}(R_{j-1})$ then
- 4: return \emptyset .
- 5: else
- 6: Set $R_j \leftarrow \{t\}$, where $t \in R_{j-1}$ and the pair t, t witnesses the triple (j, a_j, a_j) .
- 7: for all $(i, a, b) \in \text{Sig}(R_{j-1})$ with $i > j$ do
- 8: Let $t_a, t_b \in R_{j-1}$ witness the triple (i, a, b) .
- 9: Let $t \leftarrow \text{Nonempty}(R_{j-1}, j, i, \{(a_j, a)\})$.
- 10: if $t \neq \emptyset$ then
- 11: Set $R_j \leftarrow R_j \cup \{t, p(t, t_a, t_b)\}$.
- 12: return R_m .

$R_j \dots$ CR of $R_1(x_1=a_1) \dots R_j(x_j=a_j)$

$t, p(t, t_a, t_b)$ witnesses
 $t[i] = a \quad p(t, t_a, t_b)[i] = p(aab) = b$

The algorithm for Mal'tsev CSPs [Zeb's CSP notes]

Algorithm 4 $\text{Nonempty}(R, i_1, \dots, i_k, S)$, p a Mal'tsev term, R a compact representation of $\mathbb{R} \leq A_1 \times \dots \times A_n$, $S \leq A_{i_1} \times \dots \times A_{i_k}$.

$\text{poly}(|R|, |A|^{i_k})$
 $\rightsquigarrow \bar{a} \in R \cap S$ or \emptyset

Algorithm 5 $\text{Fix-values}(R, a_1, \dots, a_m)$, p a Mal'tsev term, R a compact representation of $\mathbb{R} \leq A_1 \times \dots \times A_n$.

$\text{poly}(|R|, m)$
 $\rightsquigarrow \text{CR of } R \wedge x_i = a_i \dots$ or \emptyset

Algorithm 6 $\text{Next-beta}(R, i_1, \dots, i_k, S)$, R a compact representation of $\mathbb{R} \leq A_1 \times \dots \times A_n$, $S \leq A_{i_1} \times \dots \times A_{i_k}$.

$\text{poly}(|R|, |A|^{i_k})$
 $\rightsquigarrow \text{CR of } R \cap S$ or \emptyset

1: Set $R' \leftarrow \emptyset$.

2: for all $(i, a, b) \in \text{Sig}(R)$ do

3: Set $t_a \leftarrow \text{Nonempty}(R, i_1, \dots, i_k, i, S \times \{a\})$.

4: if $t_a \neq \emptyset$ then

5: Set $t_b \leftarrow \text{Nonempty}(\text{Fix-values}(R, \pi_1(t_a), \dots, \pi_{i-1}(t_a)), i_1, \dots, i_k, i, S \times \{b\})$.

6: if $t_b \neq \emptyset$ then

7: Set $R' \leftarrow R' \cup \{t_a, t_b\}$.

8: return R' .

witnesses for parts of $R \cap S$

The algorithm for Mal'tsev CSPs [Zeb's CSP notes]

Algorithm 4 Nonempty(R, i_1, \dots, i_k, S), p a Mal'tsev term, R a compact representation of $\mathbb{R} \leq A_1 \times \dots \times A_n$, $S \leq A_{i_1} \times \dots \times A_{i_k}$.

$\text{poly}(|R|, |A|^{i_k})$
 $\leadsto \bar{a} \in R \cap S$ or \emptyset

Algorithm 5 Fix-values(R, a_1, \dots, a_m), p a Mal'tsev term, R a compact representation of $\mathbb{R} \leq A_1 \times \dots \times A_n$.

$\text{poly}(|R|, m)$
 $\leadsto \text{CR of } R \wedge x_i = a_i \dots$ or \emptyset

Algorithm 6 Next-beta(R, i_1, \dots, i_k, S), R a compact representation of $\mathbb{R} \leq A_1 \times \dots \times A_n$, $S \leq A_{i_1} \times \dots \times A_{i_k}$.

$\text{poly}(|R|, |A|^{i_k})$
 $\leadsto \text{CR of } R \cap S$ or \emptyset

Algorithm 7 Intersect(R, i_1, \dots, i_k, S), R a compact representation of $\mathbb{R} \leq A_1 \times \dots \times A_n$, S a compact representation of $\mathbb{S} \leq A_{i_1} \times \dots \times A_{i_k}$.

