Analysis and Numerics of Viscoelastic Phase Separation

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collaboration with: A. Brunk, B. Dünweg



• Typical model: Cahn-Hilliard-Navier-Stokes system (Model H)

$$\frac{\partial \phi}{\partial t} + \mathbf{u} \cdot \nabla \phi = \operatorname{div} (\phi^2 (1 - \phi^2) \nabla \mu)$$
$$\mu = -\gamma \Delta \phi + f'(\phi)$$
$$\frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{u} = \operatorname{div} (\eta(\phi) \mathrm{D} \mathbf{u}) - \nabla p + \nabla \phi \mu$$
$$\operatorname{div} (\mathbf{u}) = 0$$

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$$\begin{aligned} \frac{\partial \phi}{\partial t} + \mathbf{u} \cdot \nabla \phi &= \operatorname{div} \left(\phi^2 (1 - \phi^2) \nabla \mu \right) \\ \mu &= -\gamma \Delta \phi + f'(\phi) \\ \frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{u} &= \operatorname{div} \left(\eta(\phi) \mathrm{D} \mathbf{u} \right) - \nabla p + \nabla \phi \mu \\ \operatorname{div} \left(\mathbf{u} \right) &= 0 \end{aligned}$$



Figure: Simulation: Standard phase separation model

Phase separation of a polymeric fluid

Replacing one component by a polymer introduces new effects (transient gel)

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Replacing one component by a polymer introduces new effects (transient gel)

- Dynamic asymmetry of the components (slow and fast components)
- Relaxation effects for polymer and solvent on different timescales viscoelastic relaxation in pattern formation ⇒
- Transient network structure of slow phase
 ⇒ Flow through a porous medium (polymer network)
- Tanaka¹ proposed a concept of viscoelastic phase separation

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Experiments(PS/PVME) and simulations







Top: Tanaka's real experiments, Mid: 2D simulation, Bottom: 3D simulations via variational methods.

Literature overview

- Elliott, Garcke ('96) ... CH with degenerate mobilities
- Ables ('09) ... CH-NS
- Abels, Depner, Garcke ('13) ... CH-NS with degenerate mobilities
- Abels, Garcke, Grün ('12) ... two-phase model, different densities
- Cancés et al. ('19) ... CH as constrained Wasserstein gradient flow
- Grün, Metzger ('16) ... micro-macro models two-phase, dilute polymers

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- Grün, Metzger ('16) ... micro-macro models two-phase, dilute polymers
- Barrett, Boyaval ('09) ... existence, regularized Oldroyd-B
- Barrett, Süli ('12-'18) ... existence diffusive Oldroyd-B
- Lei, Masmoudi. Zhou ('05) ... blow-up criterion
- Chupin ('18) ... strong sols.
- Constantin, Kriegl ('12) ... global regularity in 2D
- Geissert et al. ('12) ... strong sols.
- Lu, Zhang ('18) ... relative energy
- Zhang, Fang ('12) ... global strong sol. in critical L^p spaces
- Bathory, Bulíček, Málek ('24) . . . existence, NSF & Johnson-Segalman stress-diffusive viscoelastic model
- Bulíček, Málek, Průša, Süli ('21) ... incomp. heat-conducting stress-diffusive rate-type model
- Bulíček, Los, Málek ('25) ... 3D Giesekus models

Macro Model

- ϕ polymer volume fraction $((1 \phi)$ solvent volume fraction)
- q bulk stress related to polymer effects
- σ viscoelastic stress
- $\bullet~\mathbf{u}$ volume-averaged velocity of polymers and solvents

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Variational principle: minimizing the total energy

$$E = F(\phi) + \int \frac{1}{2}q^2 + \int \frac{1}{2}\mathrm{Tr}(\sigma) + \int \frac{1}{2}|u|^2, \quad \frac{d}{dt}E \leq 0$$

 $\bullet \ F(\phi) \ \ldots \ {\rm free \ energy}$

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 $\bullet \ F(\phi) \ \ldots \ {\rm free \ energy}$

$$F(\phi) = \int f(\phi) + \frac{\gamma}{2} |\nabla \phi|^2 dx$$

Viscoelastic phase separation I [Zhou, Zhang and E ('06)]

