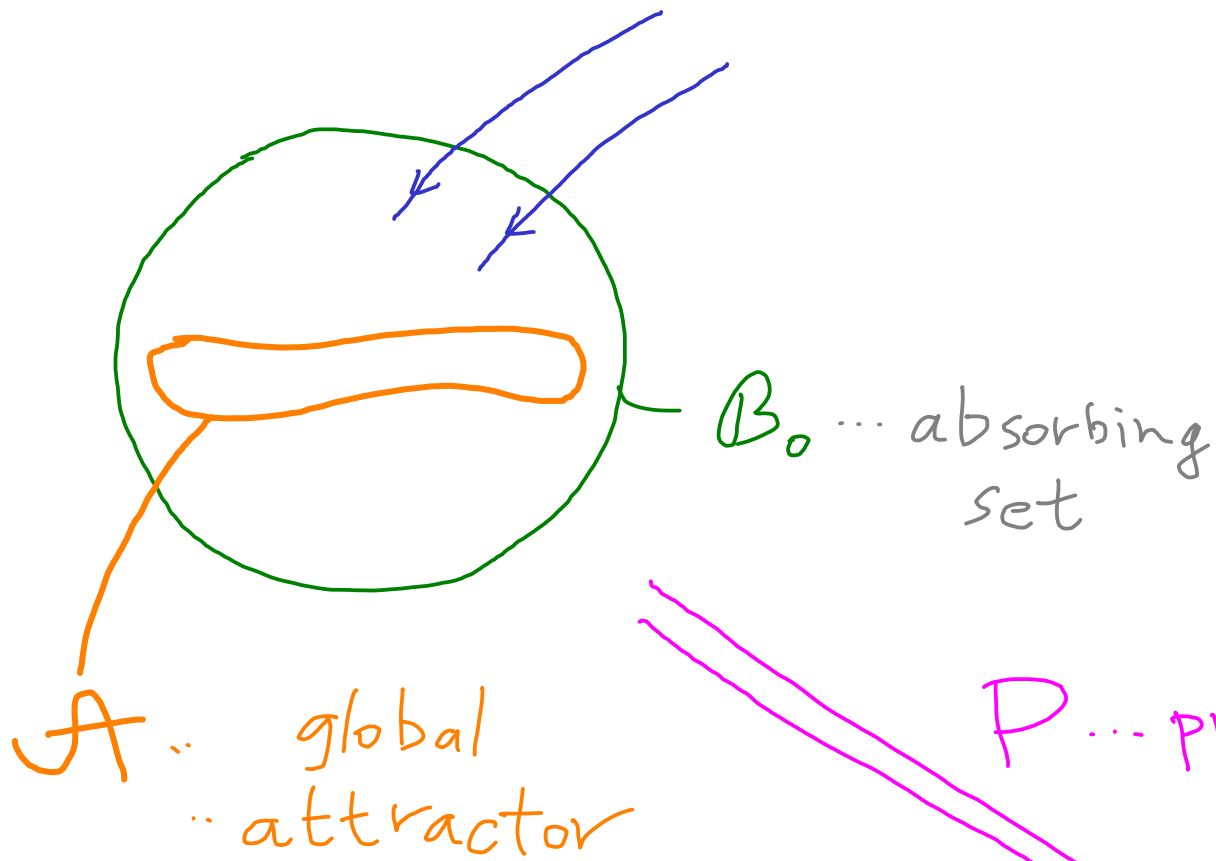


A finite-dimensional reduction of dissipative dynamical systems

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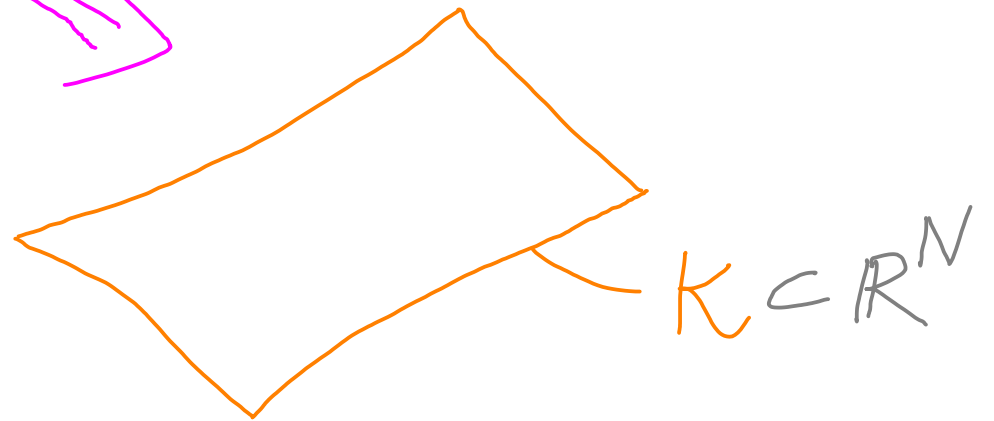
1. Basic problem
2. Dynamics of trajectories
3. Abstract result
4. Application