1: Let $t_R \in R$ and $t_S \in S$ be any tuples.

2: Set $R' \leftarrow (R \times \{t_S\}) \cup (\{t_R\} \times S) \subseteq A_1 \times \dots \times A_n \times A_{i_1} \times \dots \times A_{i_k}$.

CR of $R \times S$

3: for $j \leq k$ do

4: Set $R' \leftarrow \text{Next-beta}(R', i_j, n+j, A_{i_j})$.

5: return a minimal subset of $\pi_{1, \dots, n}(R')$ which witnesses every triple $(i, a, b) \in \text{Sig}(\pi_{1, \dots, n}(R'))$.

The algorithm for Mal'tsev CSPs [Zeb's CSP notes]

Algorithm 4 Nonempty(R, i_1, \dots, i_k, S), p a Mal'cev term, R a compact representation of $\mathbb{R} \leq A_1 \times \dots \times A_n$, $S \leq A_{i_1} \times \dots \times A_{i_k}$.

$\text{poly}(|R|, |A|^{i_k})$
 $\rightsquigarrow \bar{a} \in R \cap S$ or \emptyset

Algorithm 5 Fix-values(R, a_1, \dots, a_m), p a Mal'cev term, R a compact representation of $\mathbb{R} \leq A_1 \times \dots \times A_n$.

$\text{poly}(|R|, m)$
 $\rightsquigarrow \text{CR of } R \wedge x_i = a_i \dots$ or \emptyset

Algorithm 6 Next-beta(R, i_1, \dots, i_k, S), R a compact representation of $\mathbb{R} \leq A_1 \times \dots \times A_n$, $S \leq A_{i_1} \times \dots \times A_{i_k}$.

$\text{poly}(|R|, |A|^{i_k})$
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Algorithm 7 Intersect(R, i_1, \dots, i_k, S), R a compact representation of $\mathbb{R} \leq A_1 \times \dots \times A_n$, S a compact representation of $\mathbb{S} \leq A_{i_1} \times \dots \times A_{i_k}$.

- 1: Let $t_R \in R$ and $t_S \in S$ be any tuples.
- 2: Set $R' \leftarrow (R \times \{t_S\}) \cup (\{t_R\} \times S) \subseteq A_1 \times \dots \times A_n \times A_{i_1} \times \dots \times A_{i_k}$. **CR of $R \times S$**
- 3: for $j \leq k$ do
- 4: Set $R' \leftarrow \text{Next-beta}(R', i_j, n+j, =A_{i_j})$.
- 5: return a minimal subset of $\pi_{1, \dots, n}(R')$ which witnesses every triple $(i, a, b) \in \text{Sig}(\pi_{1, \dots, n}(R'))$.

$\text{poly}(|R|, |S|)$
 $\rightsquigarrow \text{CR of } R \cap S$ or \emptyset .

$\Rightarrow \boxed{\text{CSP}(A) \in P}$ for $\text{Pol}(A)$ Mal'tsev

Outline

- 1) What are **Mal'tsev constraints**? ✓
- 2) What are the 'canonical generating sets'?
compact representations ✓
- 3) **The algorithm** ✓*
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Bulatov, Dalman

2006 A simple algorithm
for Mal'tsev
constraints

Is the algorithm necessary? (in the light of CLAP)

Yes!

→ Monday

(next... my slide before Mo...)

Is the algorithm necessary? (in the light of CLAP)

\mathbb{A} Mal + sev

$$d(yxy) = d(yxx) = d(xxy) = y$$

→ CSP(\mathbb{A}) has bounded width \Leftrightarrow Pol(\mathbb{A}) has majority

→ If $x - y + z \in \text{Pol}(\mathbb{A}) \rightarrow$ alt. terms $x_1 - x_2 + x_3 - x_4 \dots + x_n \in \text{Pol}(\mathbb{A})$
 \Rightarrow CSP(\mathbb{A}) solvable by AIP

→ $\mathbb{A} = (\{0, 1, 2\}, (\pi)_{\pi \in S_3}, R_{01}) \xrightarrow{AT}$ CSP(\mathbb{A}) solved by AIP.