- ϕ polymer volume fraction $((1 \phi)$ solvent volume fraction)
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$$\partial_t \phi + \mathbf{u} \cdot \nabla \phi = \operatorname{div}\left(\overbrace{\phi^2(1-\phi)^2}^{n(\phi)} \nabla \mu\right) - \operatorname{div}\left(\overbrace{\phi(1-\phi)}^{n(\phi)} \nabla \left(A(\phi)q\right)\right)$$
$$\mu = -c_0 \Delta \phi + f'(\phi)$$
$$\partial_t q + \mathbf{u} \cdot \nabla q = -\frac{1}{\tau_b(\phi)}q + A(\phi)\Delta \left(A(\phi)q\right) - A(\phi)\operatorname{div}\left(\overbrace{\phi(1-\phi)}^{n(\phi)} \nabla \mu\right)$$
$$\partial_t \mathbf{u} + (\mathbf{u} \cdot \nabla)\mathbf{u} = \operatorname{div}\left(\eta(\phi)\mathrm{D}\mathbf{u}\right) - \nabla p + \operatorname{div}\boldsymbol{\sigma} - \operatorname{div}\left(\gamma\nabla\phi\otimes\nabla\phi\right)$$
$$\operatorname{div}\left(\mathbf{u}\right) = 0$$
$$\partial_t\boldsymbol{\sigma} + (\mathbf{u} \cdot \nabla)\boldsymbol{\sigma} = (\nabla\mathbf{u})\boldsymbol{\sigma} + \boldsymbol{\sigma}(\nabla\mathbf{u})^{\top} - \frac{1}{\tau_s(\phi)}\boldsymbol{\sigma} + B(\phi)\mathrm{D}\mathbf{u}$$

$$E(\phi, q, \mathbf{u}, \boldsymbol{\sigma}) = \int \frac{\gamma}{2} |\nabla \phi|^2 + f(\phi) + \frac{1}{2} |q|^2 + \frac{1}{2} |\mathbf{u}|^2 + \frac{1}{2} \operatorname{tr}(\boldsymbol{\sigma}).$$

Viscoel. phase separation II [Brunk, ML (Nonlinerity '22)]

$$\partial_{t}\phi + \mathbf{u} \cdot \nabla\phi = \operatorname{div}(m(\phi)\nabla\mu) - \operatorname{div}(n(\phi)\nabla(A(\phi)q))$$

$$\mu = -\gamma\Delta\phi + f'(\phi)$$

$$\partial_{t}q + \mathbf{u} \cdot \nabla q = -\frac{1}{\tau(\phi)}q + A(\phi)\Delta(A(\phi)q) - A(\phi)\operatorname{div}(n(\phi)\nabla\mu) + \varepsilon_{1}\Delta q$$

$$\partial_{t}\mathbf{u} + (\mathbf{u} \cdot \nabla)\mathbf{u} = \operatorname{div}(\eta(\phi)\mathbf{D}\mathbf{u}) - \nabla p + \operatorname{div}\operatorname{tr}(\mathbf{C})\mathbf{C} - \operatorname{div}(\gamma\nabla\phi\otimes\nabla\phi)$$

$$\operatorname{div}(\mathbf{u}) = 0$$

$$\partial_{t}\mathbf{C} + (\mathbf{u} \cdot \nabla)\mathbf{C} = (\nabla\mathbf{u})\mathbf{C} + \mathbf{C}(\nabla\mathbf{u})^{\top} - h(\phi)\operatorname{tr}(\mathbf{C})[\operatorname{tr}(\mathbf{C})\mathbf{C} - \mathbf{I}] + \varepsilon_{2}\Delta\mathbf{C}$$

 \bullet viscoelastic stress tensor $\qquad \mathbf{T} = \mathrm{tr}\left(\mathbf{C}\right)\mathbf{C} - \mathbf{I}$

$$E(\phi, q, \mathbf{u}, \mathbf{C}) = \int_{\Omega} \frac{\gamma}{2} |\nabla \phi|^2 + f(\phi) + \frac{1}{2} |q|^2 + \frac{1}{2} |\mathbf{u}|^2 + \frac{1}{4} \operatorname{tr} \left(\operatorname{tr} \left(\mathbf{T} \right) - 2 \ln \mathbf{C} \right)$$
$$E(t) + \int_0^t D(s) \, ds \le E(0)$$