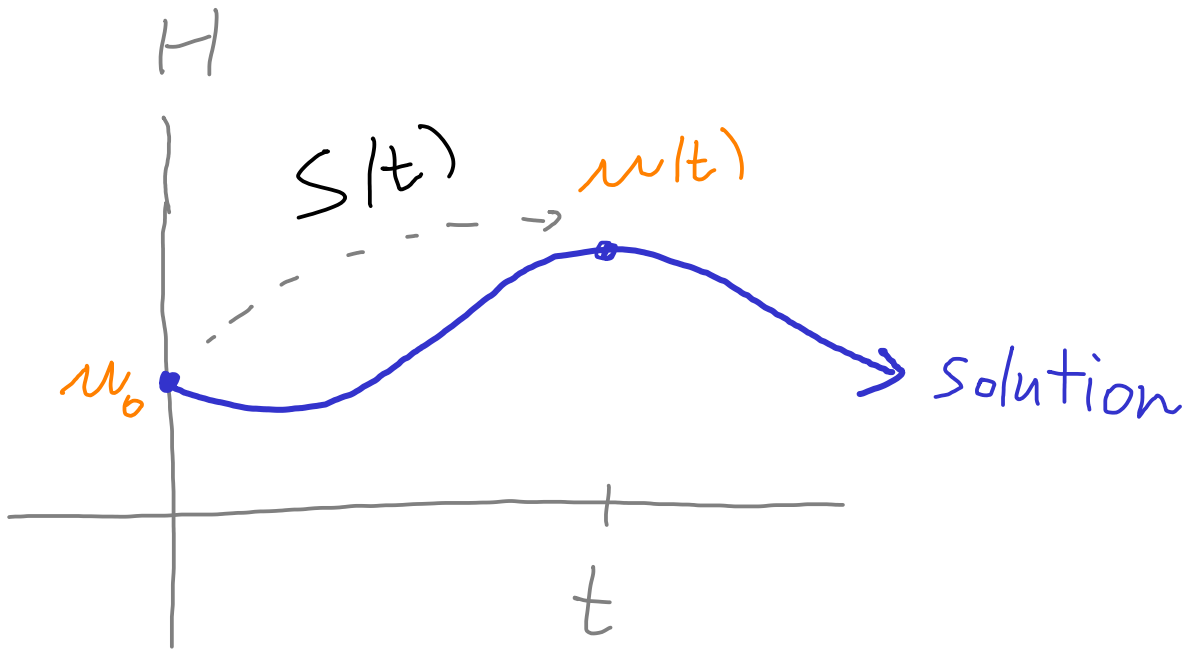
$$\frac{d}{dt} u = F(u) \quad (1)$$

$$u(0) = u_0$$

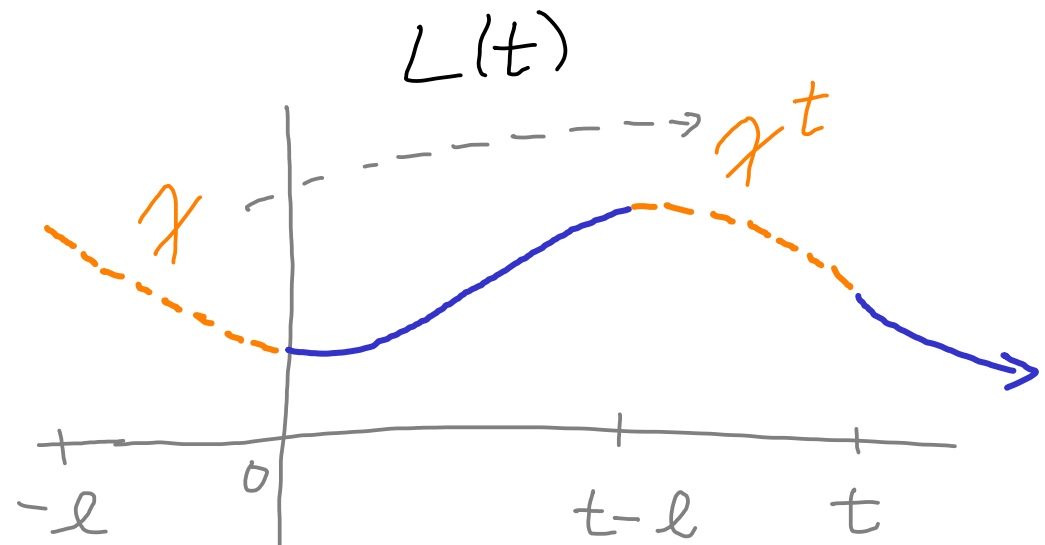
- $\dim A < \infty$
- Mañé's projections
- inertial manifolds



Dynamics of trajectories



$$\frac{d}{dt} u = F(u) \quad (1)$$
$$u(0) = u_0$$



- (semi)infinite traj.

An abstract problem

(1)

$$\frac{d}{dt}u + A(u) + B(u) = 0$$

$$u(0) = u_0$$

$$u : [0, T] \rightarrow H$$

$$A : V \rightarrow V'$$

$$B : V \rightarrow V'$$

the unknown

nonlinear, elliptic

lower-order

Gelfand
triple

$$V \hookrightarrow G \hookrightarrow H \hookrightarrow V'$$

↑ Hilbert

Typical assumptions

$$A(0) = 0,$$