→ Pol(\mathbb{A}) conservative \Rightarrow Andrew's talk! $\exists L - \varepsilon$

[BGWŽ'20]

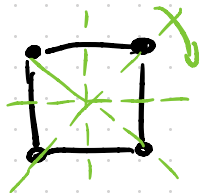
PCSP(\mathbb{A}, \mathbb{B}) is solvable by BLP + AIP

\Leftrightarrow Pol(\mathbb{A}, \mathbb{B}) has block symmetric t

$$t(\overleftarrow{x_1 \dots x_e}, \overrightarrow{x_{e+1} \dots x_{2e+1}}) \quad \forall e \geq 1$$

An example not solved by BLP+AIP

(D_8, \cdot) dihedral group ...



$t \in \text{Clo}(D_8, \cdot)$

has normal form

$$t(x_1, \dots, x_n) = x_1^{\alpha_1} \cdot x_2^{\alpha_2} \cdots x_n^{\alpha_n} [x_1, x_2]^{\beta_{12}} [x_1, x_3]^{\beta_{13}} \cdots [x_{n-1}, x_n]^{\beta_{n-1,n}}$$

$$[x, y] = x^{-1} y^{-1} x y$$

$$\alpha_i \in [4]$$

$$\beta_{ij} \in [2]$$

Claim: \exists idempotent block symmetric $t \in \text{Clo}(D_8, \cdot)$

Pf.

Assume $t(x_1, \dots, x_n) = x_1^{\alpha_1} x_2^{\alpha_2} \cdots x_n^{\alpha_n} [x_1, x_2]^{\beta_{12}} [x_1, x_3]^{\beta_{13}} \cdots [x_{n-1}, x_n]^{\beta_{n-1,n}}$ is block symmetric $t(\overleftarrow{x_1, \dots, x_{n/2}} \overrightarrow{x_{n/2+1}, \dots, x_n})$, idempotent

(i) $x = t(x, x, \dots, x) = x^{\sum \alpha_i} \Rightarrow \exists \alpha_i = \pm 1$ (wlog $i=1$)

(ii) $t(x, 1, \dots, 1) = t(1, x, \dots, 1) \Rightarrow \alpha_1 = \alpha_2 = \alpha$

(iii) $t(xy, 1, \dots, 1) = x^\alpha y^\alpha [x, y]^{\beta_{12}}$
 $t(yx, 1, \dots, 1) = y^\alpha x^\alpha [y, x]^{\beta_{12}}$
 $\Rightarrow x \cdot y = y \cdot x$ in D_8 \downarrow

An example not solved by BLP+AIP

Thm.

[AMM'14] For every finite Mal'tsev \underline{A} ,
 $\exists \mathbb{A} = (A, R_1, \dots, R_n) : \text{Pol}(\mathbb{A}) = \text{Clo}(\underline{A})$

$\Rightarrow \exists \mathbb{D} = (D, R_1, \dots, R_n) : \text{Pol}(\mathbb{D}) = \text{Clo}(D, x y^{-1} z)$

$\text{CSP}(\mathbb{D})$ solved by Mal'tsev, **not AIP+BLP**.

Moreover $\text{Clo}(D, x y^{-1} z)$ is minimal Taylor.

\rightarrow Is $\text{CSP}(\mathbb{D})$ solved by **CLAP**?

[AMM'14] uses compactness.

\rightsquigarrow How can we **construct** \mathbb{A} from \underline{A} ?

Mal'tsev terms,
relational bases

& socialism

6th CWC
27.09.24 - Calfasch

Michael Kompatscher
Charles University

... Yesterday

Thm.

[AMM'14] For every finite Mol'tsev \underline{A} ,
 $\exists A = (A, R_1, \dots, R_n) \quad \text{Pol}(A) = \text{Clo}(\underline{A})$

$R \leq S \leq \underline{A}^n$
 $\text{Sig}(R) \subsetneq \text{Sig}(S)$

(non - constr. proof)

- $\rightarrow \forall n: \text{Clo}(\underline{A})^n \leq A^{A^n}$ has forks $(\bar{a}, f(\bar{a}), g(\bar{a}))$
- $\rightarrow \lambda(c, d) := \{ \bar{a} \in A^{<\omega} \mid (\bar{a}, c, d) \text{ not fork} \}$ $\xrightarrow{\text{compactness}} \exists$ fin. many "minimal" \bar{a} in $\lambda(c, d)$
- \rightarrow take $m := \max |\bar{a}| \Rightarrow \text{Clo}(\underline{A}) = \text{Pol}(\text{Clo}(\underline{A})^m)$

Question today: How can we construct $A = (A, \underline{R_1, \dots, R_n})$?