• additional energy functional (Lyapunov functional)

$$E = \int_{\Omega} \frac{\gamma}{2} |\nabla \phi|^2 + f(\phi) + \frac{1}{2} |q|^2 + \frac{1}{2} |\mathbf{u}|^2 + \frac{1}{4} |\mathbf{C}|^2 \, \mathrm{dx}$$

with energy dissipation

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$$E(t) + \int_0^t \int_\Omega \left(\sqrt{m(\phi)}\nabla\mu - \nabla(A(\phi)q)\right)^2 + \varepsilon_1 |\nabla q|^2 + \eta(\phi)|\mathbf{D}(\mathbf{u})|^2 + \int_0^t \int_\Omega \frac{q^2}{\tau(\phi)} + \frac{\varepsilon_2}{2}|\nabla \mathbf{C}|^2 + \frac{1}{2}h(\phi)\mathrm{tr}(\mathbf{C})^2|\mathbf{C}|^2 - \frac{1}{2}h(\phi)\mathrm{tr}(\mathbf{C})^2 = E(0)$$

Well-posedness

► Well-posedness

- Existence of solutions
- Oniqueness of solution
- Solution depends continuously on data

Well-posedness

Well-posedness

- Existence of solutions weak solutions
- Oniqueness of solution
- Solution depends continuously on data

Existence [Brunk, M.L. (Nonlinearity 2022)]

There exists at least one global weak dissipative solution, in *two space dimensions*, which satisfies the integrated energy inequality.

Existence/ regular & singular case

Regular case

- All parametric functions are continuous and positively bounded
- A(s) is allowed to be zero somewhere
- mobility functions m(s), n(s)

$$0 < m_1 \le m(s) = n(s) \le 1$$
,

- mixing potential f(s) is polynomial (Ginzburg-Landau) potential, e.g. $f(s) = (s-1)^2 s^2$

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Singular case

• mobility functions m(s), n(s) = 0 if and only if $x \in \{0, 1\}$

$$m(s) = n(s)^2$$

• mixing potential f(s) is logarithmic (Flory-Huggins) potential

Weak solutions

▶ Brunk, ML (Nonlinearity '22)

For given initial conditions

$$(\phi_0, q_0, \mathbf{u}_0, \mathbf{C}_0) \in \left[H^1(\Omega) \times L^2(\Omega) \times L^2_{\sigma}(\Omega) \times (L^2(\Omega))^{2 \times 2} \right]$$

there exists a global weak solution of the regular problem with

$$\begin{split} \phi &\in L^{\infty}(0,T;H^{1}(\Omega)) \cap L^{2}(0,T;H^{2}(\Omega)), & \frac{\partial \phi}{\partial t} \in L^{2}(0,T;H^{-1}(\Omega)) \\ \mathbf{u} &\in L^{\infty}(0,T;L^{2}_{\sigma}(\Omega)) \cap L^{2}(0,T;H^{1}_{0,\sigma}(\Omega)), & \frac{\partial \mathbf{u}}{\partial t} \in L^{2}(0,T;H^{-1}_{0,\sigma}(\Omega)) \\ \mathbf{C}, q &\in L^{\infty}(0,T;L^{2}(\Omega)) \cap L^{2}(0,T;H^{1}(\Omega)), & \frac{\partial q}{\partial t}, \frac{\partial \mathbf{C}}{\partial t} \in L^{\frac{4}{3}}(0,T;H^{-1}(\Omega)) \\ \mu &\in L^{2}(0,T;H^{1}(\Omega)), \end{split}$$

which obey the energy inequality

Existence of global weak dissipative solutions

- Existence of solutions 2D \checkmark
- Ø Main problem

$$\frac{1}{2}\left[\nabla \mathbf{u}\mathbf{C} + \mathbf{C}(\nabla \mathbf{u})^T\right] : \mathbf{C} \neq \mathsf{tr}(\mathbf{C})\mathbf{C} : \nabla \mathbf{u} \text{ in } 3\mathsf{D}$$

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- ② Existence of solutions in 3D:
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We only have

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Existence, regularity & weak-strong uniqueness for the Peterlin model in 3D ... Brunk, M.L., Lu: Commun. Math. Sci. 2022

Extension to a reduced viscoelastic phase separation model in 3D ... Brunk: DCDS 2022

Relative energy

● Uniqueness of solution → *weak-strong uniqueness*

Solution depends continuously on data — stability estimate

Relative energy

Relative energy

- Uniqueness of solution → weak-strong uniqueness
- 2 Solution depends continuously on data \longrightarrow *stability estimate*

Let E(z) be a convex energy, then the relative energy is given by

$$\mathcal{E}(z|\hat{z}) := E(z) - E(\hat{z}) - \left\langle \frac{\delta E}{\delta z}(\hat{z}), z - \hat{z} \right\rangle$$

