## Weak dependence in stochastic programming

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Michal Houda Weak dependence in stochastic programming

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## I. Coefficients of weak dependence and convergence of integrated empirical process

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- $(\Omega, \mathcal{A}, \mathbb{P})$  ... probability space
- $(X, \mathbb{B})$  ... measurable space (value space)
- $\{\xi_t\}_{-\infty}^{+\infty}$  ... X-valued stochastic process with discrete or continuous time
- $\mathcal{B}^b_a \dots \sigma$ -algebra generated by events

$$\{\xi_{t_1}\in A_{t_1},\ldots,\xi_{t_n}\in A_{t_n}\}$$

where  $(a \leq) t_1 \leq \cdots \leq t_n \ (\leq b), n$  are arbitrary,  $A_{t_1}, \ldots, A_{t_n}$  are  $\mathcal{B}$ -measurable sets

•  $\mathcal{B}_1, \mathcal{B}_2 \dots$  two arbitrary  $\sigma$ -algebras of subsets of  $\Omega$ 

#### Definition

The process  $\{\xi_t\}$  is *m*-dependent if  $\mathcal{B}^a_{-\infty}$  and  $\mathcal{B}^{+\infty}_b$  are independent when b-a>m

Example: moving average process MA(m) is (m + 1)-dependent (but not *m*-dependent)

## Strong mixing ( $\alpha$ -mixing) coefficient

$$\alpha(\mathcal{B}_1, \mathcal{B}_2) = \sup_{\substack{A \in \mathcal{B}_1, B \in \mathcal{B}_2\\s}} |\mathbb{P}(A \cap B) - \mathbb{P}(A)\mathbb{P}(B)|$$
$$\alpha(t) = \sup_{s} \alpha(\mathcal{B}_{-\infty}^s, \mathcal{B}_{s+t}^{+\infty})$$

#### Definition

The process  $\{\xi_t\}$  is  $\alpha$ -mixing if  $\alpha(t) \to 0$  as  $t \to +\infty$ 

- $\alpha$ -coefficient measures direct covariance dependence
- range:  $\alpha(\mathcal{B}_1, \mathcal{B}_2) \leq 1/4$

Example: autoregressive process AR(m) with normal increments is strong mixing (but not with binomial increments)

## Absolute regularity ( $\beta$ -mixing) coefficient

$$eta(\mathcal{B}_1,\mathcal{B}_2) = \mathbb{E} \operatorname*{esssup}_{B\in\mathcal{B}_2} |\mathbb{P}(B|\mathcal{B}_1) - \mathbb{P}(B)|$$
  
 $eta(t) = \sup_s eta(\mathcal{B}_{-\infty}^s,\mathcal{B}_{s+t}^{+\infty})$ 

## Definition

The process  $\{\xi_t\}$  is  $\beta$ -mixing if  $\beta(t) \to 0$  as  $t \to +\infty$ 

• 
$$\beta(\mathcal{B}_1, \mathcal{B}_2) = \sup_{\{A_i\}, \{B_i\}} \frac{1}{2} \sum_{i=1}^{I} \sum_{j=1}^{J} |\mathbb{P}(A_i \cap B_j) - \mathbb{P}(A_i)\mathbb{P}(B_j)|$$
  
 $\{A_i\} \subset \mathcal{B}_1, \{B_i\} \subset \mathcal{B}_2$  are partitions of  $\Omega$ 

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\*-mixing ( $\varphi$ -mixing) coefficient

$$\varphi(\mathcal{B}_1, \mathcal{B}_2) = \sup_{\substack{A \in \mathcal{B}_1, B \in \mathcal{B}_2 \\ s}} \left| \frac{\mathbb{P}(A \cap B) - \mathbb{P}(A)\mathbb{P}(B)}{\mathbb{P}(A)\mathbb{P}(B)} \right|$$
$$\varphi(t) = \sup_{s} \varphi(\mathcal{B}^s_{-\infty}, \mathcal{B}^{+\infty}_{s+t})$$

## Definition

The process  $\{\xi_t\}$  is  $\varphi$ -mixing if  $\varphi(t) \to 0$  as  $t \to +\infty$ 

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Uniform mixing ( $\phi$ -mixing) coefficient

$$\phi(\mathcal{B}_1, \mathcal{B}_2) = \sup_{\substack{A \in \mathcal{B}_1, B \in \mathcal{B}_2}} \left| \frac{\mathbb{P}(A \cap B) - \mathbb{P}(A)\mathbb{P}(B)}{\mathbb{P}(A)} \right|$$
$$\phi(t) = \sup_{s} \phi(\mathcal{B}_{-\infty}^s, \mathcal{B}_{s+t}^{+\infty})$$

## Definition

The process  $\{\xi_t\}$  is  $\phi$ -mixing if  $\phi(t) \to 0$  as  $t \to +\infty$ 