\hookrightarrow In general unknown, e.g. for $(G, \times y^{-1} z)$

relational
basis

Motivation 1

Thm.

[AMM'14] For every finite Mal'tsev \underline{A} ,
 $\exists A = (A, R) \quad \text{Pol}(A) = \text{Clo}(\underline{A})$

Cor.: For fixed \underline{A} Mal'tsev

$\text{Term}(\underline{A})$

Input: $f: A^n \rightarrow A$

Question: Is $f \in \text{Clo}(\underline{A})$?

is in P
check if f preserves R

Remark

$\exists A: \text{Term}(\underline{A}) \in \text{EXPTIME-c. [Kozik '08]}$

$f_{\text{in.}}$
not Mal'tsev

cannot describe
algorithm, unless
we know R

Motivation 2

Thm.

[AMM'14] For every finite Mal'tsev \underline{A} ,
 $\exists A = (A, R) \quad \text{Pol}(A) = \text{Clo}(\underline{A})$

Corollary:

On fixed $A \quad \exists \leq$ countable Mal'tsev clones

can we classify them?

\Leftrightarrow Can we classify Mal'tsev CSP templates
up to pp-definability?

Motivation 2

Thm [Bulatov '05] $\text{Clo}(\underline{A}) = \text{Pol}(\text{Inv}^{(4)}(\underline{A}))$

On $|A| = 3$, there are 1129 Mal'tsev clones.

But on $|A| = 4$

Why?

$$\underline{A}_k = (\mathbb{Z}_4, +, 0, -, \cdot, x_1 x_2 \dots x_k)$$

$$\text{Clo}(\underline{A}_n) = \{ \sum \alpha_i x_i + 2 \cdot p(x_1 \dots x_n) \mid \deg(p) \leq k \}$$

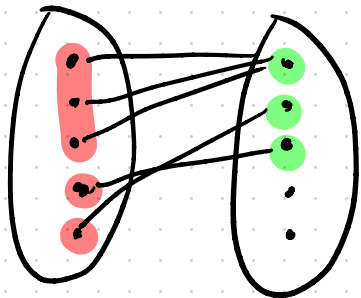
$$\text{Clo}(\underline{A}_1) \subsetneq \text{Clo}(\underline{A}_2) \subsetneq \text{Clo}(\underline{A}_3) \subsetneq \dots$$

Basic questions are still open, e.g.:

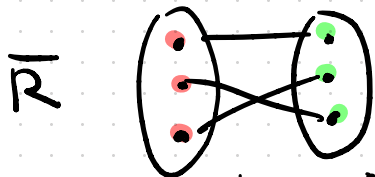
\exists infinite autichain on some A ?

An observation

\underline{A} Mal'tsev, $R \subseteq \underline{A}^2$



$(x, y) \mapsto (x/\alpha_1, y/\alpha_2)$
maps to



$\underline{A}_1 = \text{pr}_1 R / \alpha_1$ $\underline{A}_2 = \text{pr}_2 R / \alpha_2$

Link-congruences $\alpha_i \in \text{Con}(\text{pr}_i R)$

$$x \alpha_1 y \Leftrightarrow \exists z R(xz) \wedge R(yz)$$

$$x \alpha_2 y \Leftrightarrow \exists z R(zx) \wedge R(zy)$$

So binary relations $R \subseteq \underline{A}^2 \Leftrightarrow$

isomorphisms $\bar{R} \subseteq \underline{A}_1 \times \underline{A}_2$ $\underline{A}_i \in \text{HS}(\underline{A})$

Similarly

$R \subseteq \underline{A}^n \Leftrightarrow$ reduced representation

$\bar{R} \subseteq_{\text{sd}} \underline{A}_1 \times \dots \times \underline{A}_n$ $\underline{A}_i \in \text{HS}(\underline{A})$

