

DEFINITION OF RS AND EXAMPLES

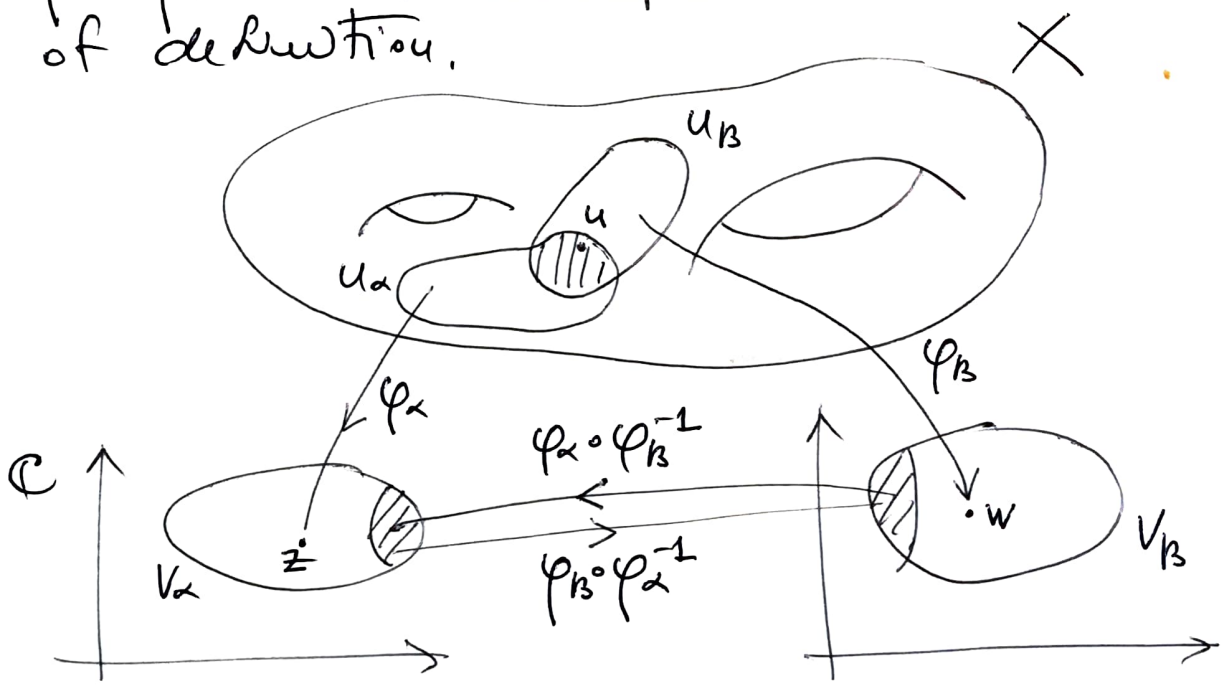
RS = 1-dim complex manifold

DEF A Riemann surface is given by the following data:

- (1) A Hausdorff topological space X (with a countable basis of open sets);
- (2) a collection of open sets $U_\alpha \subset X, \alpha \in I$ such that $X = \bigcup_{\alpha \in I} U_\alpha$;

(3) For each $\alpha \in I$, a homeomorphism $\varphi_\alpha: U_\alpha \rightarrow V_\alpha$ is given where V_α is an open set in \mathbb{C} , with the property that for all $\alpha, \beta \in I$ the composite map

(*) $\varphi_\alpha \circ \varphi_\beta^{-1}$ is holomorphic on its domain of definition.



Riemann surface theory studies properties independent of the choice of co-ordinates chart. RS3

3.) For any atlas \mathcal{A} on X , there is a unique maximal atlas $\tilde{\mathcal{A}}$ on X such that $\tilde{\mathcal{A}} \supset \mathcal{A}$. We call $\tilde{\mathcal{A}}$ a conformal structure on X .

If atlases \mathcal{A} and \mathcal{B} on X give the same conformal structure (i.e., $\mathcal{A} \cup \mathcal{B}$ is an atlas on X), then we consider the corresponding \mathbb{R}^2 's as the same.

4.) If we take the same definition but in (*) replace the word 'holomorphic' by smooth (with positive Jacobian) we get the definition of an (oriented) smooth surface.

Let $U \subset \mathbb{C}$ be open and $f: U \rightarrow \mathbb{C}$. Since $\mathbb{C} \cong \mathbb{R}^2$, $z = x + iy = (x, y)$ we can view f as a map from \mathbb{R}^2 to \mathbb{R}^2 . Here f is smooth if f is C^∞ in the sense of two real variables.

