Background	Convex sets	Convex functions	Stronger cases	Semiconvex functions	Quasi-convex functions	References

# Stochastic Programming and Convexity

#### Petr Lachout

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Backg	round					

We consider

- Sets in a finite-dimensional Euclidian space  $\mathbb{R}^n$ .
- ► Functions defined on a finite-dimensional Euclidian space ℝ<sup>n</sup> with values in the generalized Euclidian space ℝ<sup>\*</sup> = [-∞, +∞].

Having function  $f : \mathbb{R}^n \to \mathbb{R}^*$  we define its <u>graph</u>, <u>epigraph</u>, <u>hypograph</u>, <u>domain</u>

graph 
$$(f) = \{(x, f(x)) : x \in \mathbb{R}^n\}$$
  
 $= \{(x, \eta) : f(x) = \eta, x \in \mathbb{R}^n, \eta \in \mathbb{R}^*\},\$ 
epi  $(f) = \{(x, \eta) : f(x) \le \eta, x \in \mathbb{R}^n, \eta \in \mathbb{R}\},\$ 
hypo  $(f) = \{(x, \eta) : f(x) \ge \eta, x \in \mathbb{R}^n, \eta \in \mathbb{R}\},\$ 
Dom  $(f) = \{x : f(x) < +\infty, x \in \mathbb{R}^n\}.$ 

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Conve	x sets					

A set  $A \subset \mathbb{R}^n$  is called <u>convex</u> whenever for each couple of points  $x, y \in A$  and  $0 < \lambda < 1$  we have  $\lambda x + (1 - \lambda)y \in A$ .

Equivalently, *A* is convex iff for each couple of points  $x, y \in A$  we have

 $[x,y] = \{tx + (1-t)y : 0 \le t \le 1\} \subset A.$ 

Background	Convex sets	Convex functions	Stronger cases	Semiconvex functions	Quasi-convex functions	References
Conve	x funct	ions				

- A function  $f : \mathbb{R}^n \to \mathbb{R}^*$  is called <u>convex</u> if
  - ▶ Dom (f) is a convex set.
  - For all  $x, y \in \text{Dom}(f)$  and  $0 < \lambda < 1$

$$f(\lambda x + (1 - \lambda)y) \leq \lambda f(x) + (1 - \lambda)f(y).$$

Equivalently, f is convex iff epi (f) is convex.

A function  $f : \mathbb{R}^n \to \mathbb{R}^*$  is called <u>concave</u> iff -f is <u>convex</u>.

## Properties of convex functions

 $\blacktriangleright$  Each level set of a convex function is a convex set, i.e. for each  $\alpha \in \mathbb{R}$ 

$$\begin{aligned} \mathsf{lev}_{[\leq \alpha]}\left(f\right) &= \{x : f\left(x\right) \leq \alpha, \ x \in \mathbb{R}^n\}, \\ \mathsf{lev}_{[<\alpha]}\left(f\right) &= \{x : f\left(x\right) < \alpha, \ x \in \mathbb{R}^n\}. \end{aligned}$$

▶ Each convex function *f* is continuous on int (Dom (*f*)).

Background	Convex sets	Convex functions	Stronger cases	Semiconvex functions	Quasi-convex functions	References
Strong	ger case	S				

- A function  $f : \mathbb{R}^n \to \mathbb{R}^*$  is called strictly convex if
  - ▶ Dom (f) is a convex set.
  - ▶ For all  $x, y \in Dom(f)$ ,  $x \neq y$  and  $0 < \lambda < 1$

 $f(\lambda x + (1 - \lambda)y) < \lambda f(x) + (1 - \lambda)f(y).$ 

Equivalently, f is strictly convex iff epi(f) is convex and each tangent hyperplane to epi(f) which is not perpendicular to horizontal hyperplane contains at most one point of graph (f).

A function  $f : \mathbb{R}^n \to \mathbb{R}^*$  is called strictly concave iff -f is strictly convex.