- for non-convex double-well potential add a penalty term
- f is λ -convex if $f(z) + \lambda |z|^2$ is convex for some $\lambda > 0$
- for d=2

$$\mathcal{E}(z|\hat{z}) := \int_{\Omega} \frac{\gamma}{2} |\nabla(\phi - \hat{\phi})|^2 + f(\phi) - f(\hat{\phi}) - f'(\hat{\phi})(\phi - \hat{\phi}) \\ + \frac{\alpha}{2} |\phi - \hat{\phi}|^2 + \frac{1}{2} |q - \hat{q}|^2 + \frac{1}{2} |\mathbf{u} - \hat{\mathbf{u}}|^2 + \frac{1}{4} |\mathbf{C} - \hat{\mathbf{C}}|^2$$

 $\alpha > \lambda := \max\{\gamma, \gamma - \min f^{''}\}$

Relative energy

► Relative energy

Uniqueness of solution — weak-strong uniqueness

- 2 Solution depends continuously on data \longrightarrow *stability estimate*
- ▶ Weak-strong uniqueness [Brunk, ML (ZAMM 2022)]

Compare a weak solution z with a more regular (strong) solution \hat{z} starting from the same initial data

$$\mathcal{E}(z|\hat{z})(t) + \mathcal{D}(t) \le c(t)\mathcal{E}(z|\hat{z})(0) = 0$$

$$\mathcal{D} = \frac{1}{2} \int_0^t \int_{\Omega} |n(\phi)\nabla(\mu - \hat{\mu}) - \nabla(A(\phi)(q - \hat{q}))|^2 + \frac{1}{\tau(\phi)}|q - \hat{q}|^2 + \varepsilon_1 |\nabla(q - \hat{q})|^2 + \eta(\phi)|\mathbf{D}\mathbf{v} - \mathbf{D}\hat{\mathbf{v}}|^2 + \frac{\varepsilon_2}{2}|\nabla(\mathbf{C} - \hat{\mathbf{C}})|^2 + h(\phi)\Phi(\operatorname{tr}(\mathbf{C}))\operatorname{tr}(\mathbf{C})|\mathbf{C} - \hat{\mathbf{C}}|^2 dx dt'$$

$$\Rightarrow z = \hat{z} \text{ weak-strong uniqueness}$$

Compare a weak solution z with arbitrary functions \hat{z} :

$$\mathcal{E}(z|\hat{z})(t) + \mathcal{D}(t) \le e^{c(t)} \mathcal{E}(z|\hat{z})(0) + Ce^{c(t)} \int_0^t \sum_{i=1}^5 ||r_i||_*^2.$$

• residuals r_i study parameter changes, asymptotic limits, coarse-graining errors for a hierarchy of models (relative entropy) and convergence of numerical schemes

Error estimates I

 rigorous error estimate for the Cahn-Hilliard equation through the relative energy: Brunk, Egger, Habrich, ML: M²AN'23

$$\mathcal{E}(z|\hat{z}) := \int \frac{\gamma}{2} |\nabla(\phi - \hat{\phi})|^2 + f(\phi) - f(\hat{\phi}) - f'(\hat{\phi})(\phi - \hat{\phi}) + \frac{\alpha}{2} |\phi - \hat{\phi}|^2$$

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- periodic BC, second order conforming finite elements
- Cranck-Nicolson-type in time

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- periodic BC, second order conforming finite elements
- Cranck-Nicolson-type in time
- Let (ϕ, μ) be a regular periodic weak solution with $\phi_0 \in H^3(\Omega)$ s.t.

$$\begin{split} \phi &\in H^2(0,T; H^1(\Omega)) \cap H^1(0,T; H^3(\Omega)), \\ \mu &\in H^2(0,T; H^1(\Omega)) \cap L^{\infty}(0,T; W^{1,3}(\Omega)). \end{split}$$

and let $(\phi_{h,\tau}, \mathbf{u}_{h,\tau})$ be a solution of FEM.

Then

$$\max_{t^n} \|\phi_{h,\tau}(t^n) - \phi(t^n)\|_{H^1} + \left\|\overline{\mu}_{h,\tau} - \overline{\mu}\right\|_{L^2(0,T;H^1)} \le C_T(h^2 + \tau^2)$$

Error estimates II

- error estimates for Navier-Stokes-Cahn-Hilliard system: Brunk, Egger, Habrich, ML: M³AS 2023
- \bullet Taylor-Hood (P2/P1) finite elements for the velocity and pressure
- \bullet P2 finite elements for ϕ,μ
- two-, three-dimensional model, periodic BC

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- Taylor-Hood (P2/P1) finite elements for the velocity and pressure
- P2 finite elements for ϕ, μ
- two-, three-dimensional model, periodic BC