$$\|A(u) - A(v)\|_{V'} \leq c_1 \|u - v\|_V,$$

$$\langle A(u) - A(v), u - v \rangle \geq a \|u - v\|_V^2,$$

2-elliptic

lower order

$$\|B(u) - B(v)\|_{V'} \leq b \|u - v\|_H^\alpha \|u - v\|_V^{1-\alpha}, \quad \alpha \in (0, 1],$$

$$\langle B(u), u \rangle \geq -\varepsilon \|u\|_V^2 - K_\varepsilon, \quad \varepsilon > 0.$$

dissipativity

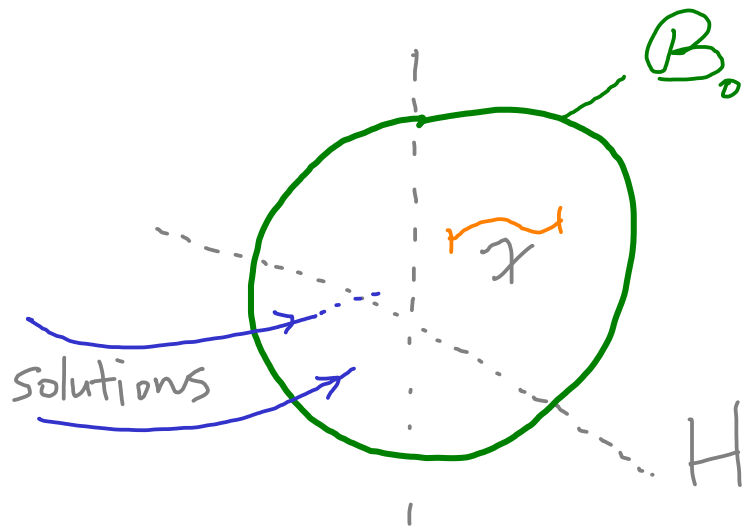
Theorem 1. Let $u_0 \in H$ and $T > 0$ be given. Then there exists a weak solution

$$\begin{aligned} u &\in L^\infty(0, T; H) \cap L^2(0, T; V), \\ d_t u &\in L^2(0, T; V'), \end{aligned} \tag{4}$$

where $u(0) = u_0$ in the sense of a representative $u \in C([0, T]; H)$.