Claim If the complex derivative $f'(z_0)$ exists, then Jacobian $J_f(z_0) = |f'(z_0)|^2$.

Proof: If $f = f_1 + if_2$, then

RS4

$$J_f = \det \begin{pmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial y} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} \end{pmatrix}.$$

At z_0 , using CR conditions, we get

$$J_f = \left(\frac{\partial f_1}{\partial x} \right)^2 + \left(\frac{\partial f_2}{\partial x} \right)^2 = \left| \frac{\partial f}{\partial x} \right|^2 = |f'|^2. \quad \square$$

By Claim, all Riemann surfaces are oriented smooth surfaces.

On the other hand, every oriented smooth surface X in \mathbb{R}^3 has a unique compatible conformal structure.

5.) If we take the same definition but replace \mathbb{C} with \mathbb{R}^n and the word 'holomorphic' in (*) with smooth we get the definition of an n -dimensional smooth manifold.

If we replace \mathbb{C} with \mathbb{C}^n and, in (*), we consider maps holomorphic in the sense of several complex variables, we get the definition of an n -dimensional complex manifold.

In particular, RS is a 1-dim complex manifold.

Examples

RS 5

1. Let X be an open set in \mathbb{C} .

Atlas: (X, Id) .

In particular, $X = \mathbb{C}$ or the unit disc

$$\mathbb{D} := \{z \in \mathbb{C} \mid |z| < 1\}.$$

Let Y be an open subset of a RS X .
If \mathcal{A} is an atlas on X , then

$$\mathcal{A}|_Y := \left\{ (U \cap Y, \varphi|_{U \cap Y}) \mid (U, \varphi) \in \mathcal{A} \right\}$$

is an atlas on Y and $(Y, \mathcal{A}|_Y)$ is a RS.

2. Riemann sphere $\mathbb{S}^1 = \mathbb{C} \cup \infty$

Atlas: (\mathbb{C}, φ_1) where $\varphi_1(z) := z$;

$(\mathbb{S}^1 \setminus \infty, \varphi_2)$ where $\varphi_2(z) := \frac{1}{z}$, $z \in \mathbb{C} \setminus \infty$,
 $:= 0$, $z = \infty$.

Then $\varphi_1 \circ \varphi_2^{-1}(z) = \frac{1}{z} = \varphi_2 \circ \varphi_1^{-1}(z)$, $z \in \mathbb{C} \setminus \infty$.

3. Algebraic curves

RSG

• studied in Algebraic Geometry

Let $P(z, w)$ be a polynomial in two complex variables, that is,

$$P(z, w) = \sum_{n, m \in \mathbb{N}_0} a_{nm} z^n w^m$$

where $a_{nm} \neq 0$ for a finitely many $(n, m) \in \mathbb{N}_0^2$.

Put

$$(AC) \quad X := \{(z, w) \in \mathbb{C}^2 \mid P(z, w) = 0\},$$

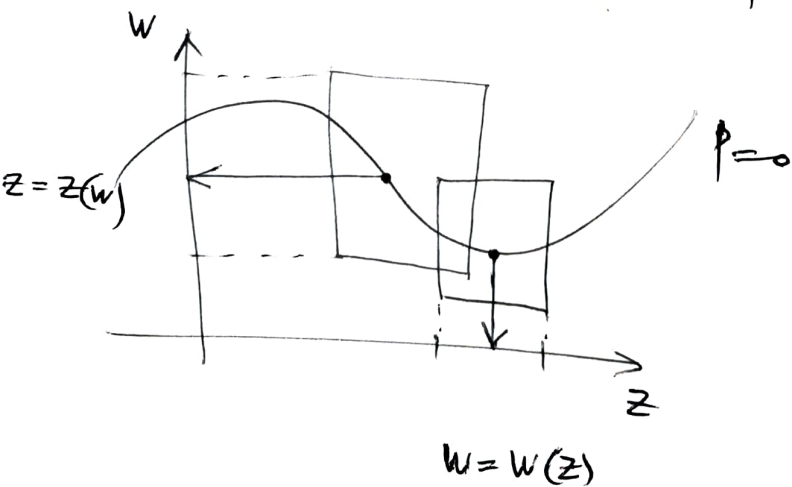
the zero set of the polynomial P .