Outline

- 1) Relational basis ✓
- 2) Commutator theory
- 3) Critical relations
- 4) 3-element Mal'tsev algebras

COMMUTATOR

CRITICAL RELATIONS
THEORY

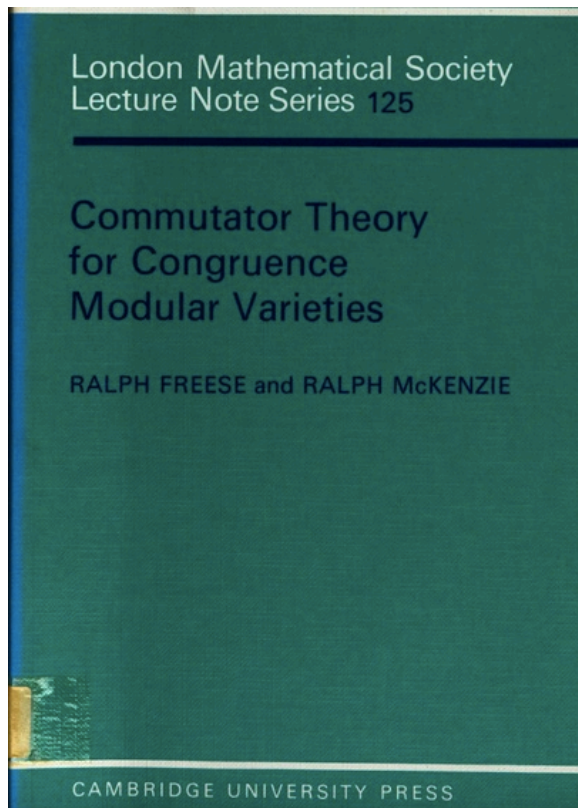
SELECTED ESSAYS

~~MAX HORKHEIMER~~

Freese, McKenzie,
Kearnes, Szendrei,
Atchinger, Mayr,
...



Commutator Theory



Generalizes concepts as

Abelian
nilpotent
solvable

Commutator
centralizer
...

groups / NS
↓ ↓
algebras / congruences.

Abelianness

A ... algebra with Mal'tsev term $d(xyz)$

Def. A is Abelian : \Leftrightarrow

$$d = \left\{ \begin{array}{c|c} x & -d(xyz) \\ \hline y & -z \end{array} \mid x, y, z \in A \right\} \subseteq \underline{A}^4$$

Ex. $\underline{G} = (G, \cdot, 1, ^{-1})$ group, $d(xyz) = xy^{-1}z$

G Abelian

$d \subseteq G^4$

$$\begin{array}{c} 1 \\ | \\ 1 \end{array} \begin{array}{c} a \\ | \\ a \end{array}, \begin{array}{c} b \\ | \\ 1 \end{array} \begin{array}{c} b \\ | \\ 1 \end{array} \in d \Rightarrow \begin{array}{c} b \\ | \\ 1 \end{array} \begin{array}{c} -ab \\ | \\ -a \end{array} \in d \Rightarrow ab = b \cdot 1^{-1} \cdot a = ba \rightarrow \underline{G} \text{ abelian}$$

Thm [S. 70ies] A Abelian $\Leftrightarrow \text{Cl}(A, (a)_{a \in A}) = \left\{ \bar{x} \mapsto \sum_{i=1}^n r_i \cdot x_i + c \right\}$ w.r. to a module

Centralizers

Def. $\alpha \in \text{Con}(\underline{G})$ Abelian \Leftrightarrow

$$d\Gamma_{\alpha} := \left\{ \begin{array}{c|c} x & -d(x,y,z) \\ \hline y & z \end{array} \mid x \alpha y \alpha z \right\} \leq \underline{A}^4 \quad \begin{array}{l} d(x,y,z) \\ x = d(\begin{smallmatrix} x & y \\ y & y \end{smallmatrix}) \end{array}$$

α centralizes $\beta \Leftrightarrow$

$$d\Gamma_{\alpha, \beta} := \left\{ \begin{array}{c|c} x & -d(x,y,z) \\ \hline y & z \end{array} \mid x \alpha y \beta z \right\} \leq \underline{A}^4$$

centralizer ($\alpha = \alpha$) \Leftrightarrow biggest $\beta : d\Gamma_{\alpha, \beta} \leq \underline{A}^4$

Ex. In groups \underline{G} $\alpha \in \text{Con}(\underline{G}) \Leftrightarrow N \trianglelefteq \underline{G} \quad x \alpha y \Leftrightarrow xy^{-1} \in N$

α centralizes $\beta \Leftrightarrow$ for $N = [1]_{\alpha} \quad \forall n \in N, m \in M:$
 $M = [1]_{\beta} \quad n \cdot m = m \cdot n$

Central congruences

unlike in groups for A Maltsev, $\alpha \in \text{Con}(A)$

$|[a]_\alpha| \neq |[b]_\alpha|$ possible.