Background	Convex sets	Convex functions	Stronger cases	Semiconvex functions	Quasi-convex functions	References
Strong	ger case	S				

A function  $f : \mathbb{R}^n \to \mathbb{R}^*$  is called strongly convex if

- Dom (f) is a convex set.
- For all  $x, y \in \text{Dom}(f)$ ,  $x \neq y$  and  $0 < \lambda < 1$

$$egin{array}{ll} f\left(\lambda x+(1-\lambda)y
ight) &\leq & \lambda f\left(x
ight)+(1-\lambda)f\left(y
ight)-rac{\mathsf{C}}{2}\lambda(1-\lambda)\left\|x-y
ight\|^{2}, \end{array}$$

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for an appropriate constant C > 0.

Equivalently,  $f : \mathbb{R}^n \to \mathbb{R}^*$  is strongly convex iff  $g(x) = f(x) - \frac{C}{2} ||x||^2$  is a convex function.

A function  $f : \mathbb{R}^n \to \mathbb{R}^*$  is called <u>strongly concave</u> iff -f is <u>strongly convex</u>.

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### Strongly convex functions - verification

We verify that  $g(x) = f(x) - \frac{C}{2} ||x||^2$  is a convex function:

$$\begin{split} \lambda g(x) &+ (1 - \lambda)g(y) - g(\lambda x + (1 - \lambda)y) = \\ &= \lambda f(x) + (1 - \lambda)f(y) - f(\lambda x + (1 - \lambda)y) - \\ &- \frac{\mathsf{C}}{2} \left( \lambda \|x\|^2 + (1 - \lambda) \|y\|^2 - \|\lambda x + (1 - \lambda)y\|^2 \right) \\ &\geq \frac{\mathsf{C}}{2} \lambda (1 - \lambda) \|x - y\|^2 - \frac{\mathsf{C}}{2} \left( \lambda \|x\|^2 + (1 - \lambda) \|y\|^2 - \\ &- \lambda^2 \|x\|^2 - (1 - \lambda)^2 \|y\|^2 - 2\lambda (1 - \lambda) x^\top y \right) \\ &= \frac{\mathsf{C}}{2} \lambda (1 - \lambda) \|x - y\|^2 - \frac{\mathsf{C}}{2} \lambda (1 - \lambda) \left( \|x\|^2 + \|y\|^2 - 2x^\top y \right) \\ &= \frac{\mathsf{C}}{2} \lambda (1 - \lambda) \|x - y\|^2 - \frac{\mathsf{C}}{2} \lambda (1 - \lambda) \|x - y\|^2 = 0. \end{split}$$

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# Semiconvex functions

A function  $f : \mathbb{R}^n \to \mathbb{R}^*$  is called <u>semiconvex function</u> with <u>linear modulus</u> if

- ▶ Dom (f) is an open set.
- ▶ *f* is continuous on Dom (*f*).
- ▶ For all  $x, h \in \mathbb{R}^n$ ,  $[x h, x + h] \subset \text{Dom}(f)$

$$2f(x) \leq f(x-h) + f(x+h) + C ||h||^2$$
.

for an appropriate constant  $C \ge 0$ .

Constant C is called a <u>semiconvex constant</u> for f in Dom(f).

This definition is frequently used as a definition of "semiconvex functions" in literature. Here we accept a more general concept. Therefore, we added the second prefix "with linear modulus". Latter, we will see why.

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Let Dom(f) be an open set. Hence,

$$\begin{split} &f: \mathbb{R}^n \to \mathbb{R}^* \text{ is } \underline{\text{semiconvex function}} \text{ with } \underline{\text{linear modulus}} \text{ and a} \\ &\text{semiconvex constant } \mathsf{C} \geq 0 \\ &\text{iff} \\ &\text{For all } x, y \in \mathsf{Dom}\,(f), \, [x,y] \subset \mathsf{Dom}\,(f) \text{ and } 0 < \lambda < 1 \\ &f\left(\lambda x + (1-\lambda)y\right) \leq \lambda f\left(x\right) + (1-\lambda)f\left(y\right) + \frac{\mathsf{C}}{2}\lambda(1-\lambda) \left\|x - y\right\|^2. \end{split}$$

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### Semiconvex functions - equivalences

