

# On the analysis of unsteady flows of implicitly constituted incompressible fluids

Miroslav Bulíček

Mathematical Institute of the Charles University  
Sokolovská 83, 186 75 Prague 8, Czech Republic

**P. Gwiazda, J. Málek and A. Świerczewska-Gwiazda**

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## Balance equations

We consider flow of a homogeneous incompressible fluid under constant temperature

$$\operatorname{div} \boldsymbol{v} = 0$$

$$\boldsymbol{v}_{,t} + \operatorname{div}(\boldsymbol{v} \otimes \boldsymbol{v}) - \operatorname{div} \boldsymbol{S} = -\nabla p + \boldsymbol{f}$$

$$\boldsymbol{S} = \boldsymbol{S}^T$$

- $\boldsymbol{v}$  is the velocity of the fluid
- $p$  is the pressure
- $\boldsymbol{f}$  external body forces ( $\equiv \mathbf{0}$ )
- $\boldsymbol{S}$  is the constitutively determined part of the Cauchy stress

The Cauchy stress is given as  $\boldsymbol{T} = -p\mathbf{I} + \boldsymbol{S}$

# Point-wisely given constitutive equations

- We denote by  $\mathbf{D}(v)$  the symmetric part of the velocity gradient, i.e.,  $2\mathbf{D}(v) := \nabla v + (\nabla v)^T$ .
- We assume for simplicity only point-wise relation between  $\mathbf{D}$  and  $\mathbf{S}$ .
- We add to balance equations some implicit (constitutive) formula:

$$\mathbf{F}(\mathbf{S}, \mathbf{D}, \rho, x, t, \text{temperature, concentration, etc.}) = \mathbf{0}.$$

- In what follows we consider only:

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# Explicit constitutive equations

Nice “continuous” explicit models ( $\mathbf{S} := \mathbf{S}(\mathbf{D})$ )

- Newtonian fluid

$$\mathbf{S} = \nu_0 \mathbf{D}, \quad \nu_0 > 0,$$

- Ladyzhenskaya (power-law like fluid)

$$\mathbf{S} = \nu_0 (\nu_1 + |\mathbf{D}|^2)^{\frac{r-2}{2}} \mathbf{D}, \quad r > 1, \quad \nu_1 \geq 0.$$

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$$\mathbf{D} = \nu_0^* \mathbf{S}, \quad \nu_0^* > 0,$$

- Inverse-like Ladyzhenskaya (power-law like fluid)

$$\mathbf{D} = \nu_0^* (\nu_1^* + |\mathbf{S}|^2)^{\frac{r^*-2}{2}} \mathbf{S}, \quad r^* > 1, \quad \nu_1^* \geq 0.$$

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# Explicit constitutive equations

## “Discontinuous” explicit models

- Perfect plastic

$$|\mathbf{D}| = 0 \implies |\mathbf{S}| \leq 1$$

$$|\mathbf{D}| > 0 \implies \mathbf{S} := \frac{\mathbf{D}}{|\mathbf{D}|}$$

- Bingham (Herschley-Bulkley fluid)

$$|\mathbf{D}| = 0 \implies |\mathbf{S}| \leq \nu_0$$

$$|\mathbf{D}| > 0 \implies \mathbf{S} := \frac{\nu_0 \mathbf{D}}{|\mathbf{D}|} + \nu(|\mathbf{D}|) \mathbf{D}$$

- Fluids with activation criteria

$$\mathbf{S} = \nu(|\mathbf{D}|) \mathbf{D}$$

with  $\nu$  being discontinuous at some  $d^*$ -the activation criterium



# Implicit-like constitutive equations

Still nice continuous explicit formula

- Bingham fluid

$$\mathbf{D} = \frac{(|\mathbf{S}| - \nu_0)_+}{\nu_1 |\mathbf{S}|} \mathbf{S}$$

Only fully implicit continuous choice

- Perfect plastic

$$||\mathbf{D}|\mathbf{S} - \mathbf{D}| + (|\mathbf{S}| - 1)_+ = 0$$

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# Implicit formulation - maximal (monotone) graph setting