But if α centralizes $1_A = A \times A$ (α is central)

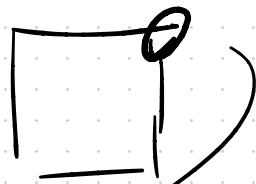
$$\left\{ \begin{array}{c} x \\ | \\ y \end{array} \begin{array}{c} - \\ | \\ - \end{array} \begin{array}{c} d(x,yz) \\ | \\ z \end{array} \right\} = d|_{\alpha, 1} = \text{Sq}_{A^4} \left\{ \begin{array}{c} x \\ | \\ x \end{array} \begin{array}{c} - \\ | \\ - \end{array} \begin{array}{c} y \\ | \\ y \end{array} \right\}, \left\{ \begin{array}{c} u \\ | \\ v \end{array} \begin{array}{c} - \\ | \\ - \end{array} \begin{array}{c} u \\ | \\ v \end{array} \right\} = \left\{ \begin{array}{c} x \\ | \\ d(x,yz) \end{array} \begin{array}{c} - \\ | \\ - \end{array} \begin{array}{c} y \\ | \\ z \end{array} \right\} \leq A^4$$

\Rightarrow For fixed a, b $x \mapsto d(x, a, b)$ is bijection
from $[a]_\alpha \rightarrow [b]_\alpha$

$\Rightarrow |[a]_\alpha| = |[b]_\alpha|$ for α central.

Commutator

$$\triangle_{\alpha\beta} = \text{Sg}_{\underline{A}}(d_{\alpha\beta})$$



$[\alpha, \beta] :=$ linkedness-congruence

$\Leftrightarrow [\alpha, \beta]$ is smallest $\mu \in \text{Con}(\underline{A})$:

in \underline{A}/μ α/μ centralizes β/μ

Outline

- 1) Relational basis ✓
- 2) Commutator theory ✓
- 3) Critical relations
- 4) 3-element Mal'tsev algebras

COMMUTATOR

CRITICAL RELATIONS
THEORY

SELECTED ESSAYS

~~MAX HORKHEIMER~~

Freese, McKenzie,
Kearnes, Szendrei,
Aichinger, Mayr,
...



Critical relations

Def. For algebra \underline{A} ,

$R \leq \underline{A}^n$ is critical \Leftrightarrow

-) no dummy variables
-) $\exists R < R_1, R_2 \leq \underline{A}^n$
with $R = R_1 \wedge R_2$

Ex.

·) $\underline{A} = (\{0, 1\}, \wedge, \vee)$ \leq $\{0\}, \{1\}$ critical

·) $\underline{A} = (\mathbb{Z}_3, x - y + z)$

$R(x_1, \dots, x_n)$ is critical $\Leftrightarrow R = \{ \bar{x} \mid \sum \alpha_i x_i = c \}$ for $\alpha_i \neq 0$

Γ pp-defines $\text{Inv}(\underline{A}) \Leftrightarrow \Gamma$ pp-def. all critical relations