FACT If $(\frac{\partial P}{\partial z} \mid \frac{\partial P}{\partial w}) \neq (0, 0)$ on X , then

X is a RS with local co-ordinates given by

(i) $(z, w) \rightarrow w$ on neighborhoods of points at which $\frac{\partial P}{\partial z} \neq 0$;

(ii) $(z, w) \rightarrow z$ on ngh of points at which $\frac{\partial P}{\partial w} \neq 0$.



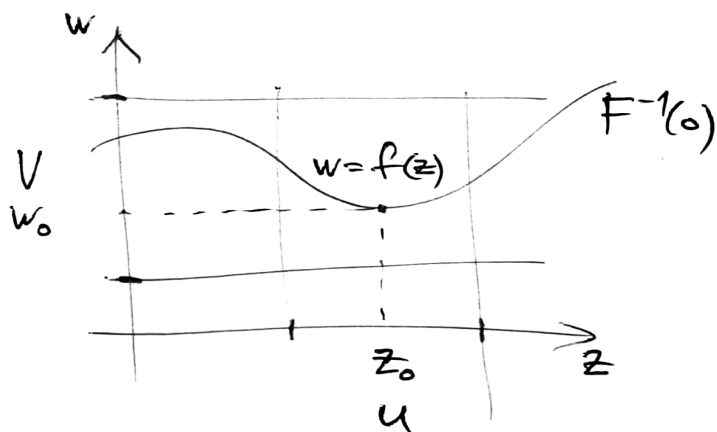
A proof of FACT follows from the following theorem.

Theorem (on implicit function, complex version)

Let $F: \mathbb{C}^2 \rightarrow \mathbb{C}$ be a holomorphic function in a ngl. of $(z_0, w_0) \in \mathbb{C}^2$, i.e., $F = F(z, w)$ and has (continuous) $\frac{\partial F}{\partial z}$ and $\frac{\partial F}{\partial w}$ there. Let $F(z_0, w_0) = 0$.

(a) Assume $\frac{\partial F}{\partial w}(z_0, w_0) \neq 0$. Then $F^{-1}(0)$ in some ngl. of (z_0, w_0) is the graph of a holomorphic function $w = w(z)$. To be more precise, there are a ngl $U \subset \mathbb{C}$ of z_0 , a ngl $V \subset \mathbb{C}$ of w_0 and a holomorphic function $f: U \rightarrow V$ such that

$$F^{-1}(0) \cap (U \times V) = \text{graph } f \stackrel{\text{def.}}{=} \{(z, f(z)) \mid z \in U\}.$$



(b) Assume $\frac{\partial F}{\partial z}(z_0, w_0) \neq 0$. Then $F^{-1}(0)$ in some ngl. of (z_0, w_0) is the graph of a holomorphic function $z = z(w)$.

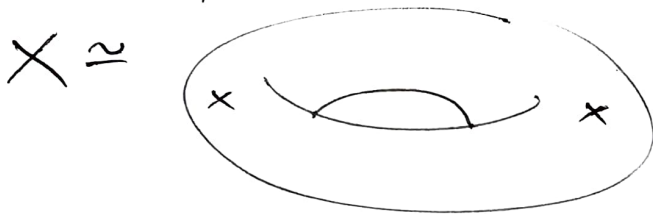
(c) If $\frac{\partial F}{\partial z}(z_0, w_0) \neq 0$ and $\frac{\partial F}{\partial w}(z_0, w_0) \neq 0$, then the functions $z = z(w)$ and $w = w(z)$ of (a) and (b) are

inverse of each other.

RSF

Proof: We can view F also as a function from \mathbb{R}^4 to \mathbb{R}^2 . Since F is C^1 we can use a 'real' version of Theorem on an implicit function. To verify that corresponding Jacobians are non-zero and that $w = w(z)$, $z = z(w)$ are holomorphic, we use the CR conditions. Exercise ▣

Example Consider $X := \{(z, w) \in \mathbb{C}^2 \mid w^2 = p(z)\}$ where $p(z) = (z^2 - 1)(z^2 - 4)$. We know that



Then X is a RS because, for

$P(z, w) := w^2 - p(z)$, we have

- $\frac{\partial P}{\partial w} = 2w \neq 0$ iff $w \neq 0$;
- $\frac{\partial P}{\partial z} = -p' \neq 0$ if $w = 0$ and $z = \pm 1, \pm 2$
simple roots of p