Let Dom(f) be an open convex set. Hence,

$$\begin{split} f: \mathbb{R}^n &\to \mathbb{R}^* \text{ is } \underline{\text{semiconvex function}} \text{ with } \underline{\text{linear modulus}} \text{ and a} \\ \text{semiconvex constant } \mathsf{C} &\geq 0 \\ \text{iff} \\ \text{Function } x &\mapsto f(x) + \frac{\mathsf{C}}{2} \|x\|^2 \text{ is convex.} \\ \text{iff} \\ \text{There are } u, v: \text{Dom}(f) \to \mathbb{R} \text{ such that } f = u + v, u \text{ is convex,} \\ v \in C^2(\text{Dom}(f)) \text{ and } \forall x \in \text{Dom}(f) : \|\nabla^2_{x,x}v(x)\|_{\infty} \leq \mathsf{C}. \end{split}$$

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### Semiconvex functions - verification

We verify that  $g(x) = f(x) + \frac{C}{2} ||x||^2$  is a convex function:

$$\begin{split} \lambda g(x) &+ (1-\lambda)g(y) - g(\lambda x + (1-\lambda)y) = \\ &= \lambda f(x) + (1-\lambda)f(y) - f(\lambda x + (1-\lambda)y) + \\ &+ \frac{C}{2} \left( \lambda \|x\|^2 + (1-\lambda) \|y\|^2 - \|\lambda x + (1-\lambda)y\|^2 \right) \\ &\geq -\frac{C}{2} \lambda (1-\lambda) \|x - y\|^2 + \frac{C}{2} \left( \lambda \|x\|^2 + (1-\lambda) \|y\|^2 - \\ &- \lambda^2 \|x\|^2 - (1-\lambda)^2 \|y\|^2 - 2\lambda (1-\lambda)x^\top y \right) \\ &= -\frac{C}{2} \lambda (1-\lambda) \|x - y\|^2 + \frac{C}{2} \lambda (1-\lambda) \left( \|x\|^2 + \|y\|^2 - 2x^\top y \right) \\ &= -\frac{C}{2} \lambda (1-\lambda) \|x - y\|^2 + \frac{C}{2} \lambda (1-\lambda) \|x - y\|^2 = 0. \end{split}$$

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#### Semiconvex functions - general definition

General definition is taken from the book

Cannarsa, Piermarco; Sinestrari, Carlo: Semiconcave Functions, HamiltonJacobi Equations, and Optimal Control. Birkhuser, Boston, 2004.

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#### Semiconvex functions - general definition

- A function  $f : \mathbb{R}^n \to \mathbb{R}^*$  is called <u>semiconvex function</u> with <u>modulus  $\omega$ </u> if
  - ▶  $\omega : \mathbb{R}_{+,0} \to \mathbb{R}_{+,0}$  is a nondecreasing upper semicontinuous function with  $\omega(0) = 0$ .
  - ▶ For all  $x, y \in Dom(f)$ ,  $[x, y] \subset Dom(f)$  and  $0 < \lambda < 1$

$$\begin{array}{ll} f\left(\lambda x+(1-\lambda)y\right) &\leq & \lambda f\left(x\right)+(1-\lambda)f\left(y\right)+\\ &\quad +\lambda(1-\lambda)\left\|x-y\right\|\omega\left(\|x-y\|\right). \end{array}$$

A function  $f : \mathbb{R}^n \to \mathbb{R}^*$  is called <u>semiconcave</u> iff -f is <u>semiconvex</u>.

### Semiconvex functions - general definition

A function  $f : \mathbb{R}^n \to \mathbb{R}^*$  is called <u>locally semiconvex function</u> if it is <u>semiconvex function</u> on every compact subset of  $\mathbb{R}^n$ .

A function  $f : \mathbb{R}^n \to \mathbb{R}^*$  is called <u>locally semiconcave</u> iff -f is locally semiconvex.

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$$\omega(0+) = \lim_{t\to 0+} \omega(t) = 0.$$

- If  $\omega(t) = \frac{C}{2}t$  then f is <u>semiconvex function</u> with <u>linear modulus</u> and <u>semiconvexity constant</u> C.
- If v ∈ C<sup>1</sup> and Dom (v) is an open convex set then both v, −v are semiconvex with modulus  $ω(t) = \max \{ \|\nabla_x v(x) \nabla_x v(y)\| : \|x y\| \le t \}.$
- If Dom (f) is an open convex set, f = u + v, u is convex, v ∈ C<sup>1</sup>(Dom (f)) then f is locally semiconvex.