Outline

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CRITICAL RELATIONS
THEORY

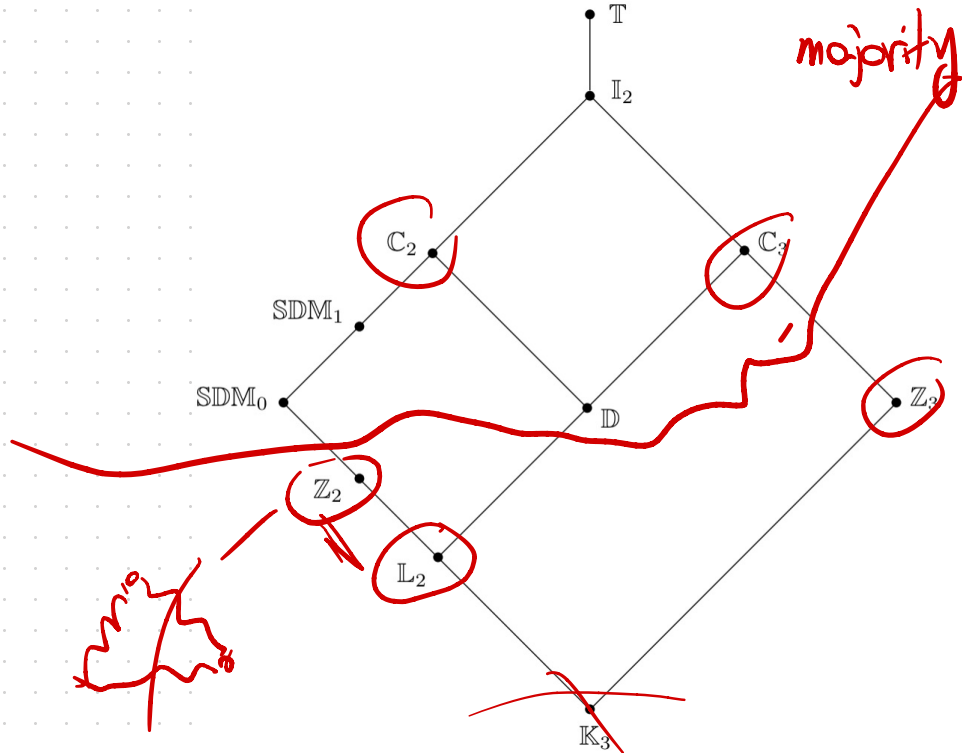
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...



3-element Mal'tsev up to minion homom.



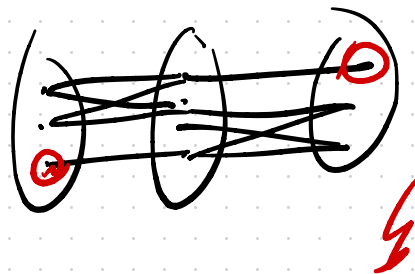
A Mal'tsev $A = \{0, 1, 2\}$

$R \subseteq \underline{A}^2 \Leftrightarrow$ isomorphism: $HS(\underline{A})$

Lemma $Con \underline{A}$

$$\begin{array}{ccc}
 1_4 & & 1_4 \\
 | & & | \\
 0_4 & & \mu \\
 & & | \\
 & & 0_4
 \end{array}$$

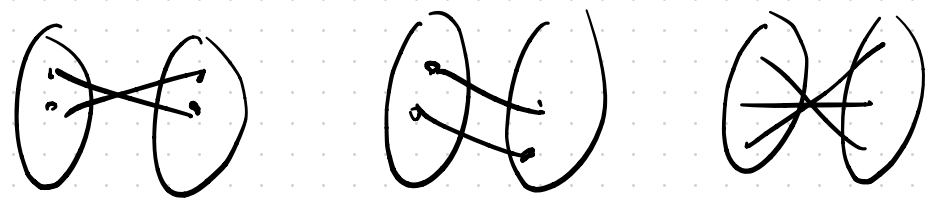
Proof Assume
 $0112, 0112 \in Con \underline{A}$
 $\alpha \quad \beta$



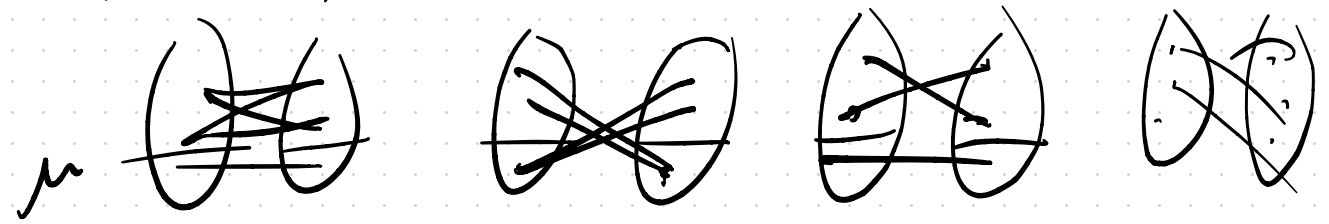
$(2,0) \notin$
 $\alpha \circ \beta$
 $(0,2) \in$