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## Complete regularity ( $\rho$ -mixing) coefficient

$$egin{aligned} & eta(\mathcal{B}_1,\mathcal{B}_2) = \sup_{\eta_1,\eta_2} \Big| rac{\mathbb{E}\eta_1\eta_2 - \mathbb{E}\eta_1\mathbb{E}\eta_2}{\sqrt{ ext{var}\,\eta_1\, ext{var}\,\eta_2}} \Big| \ & \phi(t) = \sup_{a} 
ho(\{\xi_s,s\leq a\},\{\xi_s,s\geq a+t\}) \end{aligned}$$

 $\eta_1, \eta_2$  are  $\mathcal{B}_1$ -,  $\mathcal{B}_2$ -measurable random variables

### Definition

The process  $\{\xi_t\}$  is  $\phi$ -mixing if  $\phi(t) \to 0$  as  $t \to +\infty$ 

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## Relationships among mixing conditions

General relationships:

$$\begin{array}{cccc} \varphi & \Rightarrow & \phi & \Rightarrow & \beta \\ \varphi & \Rightarrow & \phi & \Rightarrow & \alpha \\ \rho & & & \end{array}$$

Strictly stationnary Gaussian sequences:

$$\begin{array}{ccc} \begin{array}{ccc} \textbf{m-dep.} & & \rho \\ \uparrow & & \rho \\ \varphi & \Rightarrow & \beta & \Rightarrow & \uparrow \\ \uparrow & & & \alpha \\ \phi & & & \end{array}$$

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## Relationships among mixing conditions

Various limiting theorems remain valid with weakly dependent sequences. Example of CLT:

Theorem (MORI, YOSHIHARA (1986))

Let

•  $\{\xi_i\}$  ... strong mixing sequence with  $\alpha(n)$ 

• 
$$\mathbb{E}\xi_1 = 0$$
,  $\mathbb{E}\xi_1^2 < +\infty$ 

• 
$$S_0 = 0, \ S_n = \sum_{j=1}^n \xi_j$$

• 
$$s_n^2 = ES_n^2$$

Then

$$\frac{S_n}{s_n} \longrightarrow^d N(0;1)$$

iif  $\left\{\left(\frac{S_n}{s_n}\right)^2\right\}_{n=1}^{+\infty}$  is uniformly integrable, i.e.,

$$\lim_{a\to+\infty}\sup_{n\geq 1}\int_{|\frac{S_n}{s_n}|>a}\frac{S_n^2}{s_n^2}\mathrm{d}\mathbb{P}=0$$

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## Wasserstein distance

Convergence of integrated empirical process

$$\sqrt{N} W(\mu_N, \mu) = \int_{-\infty}^{+\infty} \sqrt{N} |F_N(t) - F(t)| \,\mathrm{d}t \tag{1}$$

•  $F_N(t) = rac{1}{N} \sum_{i=1}^N I_{(-\infty;t]}(\xi_i), \quad t \in \mathbb{R} \dots$  empirical distribution function

- $\mu_N$  ... corresponding probability measure
- $\mu$  ... probability measure with finite first moment and distribution function  ${\it F}$
- $\xi_1, \ldots, \xi_N \ldots$  iid sample from  $\mu$

Classical result for  $\mu$  uniform distribution on [0; 1]:

$$\int_0^1 \sqrt{N} \left| \frac{1}{N} \sum_{i=1}^N I_{(0;t]}(\xi_i) - F(t) \right| \mathrm{d}t \to_d \int_0^1 |\mathbb{U}(t)| \mathrm{d}t \tag{2}$$

Distribution of RHS is known explicitly in this case. SHORACK, WELLNER (1986)

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General distribution

$$\int_{-\infty}^{+\infty} \sqrt{N} \left| \frac{1}{N} \sum_{i=1}^{N} I_{(-\infty;t]}(\xi_i) - F(t) \right| \mathrm{d}t \to_d \int_{-\infty}^{+\infty} |\mathbb{U}(F(t))| \mathrm{d}t.$$
(3)

DEL BARRIO, GINÉ, MATRÁN (1999): (3) is valid if (and only if)

$$\int_{-\infty}^{+\infty} \sqrt{F(t)(1-F(t))} \mathrm{d}t < +\infty$$

(In fact: if some processes  $Y_N$  converge weakly in  $L_1(\mathbb{R})$  to Y, then, among others,  $||Y_N||_{L_1} \rightarrow_d ||Y||_{L_1}$  where  $||g||_{L_1} = \int_{-\infty}^{\infty} g(t) dt$  for each non-negative  $g \in L_1(\mathbb{R})$ .)

- idea: convergence is proved for iid data, but some weak dependence property would not make difficulties (as CLT is valid with weak dependence)
- illustration: on simple MA(1) process ξ<sub>k</sub> := 0.5ζ<sub>k</sub> + 0.5ζ<sub>k−1</sub> with normal distribution comparison of independent and weakly dependent and samples
- still to do: AR process ( $\alpha$ -mixing for some class of continuous distributions)
- still to do: modify the proof of DEL BARIO ET AL. (1999) involving the appropriate condition from theory of weakly dependent sequences

## Wasserstein distance Convergence of integrated empirical process



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# Convexity of chance-constrained programs – independent and dependent rows

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## Chance-constrained programming

Basic formulation of the problem

$$\min F_0(x)$$
 subject to  $\mathbb{P}(h(x;\xi) \ge 0)) \ge p$  (4)