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- For each 0 < α < 1 there exists a function f<sub>α</sub> : [0, 1] → ℝ which is semiconvex with modulus ω (t) = Ct<sup>α</sup>, C > 0 and cannot be written as f<sub>α</sub> = u + v, where u is convex, v ∈ C<sup>1</sup>([0, 1]).
- If f<sub>λ</sub>, λ ∈ Λ is a family of semiconvex functions with the same modulus ω then sup<sub>λ∈Λ</sub> f<sub>λ</sub> is a semiconvex function with the modulus ω.
- ► Each semiconvex function f is locally Lipschitz continuous in int (Dom (f)).
- Each locally semiconvex function f is locally Lipschitz continuous in int (Dom (f)).

# Quasi-convex functions

Here we refer from the paper

Prékopa, András; Yoda, Kunikazu; Subasi, Munevver Mine: Uniform Quasi-Concavity in Probabilistic Constrained Stochastic Programming. Operations Research Letters, 39,1(2011), 188-192.

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### Quasi-convex functions

A function  $f : \mathbb{R}^n \to \mathbb{R}^*$  is called <u>quasi-convex</u> if all its level sets are convex sets, i.e. for each  $\alpha \in \mathbb{R}$ 

$$\begin{aligned} \mathsf{lev}_{[\leq \alpha]}\left(f\right) &= \{x : f\left(x\right) \leq \alpha, \ x \in \mathbb{R}^n\},\\ \mathsf{lev}_{[<\alpha]}\left(f\right) &= \{x : f\left(x\right) < \alpha, \ x \in \mathbb{R}^n\}. \end{aligned}$$

A function  $f : \mathbb{R}^n \to \mathbb{R}^*$  is called quasi-concave iff -f is quasi-convex.

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Exam	oles					

$$\begin{array}{rcl} f\left(x\right) &=& \log(x) & \forall x > 0, \\ &=& +\infty & \forall x \leq 0, \\ f\left(x\right) &=& \arctan(x) & \forall x \in \mathbb{R}, \\ f\left(x\right) &=& \sqrt{|x|} & \forall x \in \mathbb{R}. \end{array}$$

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Prope	rtiac					

If a function  $f : \mathbb{R}^n \to \mathbb{R}^*$  is quasi-convex and  $\varphi : \mathbb{R}^* \to \mathbb{R}^*$  is non-decreasing then  $\varphi \circ f$  is also quasi-convex.

## Example (Kataoka 1963, de Panne & Popp 1963)

Let  $b \in \mathbb{R}$  be deterministic and row  $T \in \mathbb{R}^{1 \times n}$  be random and normally distributed.

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Then the function  $h(x) = P(Tx \le b)$  is a quasi-concave function on  $\{y \in \mathbb{R}^n : h(y) \ge \frac{1}{2}\}.$ 

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Proof	1)					

If 
$$x^{\top}$$
 var  $(T) x = 0$  then  $Tx = E[T] x$  a.s. and

$$h(x) = P(Tx \le b) = P(E[T]x \le b) = 1$$
 whenever  $E[T]x \le b$ ,

$$= 0$$
 whenever  $E[T] x \not\leq b$ .

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Proof	2)					

If  $x^{\top}$  var  $(T) x \neq 0$  then

$$h(x) = P(Tx \le b) = \Phi\left(\frac{b - E[T]x}{\sqrt{x^{\top} \operatorname{var}(T)x}}\right).$$

Therefore,

$$\begin{split} h(x) &\geq \Delta \\ & \updownarrow \\ \frac{b - \mathsf{E}[T]x}{\sqrt{x^{\top}\mathsf{var}(T)x}} \geq \Phi^{-1}(\Delta) \\ & \updownarrow \\ \Phi^{-1}(\Delta) \sqrt{x^{\top}\mathsf{var}(T)x} + \mathsf{E}[T]x \leq b. \end{split}$$

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Proof						

The left-hand side of the inequality is a convex function in x iff  $\Phi^{-1}(\Delta) \ge 0$ . Consequently, if  $\Delta \ge \frac{1}{2}$  then

$$\begin{aligned} \{x \in \mathbb{R}^n \, : \, h(x) \ge \Delta\} &= \\ &= \left\{ x \in \mathbb{R}^n \, : \, \Phi^{-1}\left(\Delta\right) \sqrt{x^\top \mathsf{var}\left(T\right) x} + \mathsf{E}\left[T\right] x \le b \right\} \end{aligned}$$

is a convex set.