If A simple

$\rightarrow R$ is a partial isomorphism



If $\exists \mu \neq 0_A, 1_A$



$$|A|^{(|A|+1)/(|B(|A|+1)-1)}$$

$\mu = 0, 1, 2 \in \text{con } A$

μ is not central

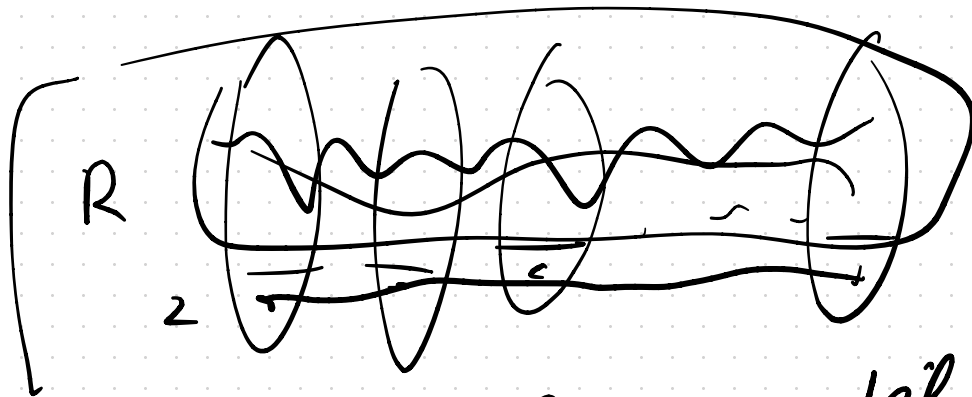
if μ is Abelian

Def if $\forall B \in HS(\underline{A})$

μ_B Abelian nondlth of \underline{B}

$\Rightarrow (0: \mu_B)$ is Abelian

$\Rightarrow \mu = (0: \mu) \Rightarrow \underline{A}$ satisfies (C1)



$$\{ \sum \alpha_i x_i = c \quad (2) \}$$

R is pp-def by df_{μ} and binary

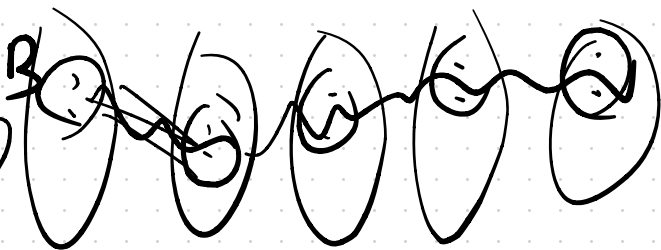
1) No algebra in $\text{HS}(\underline{A})$ has Ab. monolith
 \Rightarrow all crit. rel. have arity ≤ 2
 $\Leftrightarrow \underline{A}$ has majority


2) $R \leq \underline{A}^n$ $R = \bar{R} \leq \underline{A}_1 \times \dots \times \underline{A}_n$

assume \underline{A}_i are not Abelian $\Rightarrow |A_i| = 3$
 μ_i Abelian $\mu_i = (0; \mu_i)$

3) $\exists \underline{A}_i$ Abelian $\Rightarrow \forall \underline{A}_i$ Abelian

$$|A_i| = 3 \rightarrow \underline{A} = \mathbb{Z}_3$$

$|A_i| = 2$
if all $\underline{A}_i \in S(A)$  -- pp-definable
by $d \upharpoonright_B$

$\underline{A}_i \in H(A)$  -- pp-definable by
 $d \upharpoonright_M$

$[a, \beta]$ - linkness $Sp \left(\begin{array}{cc|cc} x & \beta & x & u \\ a & & a & v \\ \hline y & \beta & y & p \\ u & & p & v \end{array} \right)$

$[1, 1, 1] = Q_i$ linkness in 1 coordinate $Sg \left(\begin{array}{c} \text{Diagram 1} \quad \text{Diagram 2} \quad \text{Diagram 3} \end{array} \right) = \Delta_{111}$

$(2y, +, 0, -, 2xy)$ - Δ_{111} is critical
 (Q_8) ?