Implicit theory allows to get more models. Principle of objectivity and material isotropy imply that

- Explicit relation  $\mathbf{S} = \mathbf{S}(\mathbf{D})$  - the only form

$$\mathbf{S} = \alpha_0 \mathbf{I} + \alpha_1 \mathbf{D} + \alpha_2 \mathbf{D}^2$$

with  $\alpha$ 's dependent on invariants

- Implicit relation  $\mathbf{F}(\mathbf{S}, \mathbf{D})$  - the only form

$$0 = \alpha_0 \mathbf{I} + \alpha_1 \mathbf{D} + \alpha_2 \mathbf{D}^2 + \alpha_3 \mathbf{S} + \alpha_4 \mathbf{S}^2 + \alpha_5 (\mathbf{D}\mathbf{S} + \mathbf{S}\mathbf{D}) + \dots$$

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# Implicit formulation - maximal (monotone) graph setting

Implicit function  $\mathbf{F}$  determines a graph  $\mathcal{A} \subset \mathbb{R}_{sym}^{d \times d} \times \mathbb{R}_{sym}^{d \times d}$  (or  $\mathcal{A}(t, x)$ ). We assume that the graph is the  $\psi$ -maximal monotone graph:

- $(\mathbf{0}, \mathbf{0}) \in \mathcal{A}$
- Monotonicity: For any  $(\mathbf{S}_1, \mathbf{D}_1), (\mathbf{S}_2, \mathbf{D}_2) \in \mathcal{A}$

$$(\mathbf{S}_1 - \mathbf{S}_2) : (\mathbf{D}_1 - \mathbf{D}_2) \geq 0$$

**No strict monotonicity is needed!**

- Maximal graph: If for some  $(\mathbf{S}, \mathbf{D})$  there holds

$$(\mathbf{S} - \tilde{\mathbf{S}}) : (\mathbf{D} - \tilde{\mathbf{D}}) \geq 0 \quad \forall (\tilde{\mathbf{S}}, \tilde{\mathbf{D}}) \in \mathcal{A}$$

then

$$(\mathbf{S}, \mathbf{D}) \in \mathcal{A}$$

- If  $\mathcal{A}$  is  $(t, x)$ -dependent some measurability w.r.t.  $(t, x)$
- $\psi$  and  $\psi^*$  coercivity: For any  $(\mathbf{S}, \mathbf{D}) \in \mathcal{A}(t, x)$

$$\mathbf{S} : \mathbf{D} \geq \alpha(\psi(\mathbf{D}) + \psi^*(\mathbf{S})) - g(t, x) \quad (\text{En})$$

with  $\alpha \in (0, 1]$  and  $g \in L^1$ .

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# What is $\psi$ ? Excursion to Orlicz setting

Assume that  $\psi : \mathbb{R}_{sym}^{d \times d} \rightarrow \mathbb{R}$  is an  $N$ -function (if it depends only on the modulus then Young function), i.e.,

- $\psi$  is convex and continuous
- $\psi(\mathbf{D}) = \psi(-\mathbf{D})$
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$$\lim_{|\mathbf{D}| \rightarrow 0^+} \frac{\psi(\mathbf{D})}{|\mathbf{D}|} = 0, \quad \lim_{|\mathbf{D}| \rightarrow \infty} \frac{\psi(\mathbf{D})}{|\mathbf{D}|} = \infty$$

We define the conjugate function  $\psi^*$  as

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- Young inequality:

$$\mathbf{S} : \mathbf{D} \leq \psi(\mathbf{D}) + \psi^*(\mathbf{S})$$

- Orlicz spaces: The Orlicz space  $L^\psi(\mathcal{O})^{d \times d}$  is the set of all measurable function  $\mathbf{D} : \Omega \rightarrow \mathbb{R}_{sym}^{d \times d}$  such that

$$\lim_{\lambda \rightarrow \infty} \int_{\mathcal{O}} \psi(\lambda^{-1} \mathbf{D}) = 0$$

with the norm

$$\|\mathbf{D}\|_{L^\psi} := \inf \left\{ \lambda; \int_{\mathcal{O}} \psi(\lambda^{-1} \mathbf{D}) \leq 1 \right\}$$