We have proved that *h* is quasi-concave on the set  $\{x \in \mathbb{R}^n : h(x) \ge \frac{1}{2}\}$ .

## Example (Prékopa 1974)

Let  $b \in \mathbb{R}^m$  be deterministic and matrix  $T \in \mathbb{R}^{m \times n}$  be random. Rows  $T_1, \ldots, T_m$ , are independent normally distributed and var  $(T_{1,\bullet}) = \sigma_1^2 D, \ldots$ , var  $(T_{m,\bullet}) = \sigma_m^2 D.$ Then the function  $h(x) = P(Tx \le b)$  is a quasi-concave function on  $\{y \in \mathbb{R}^n : h(y) \geq \frac{1}{2}\}.$ 

Let  $b \in \mathbb{R}^m$  be deterministic and matrix  $T \in \mathbb{R}^{m \times n}$  be random. Columns  $T_{\bullet,1}, \ldots, T_{\bullet,n}$  are independent normally distributed and  $\operatorname{var}(T_{\bullet,1}) = \sigma_1^2 D, \ldots, \operatorname{var}(T_{\bullet,n}) = \sigma_n^2 D.$ Then the function  $h(x) = P(Tx \le b)$  is a quasi-concave function on  $\{ v \in \mathbb{R}^n : h(v) > \frac{1}{2} \}.$ 

## Uniformly quasi-convex functions

Let  $E \subset \mathbb{R}^n$  and  $f_i : E \to \mathbb{R}^*$ , i = 1, 2, ..., m be given.

We say  $f_i : E \to \mathbb{R}^*$ , i = 1, 2, ..., m are <u>uniformly quasi-concave</u> if

- 1. E is convex.
- 2. For each i = 1, 2, ..., m the function  $f_i$  is quasi-concave on E.
- 3. For each  $x, y \in E$  either

$$\forall i = 1, 2, \dots, m \quad \min\{f_i(x), f_i(y)\} = f_i(x)$$

or

$$\forall i=1,2,\ldots,m \quad \min\{f_i(x),f_i(y)\}=f_i(y).$$

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Prope	rties					

Sum of uniformly quasi-concave functions is quasi-concave.

Product of uniformly quasi-concave functions which are nonnegative is quasi-concave.

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Example (Prékopa 2010)

Let for each i = 1, 2, ..., m be given  $b_i > 0$  deterministic and row  $T_i \in \mathbb{R}^{1 \times n}$  be random with normal probability distribution. We set functions  $h_i(x) = P(T_i x \le b_i)$  for all i = 1, 2, ..., m. We suppose to have a given set E with properties

- 1. *E* is convex.
- 2.  $0 \in int(E)$ .
- 3. For each i = 1, 2, ..., m the function  $h_i$  is quasi-concave on E.

# Example (Prékopa 2010)

#### Then

The family of functions  $h_i$ , i = 1, 2, ..., m is uniformly quasi-concave on E.

#### iff

There are constants  $\gamma \in \mathbb{R}$ ,  $c_1, c_2, \ldots, c_m \in \mathbb{R}_{+,0}$  and positive semidefinite matrix  $\Gamma$  such that

$$\mathsf{E}[T_1] = b_1\gamma, \ \mathsf{E}[T_2] = b_2\gamma, \ \dots, \ \mathsf{E}[T_m] = b_m\gamma,$$
$$\mathsf{var}(T_1) = c_1\Gamma, \ \mathsf{var}(T_2) = c_2\Gamma, \ \dots, \ \mathsf{var}(T_m) = c_m\Gamma.$$

For example  $E = \bigcap_{i=1}^m \{y \in \mathbb{R}^n : h_i(y) \ge \frac{1}{2}\}.$ 

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- Cannarsa, Piermarco; Sinestrari, Carlo: Semiconcave Functions, HamiltonJacobi Equations, and Optimal Control. Birkhuser, Boston, 2004.
- Prékopa, András; Yoda, Kunikazu; Subasi, Munevver Mine: Uniform Quasi-Concavity in Probabilistic Constrained Stochastic Programming.. Operations Research Letters **39,1**(2011), 188-192.

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