Well-posedness

Lemma 3. For $R > 0$ large enough, the ball $\mathcal{B}_0 = \{u \in H; \|u\|_H^2 \leq R\}$ is uniformly absorbing and positively invariant.



Set of ℓ -trajectories (in \mathcal{B}_0)

$$\mathcal{B}_\ell := \{\chi : [-\ell, 0] \rightarrow H; \chi \text{ is weak solution, } \chi(-\ell) \in \mathcal{B}_0\}$$

$$H_\ell := L^2(-\ell, 0; H) \leftarrow \text{metric}$$

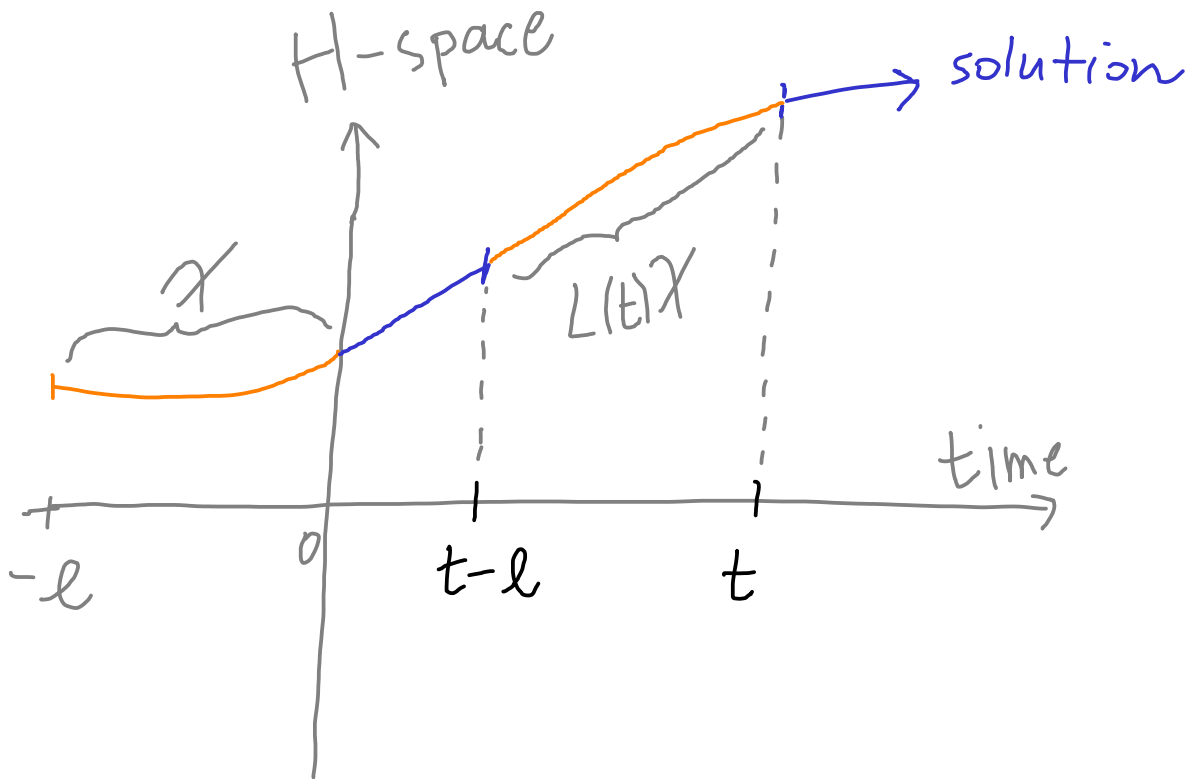
Lemma 4. The set \mathcal{B}_ℓ is compact in H_ℓ .

Lemma 5. (i) $L(t) : H_\ell \rightarrow H_\ell$ is Lipschitz continuous on \mathcal{B}_ℓ .