- $x \in \mathbb{R}^m \dots$  decision vector
- $\xi: \Omega \to \mathbb{R}^s \dots$  s-dim. random vector defined on  $(\Omega, \mathcal{A}, \mathbb{P})$
- $h: \mathbb{R}^m \times \mathbb{R}^s \to \mathbb{R}^d \dots$  vector-valued mapping
- $p \in [0; 1] \dots$  (prescribed) probability level

Denote

- $\mu = \mathbb{P} \circ \xi^{-1} \dots$  distribution of  $\xi$
- $F = F_{\mu} \dots$  distribution function of  $\xi$
- $H(x) = \{\xi \in \mathbb{R}^m : h(x;\xi) \ge 0\}$
- M(p) = {x ∈ ℝ<sup>m</sup> : ℙ(H(x)) = µ(H(x)) ≥ p} ... set of feasible decisions

## Chance-constrained programming

min 
$$F_0(x)$$
 subject to  $\int_{\mathbb{R}^s} p - \chi_{H(x)}(\xi) \ \mu(\mathrm{d}\xi) \leq 0$  (5)

• form adapted to the general stability theorem – HENRION, RÖMISCH (1999)

min 
$$F_0(x)$$
 subject to  $\mathbb{P}(h(x;\xi) < 0) \le \varepsilon$  (6)

- $\varepsilon = 1 p \dots$  (admissible) level of violation of the constraints
- $M(1-\varepsilon)$  ... set of  $\varepsilon$ -feasible solutions (used in robust programming)

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#### Key question

## When the set M(p) of feasible solutions is convex?

## Trivial result

If  $h(\cdot,\xi)$  is convex for all  $\xi$ , M(0), M(1) are convex

## M(p) is convex if

- $\mu$  is a log-concave (or *r*-concave for  $r \ge -1/s$ ) measure (implied by a log-concave, or  $\frac{r}{1-rs}$ -concave density)
- components of *h* are quasi-concave (in both variables)

## Parameterization of the concavity

#### Definition

 $f: \mathbb{R}^d \to (0; +\infty)$  is *r*-concave for  $r \in [-\infty; +\infty]$  if

$$f(\lambda x + (1-\lambda)y) \geq [\lambda f^r(x) + (1-\lambda)f^r(y)]^{1/r}$$

• cases  $r = -\infty, 0, +\infty$  by continuity

• 
$$r = +\infty$$
 ... RHS = max{ $f(x), f(y)$ }  
•  $r \in (1; +\infty)$  ...  $f^r$  is concave  
•  $r = 1$  ...  $f$  is concave  
•  $r = 0$  ...  $f$  is log-concave (log  $f$  is concave):  
•  $f(\lambda x + (1 - \lambda)y) \ge f^{\lambda}(x)f^{1-\lambda}(y)$   
•  $r < 0$  ...  $f^r$  is convex  
•  $r = -\infty$  ...  $f$  is quasi-concave: RHS = min{ $f(x), f(y)$ }

• for all  $r \leq r^*$ , f is r-concave if it is  $r^*$ -concave

• interesting cases:  $r \leq 1$ 

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## Special case: random RHS

min 
$$F_0(x)$$
 subject to  $\mathbb{P}(g(x) \ge \xi)) \ge p$  (7)

• 
$$h(x;\xi) = g(x) - \xi$$

• 
$$M(p) = \{x \in \mathbb{R}^n : F(g(x)) \ge p\}$$

Required condition: components of *h* are quasi-concave Problem: quasi-concavity is not preserved under addition  $\Rightarrow$  we require g(x) to be convex

Idea of HENRION, STRUGAREK (2006):

- relax concavity condition of g;
- make more stringent concavity condition on  $\mu$ .

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## Definition

- $f: \mathbb{R} \to \mathbb{R}$  is *r*-decreasing for  $r \in \mathbb{R}$  if
  - it is continuous on (0;  $+\infty$ ), and
  - there exists a threshold t\* > 0 such that t<sup>r</sup> f(t) is strictly decreasing for all t > t\*
  - $r = 0 \dots$  strictly decreasing (in the classical sense)
  - for all  $r \leq r^*$ , nonnegative f is r-decreasing if it is  $r^*$ -decreasing
  - key property for marginal densities from the chance-constrained problem
  - lemma: if F is distribution function with (r + 1)-decreasing density, then  $z \mapsto F(z^{-1/r})$  is concave on  $(0; (t^*)^{-r})$

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## Convexity of the problem with RHS HENRION, STRUGAREK (2006)

#### Theorem (HENRION, STRUGAREK (2006))

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- **1**  $g_i$  are  $-r_i$ -concave,
- 2  $\xi_i$  have  $(r_i + 1)$ -decreasing densities,
- $\mathbf{S}_{i}$  are independent,

then M(p) is convex for  $p \ge \max F_i(t_i^*)$ 

Notation (i = 1, ..., s):  $g_i \dots$  components of  $g_{\xi_i} \dots$  components of  $\xi_i$ 

- $F_i \ldots$  components of F
- $t_i^*$  ... threshold of  $r_i + 1$ -decreasing density