$$\frac{4}{2} = \frac{4}{3} - \frac{3}{12-3} = (4-3)(42-3) - 9 = \lambda^{2} - 16\lambda + 39 = (\lambda-3)(\lambda-13) = (\lambda-3)(\lambda-13) = \lambda(\lambda-3)(\lambda-13) = \lambda(\lambda-3) = \lambda(\lambda-3)(\lambda-3) = \lambda(\lambda-3)(\lambda-3) = \lambda(\lambda-3)(\lambda-3) = \lambda(\lambda-3)(\lambda-3) = \lambda(\lambda-3) = \lambda($$

 A^2 and A^{-1} and A + 4I keep the same eigenvectors as A. Their eigenvalues are λ^2 and λ^{-1} and $\lambda + 4$:

$$A^{2}$$
 has eigenvalues $1^{2} = 1$ and $3^{2} = 9$ A^{-1} has $\frac{1}{1}$ and $\frac{1}{3}$ $A + 4I$ has $\begin{array}{c} 1 + 4 = 5\\ 3 + 4 = 7 \end{array}$

The trace of A^2 is 5 + 5 which agrees with 1 + 9. The determinant is 25 - 16 = 9.

Notes for later sections: A has orthogonal eigenvectors (Section 6.4 on symmetric matrices). A can be diagonalized since $\lambda_1 \neq \lambda_2$ (Section 6.2). A is similar to any 2 by 2 matrix with eigenvalues 1 and 3 (Section 6.6). A is a positive definite matrix (Section 6.5) since $A = A^{T}$ and the λ 's are positive.

6.1 B Find the eigenvalues and eigenvectors of this 3 by 3 matrix *A*:

Symmetric matrix		1	-1	0
Singular matrix	A =	-1	2	-1
Trace $1 + 2 + 1 = 4$		0	-1	1

Solution Since all rows of *A* add to zero, the vector $\mathbf{x} = (1, 1, 1)$ gives $A\mathbf{x} = \mathbf{0}$. This is an eigenvector for the eigenvalue $\lambda = 0$. To find λ_2 and λ_3 I will compute the 3 by 3 determinant:

$$\det(A - \lambda I) = \begin{vmatrix} 1 - \lambda & -1 & 0 \\ -1 & 2 - \lambda & -1 \\ 0 & -1 & 1 - \lambda \end{vmatrix} = (1 - \lambda)(2 - \lambda)(1 - \lambda) - 2(1 - \lambda)$$
$$= (1 - \lambda)[(2 - \lambda)(1 - \lambda) - 2]$$
$$= (1 - \lambda)(-\lambda)(3 - \lambda).$$

That factor $-\lambda$ confirms that $\lambda = 0$ is a root, and an eigenvalue of A. The other factors $(1 - \lambda)$ and $(3 - \lambda)$ give the other eigenvalues 1 and 3, adding to 4 (the trace). Each eigenvalue 0, 1, 3 corresponds to an eigenvector:

$$\boldsymbol{x}_1 = \begin{bmatrix} 1\\1\\1 \end{bmatrix} \quad A\boldsymbol{x}_1 = \boldsymbol{0}\boldsymbol{x}_1 \qquad \boldsymbol{x}_2 = \begin{bmatrix} 1\\0\\-1 \end{bmatrix} \quad A\boldsymbol{x}_2 = \boldsymbol{1}\boldsymbol{x}_2 \qquad \boldsymbol{x}_3 = \begin{bmatrix} 1\\-2\\1 \end{bmatrix} \quad A\boldsymbol{x}_3 = \boldsymbol{3}\boldsymbol{x}_3$$

I notice again that eigenvectors are perpendicular when A is symmetric.

The 3 by 3 matrix produced a third-degree (cubic) polynomial for det $(A - \lambda I) = -\lambda^3 + 4\lambda^2 - 3\lambda$. We were lucky to find simple roots $\lambda = 0, 1, 3$. Normally we would use a command like **eig**(*A*), and the computation will never even use determinants (Section 9.3 shows a better way for large matrices).

The full command [S, D] = eig(A) will produce unit eigenvectors in the columns of the eigenvector matrix S. The first one happens to have three minus signs, reversed from (1, 1, 1) and divided by $\sqrt{3}$. The eigenvalues of A will be on the diagonal of the eigenvalue matrix (typed as D but soon called Λ).



6

2a (5 -2) D1 = 5 > 0 P.D. definite D2 = 25-4=20 >0 25 $\begin{pmatrix} -2 & 1 \\ 1 & -2 \end{pmatrix}$ $D_{A} = -2 < 0$ 3 Neg. Lefinite 02 = 4-1 =3 >0 2c $\begin{pmatrix} 1 - 4 \\ -4 & 5 \end{pmatrix}$ $b_1 = 1$ $b_1 = 1$ $b_2 = -5 - 16 = -21 < 0$ f = 1 - 21 < 022 $\begin{vmatrix} 3 & 0 & 3 \\ 0 & 1 & -2 \\ 3 & -2 & 8 \end{vmatrix}$ $b_1 = 3 > 0$ $b_2 = 3 - 0 = 3 > 0$ $b_3 = 24 - 9 - 12 = 3 > 0$ $\begin{pmatrix} -4 & -2 & 1 \\ -2 & 2 & -1 \\ 1 & -1 & 2 \end{pmatrix}$ $D_{A} = -4 \times 0$ (Infel b2 = -8-4 = - 12 <0 b3 = -16 +2 +2 - 2 +4 -8 = -1840 28 $\begin{vmatrix} -2 & 1 & 0 \\ 1 & -1 & 1 \\ 0 & 1 & -2 \\ 2g \end{vmatrix}$ b1 = -2 <0 $b_2 = 1 > 0$ $b_3 = -4 + 2 + 2 = 0$ S We to not know. $D_{A} = -3 < 0$ $b_2 = 2 > 0$ $b_3 = -6 + 3 + 2 = -1 < 0$ $\int def$ $\begin{pmatrix} -3 & 1 & 0 \\ 1 & -1 & 1 \\ 0 & 1 & -2 \end{pmatrix}$