- $\Delta_2$  condition

$$\psi(2\mathbf{D}) \leq C_1 \psi(\mathbf{D}) + C_2$$

# Optimality of $\psi$ and $\psi^*$ - more general models

- Non-polynomial growth

$$\mathbf{S} \sim (1 + |\mathbf{D}|^2)^{\frac{r-2}{2}} \ln(1 + |\mathbf{D}|) \mathbf{D} \implies \psi(\mathbf{D}) \sim |\mathbf{D}|^r \ln(1 + |\mathbf{D}|)$$

- Different upper and lower growth in principle -  $\psi$  has different polynomial upper and lower growth, for  $\psi(\mathbf{D}) := \psi(|\mathbf{D}|)$

$$c_1 |\mathbf{D}|^r - c_2 \leq \psi(|\mathbf{D}|) \leq c_3 |\mathbf{D}|^q + c_4$$

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# What is the goal?

- Goal = existence result for as general constitutive relationship as possible
- A priori = energy estimates ( $\Omega$  bounded and sufficiently smooth, boundary conditions allowing to get the estimates)

- Steady case

$$\int_{\Omega} \psi(\mathbf{D}) + \psi^*(\mathbf{S}) \, dx \leq C$$

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$$\sup_t \|v\|_2^2 + \int_0^T \int_{\Omega} \psi(\mathbf{D}) + \psi^*(\mathbf{S}) \, dx \, dt \leq C$$

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# How to get the goal

- Energy equality “holds”  $\implies$  simpler proof, i.e., if

$$\int (v \otimes v) : \mathbf{D}(v) \quad \text{is meaningful}$$

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## The key result

Theorem (Easier case; **Gwiazda, Świerczewska-Gwiazda et al**)

*If energy equality “holds” and  $\psi^*$  satisfies  $\Delta_2$  conditions then there exists a weak solution for any relevant boundary conditions.*

Theorem (Difficult case; **Bulíček, Gwiazda, Málek and Świerczewska-Gwiazda**)

*Let  $\psi(\mathbf{D}) := \psi(|\mathbf{D}|)$  and  $\psi$  and  $\psi^*$  satisfy  $\Delta_2$  condition. Assume that energy space is compactly embedded into  $L^2$ . Then there exists a weak solution for Navier’s bc.*

- The same result also holds for Dirichlet bc. by using the Wolf decomposition of the pressure.

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# Byproducts-increase the citation report

## Byproduct

*Theory for the laplace equation with Neumann bc, i.e., for  $\psi$  and  $\psi^*$  satisfying  $\Delta_2$  condition, we have*

$$\int_{\Omega} \psi(|\nabla^2 u|) \leq C \left( 1 + \int_{\Omega} \psi(|f|) \right)$$

*for any  $u$  solving homogeneous Neuman problem with right hand side  $f$ .*

## Byproduct

*Improvement of the Minty method  $\implies$  no use of the Vitali theorem  $\implies$  no strict monotonicity required*

## Byproduct

*Improvement of the Lipschitz approximation method  $\implies$  no need of  $\Delta_2$  for  $\psi \implies$  nothing to our case due to the pressure  $\implies$  but may be use for general parabolic/elliptic problems*

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# Power-law like fluid - Explicit

Compact embedding is available if  $r > \frac{6}{5}$

- $r = 2$  **Leray** (1934)
- $r \geq \frac{11}{5}$  for unsteady,  $r \geq \frac{9}{5}$  steady; **Ladyzhenskaya** 60's
- $r \geq \frac{9}{5}$  unsteady; **Málek, Nečas, Růžička** 90's
- $r \geq \frac{8}{5}$  unsteady; **Frehse, Málek, Steinhauer** (2000)
- $r > \frac{6}{5}$  steady; **Frehse, Málek, Steinhauer** (2002)
- $r > \frac{6}{5}$  unsteady; **Diening, Růžička, Wolf** (2009)