(ii) $L(\ell) : H_\ell \rightarrow W_\ell$ is Lipschitz continuous on \mathcal{B}_ℓ , where

$$\|x\|_{W_\ell}^2 = \int_{-\ell}^0 \|x\|_V^2 + \|d_t x\|_{V'}^2.$$

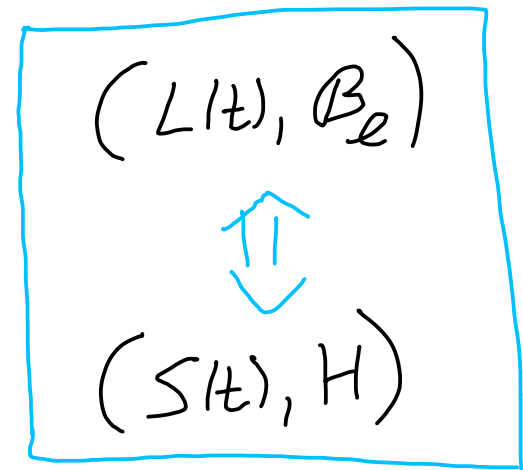
"Smoothing"
property



Results

1) \exists global attractor (with $\dim < \infty$)

\exists exponential attractor



2) \exists ODE-like reduction ($H \rightarrow \mathbb{R}^N$)

ad2) \mathcal{A}_ℓ ... global attractor (for $L(t)$)

$$\mathcal{A}^{\leq 0} = \{ \chi^t : (-\infty, 0] \rightarrow \mathcal{B}_\ell, \text{ solves (1), } \chi^0 \in \mathcal{A}_\ell \}$$

$$\mathcal{T} = \{ p(t) : (-\infty, 0] \rightarrow \mathbb{R}^N, p(t) = P\chi^t, \chi^t \in \mathcal{A}_\ell \}$$

finite-dim. projection

Lemma 6. For any $p \in \mathcal{T}$, there exists unique $\chi^0 \in \mathcal{A}^{\leq 0}$ such that $p(t) = P\chi^t$, $t \leq 0$. The mapping $E : p \mapsto \chi^0$ is Lipschitz from X to W_ℓ , where X is given by

$$\|p\|_X = \sup_{s \leq 0} e^{\gamma s} \|p(s)\|_{\mathbb{R}^N}$$

with suitable $\gamma > 0$.

X -norm

ODE-like reduction

$$(1) \quad \frac{d}{dt} u + A(u) + B(u) = 0 \quad (\text{PDE})$$



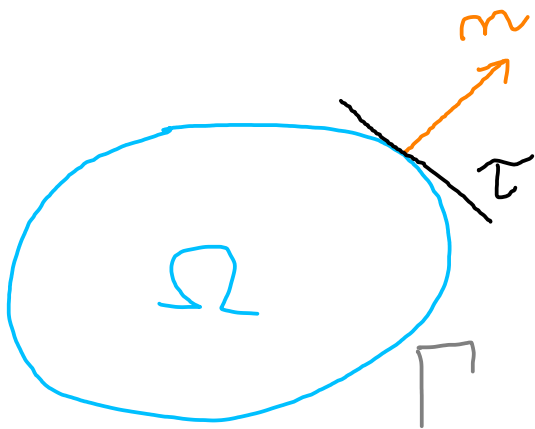
$$(2) \quad \frac{d}{dt} u(t) + F(u^{\leq t}) = 0 \quad (\text{delayed ODE})$$

(with $F: X \rightarrow \mathbb{R}^N$ Lipschitz)

Application: nonlinear fluids & dynamic b.c.

$$\left. \begin{aligned} \partial_t u + (u \cdot \nabla) u - \operatorname{div} S + \nabla \pi &= f \\ \operatorname{div} u &= 0 \end{aligned} \right\} \text{in } \Omega$$

$$\left. \begin{aligned} u \cdot n &= 0 \\ \alpha u + \beta \partial_t u + (S n)_\tau &= 0 \end{aligned} \right\} \text{on } \Gamma$$



$$S \sim \nu_0 D + \nu_1 |D| D^{\tau-2}$$

$$(\tau \geq 2)$$

Thank you!