# Power-law like fluid - implicit (discontinuous)

- $r \geq \frac{11}{5}$  - strict monotonicity - **Gwiazda, Málek, Świerczewska (2007)**
- $r > \frac{9}{5}$  - Herschel-Bulkley model - **Málek, Růžička, Shelukhin (2005)**
- $r > \frac{6}{5}$  steady - strict monotonicity - **Bulíček, Gwiazda, Málek, Świerczewska (2009)**
- $r > \frac{6}{5}$  unsteady; **Bulíček, Gwiazda, Málek, Świerczewska (2010)**

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- Fully Orlicz setting
- Fully implicit setting

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small problems if  $\psi$  does not satisfy  $\Delta_2$  condition
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- sequence of solutions  $v^n$ ;  $v^n - v$  is not possible test function
- introduce a Lipschitz function  $(v^n - v)_\lambda$  that is “closed” to to original
- previous work are based on the continuity of the Hardy-Littelwood maximal function in  $L^p$ - In Orlicz space setting one needs that  $\Delta_2$  conditions are satisfied and log continuity w.r.t.  $x$
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# Lipschitz approximation

## Lemma

$\{u^n\}_{n=1}^\infty$  tends strongly to  $\mathbf{0}$  in  $L^1$  and  $\{\mathbf{S}^n\}_{n=1}^\infty$  such that

$$\int_{\Omega} \psi^*(|\mathbf{S}^n|) + \psi(|\nabla u^n|) \, dx \leq C^* \quad (C^* > 1).$$

Then for arbitrary  $\lambda^* \in \mathbb{R}_+$  and  $k \in \mathbb{N}$  there exists  $\lambda^{\max} < \infty$  and there exists sequence of  $\{\lambda_n^k\}_{n=1}^\infty$  and the sequence  $u_k^n$  (going to zero) and open sets  $E_n^k := \{u_k^n \neq u^n\}$  such that  $\lambda_n^k \in [\lambda^*, \lambda^{\max}]$  and for any sequence  $\alpha_n^k$

$$u_k^n \in W^{1,p}, \quad \|\mathbf{D}(u_k^n)\|_\infty \leq C\lambda_n^k,$$

$$|\Omega \cap E_n^k| \leq C \frac{C^*}{\psi(\lambda_n^k)},$$

$$\int_{\Omega \cap E_n^k} |\mathbf{S}^n \cdot \mathbf{D}(u_k^n)| \, dx \leq CC^* \left( \frac{\alpha_n^k}{k} + \frac{\alpha_n^k \psi(\lambda_n^k / \alpha_n^k)}{\psi(\lambda_n^k)} \right)$$

# Use of Lipschitz approximation

- We have approximative problem  $(v^n, \mathbf{S}^n)$  and weak limits  $(v, \bar{\mathbf{S}})$ , we need to show that  $(\bar{\mathbf{S}}, \mathbf{D}(v)) \in \mathcal{A}$
- Test the approximative  $n$ - problem by Lipschitz approximation of  $v^n - v$ , i.e.,  $u_k^n := (v^n - v)_k$
- One gets (here  $\mathbf{S}$  is such that  $(\mathbf{S}, \mathbf{D}) \in \mathcal{A}$ )

$$\lim_{n \rightarrow \infty} \int_{u_k^n = u^n} (\mathbf{S}^n - \mathbf{S}) : \mathbf{D}(u_k^n) \leq CC^* \left( \frac{\alpha_n^k}{k} + \frac{\alpha_n^k \psi(\lambda_n^k / \alpha_n^k)}{\psi(\lambda_n^k)} \right)$$

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- $\varphi$  arbitrary nonnegative implies

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- Using **maximality** of the graph one gets

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# Future?????

- Extension to whole  $N$ - function setting, i.e.,  $\psi$  depends on whole  $\mathbf{D}$  and not only on  $|\mathbf{D}|$ , very hard
- Extension to “real”  $x$ -dependent setting, i.e., the growth estimates depends crucially on  $x$ , i.e., for models

$$\mathbf{S} \sim (1 + |\mathbf{D}|)^{r(c(x))-2} \mathbf{D},$$

where  $c$  satisfy convection diffusion problem.