Let (ϕ,μ,\mathbf{u},p) is a regular sol., s.t.

$$\begin{split} \phi &\in H^2(0,T;H^1(\Omega)) \cap H^1(0,T;H^3(\Omega)), \quad \mu \in H^2(0,T;H^1(\Omega)) \cap L^2(0,T;H^3(\Omega)) \\ \mathbf{u} &\in H^2(0,T;H^1(\Omega)) \cap H^1(0,T;H^3(\Omega)), \quad p \in L^2(0,T;H^2(\Omega)) \cap H^2(0,T;L^2(\Omega)) \end{split}$$

Then

$$\|\phi_{h,\tau} - \phi\|_{L^{\infty}_{t}, H^{1}_{x}} + \|\overline{\mu}_{h,\tau} - \overline{\mu}\|_{L^{2}_{t}, H^{1}_{x}} + \\ \|\mathbf{u}_{h,\tau} - \mathbf{u}\|_{L^{\infty}_{t}, L^{2}_{x}} + \|\overline{\mathbf{u}}_{h,\tau} - \overline{\mathbf{u}}\|_{L^{\infty}_{t}, L^{2}_{x}} \le C(T)(h^{2} + \tau^{2})$$

 $\overline{\mathbf{u}}$... p.w. constant projection in time on (t^n,t^{n+1})

Error estimates III

- error estimates for Cahn-Hilliard model with bulk stress *q*: Brunk, Egger, Habrich, ML: ArXiv 2024
- P2 finite elements for ϕ, μ, q
- two-, three-dimensional model, periodic BC
 - Let (ϕ, μ, q) is a regular sol., s.t.

$$\begin{split} \phi &\in H^2(0,T;H^1(\Omega)) \cap H^1(0,T;H^3(\Omega)), \\ \mu &\in H^2(0,T;H^1(\Omega)) \cap L^{\infty}(0,T;W^{1,3}(\Omega)) \cap L^2(0,T;H^3(\Omega)) \\ q &\in H^2(0,T;H^1(\Omega)) \cap L^{\infty}(0,T;W^{1,3}(\Omega)) \cap L^2(0,T;H^3(\Omega)) \end{split}$$

$$\begin{aligned} \|\phi_{h,\tau} - \phi\|_{L^{\infty}_{t},H^{1}_{x}} + \|q_{h,\tau} - q\|_{L^{\infty}_{t},L^{2}_{x}} + \left\|\overline{\mu}_{h,\tau} - \overline{\mu}\right\|_{L^{2}_{t},H^{1}_{x}} + \\ \left\|\overline{q}_{h,\tau} - \overline{q}\right\|_{L^{2}_{t},H^{1}_{x}} \le C(T)(h^{2} + \tau^{2}) \end{aligned}$$

 $\overline{q}\,\ldots\,$ p.w. constant projection in time on (t^n,t^{n+1})

Cahn-Hilliard eq.

- potential $f(\phi) = \frac{3}{2}(\phi \log(\phi) + (1 - \phi)\log(1 - \phi) + 3\phi(1 - \phi))$ $\phi_0(x, y) = 0.1\sin(4\pi x)\sin(2\pi y) + 0.6$



Table: Errors and convergence rates for the semi-discrete and fully-discrete approximations

$k \mid$	e_h	eoc	$e_{h,\tau}$	eoc
0	$5.9075 \cdot 10^{-1}$	—	$5.9426 \cdot 10^{-1}$	—
1	$1.7016 \cdot 10^{-1}$	1.80	$1.7109 \cdot 10^{-1}$	1.79
2	$4.3761 \cdot 10^{-2}$	1.96	$4.4155 \cdot 10^{-2}$	1.95
3	$1.1038 \cdot 10^{-2}$	1.99	$1.1251 \cdot 10^{-2}$	1.97
4	$2.7658 \cdot 10^{-3}$	2.00	$3.3468 \cdot 10^{-3}$	1.74

- Cahn-Hilliard and *q*-equation initial data:

$$\begin{split} \phi_0(x,y) &= 0.25\cos(2\pi x)\cos(2\pi y) + 0.5, \quad q_0(x,y) = 0.01\sin(2\pi x)\sin(2\pi y).\\ \gamma &= 10^{-3}\\ M(\phi) &= [\frac{4}{\sqrt{10}} \cdot \phi(1-\phi)]^2 + \varepsilon, \ f(\phi) &= (\phi - 0.95)^2(\phi - 0.05)^2,\\ \tau_b(\phi) &= 10^2(10\phi^2 + 10^{-4}), \text{ and}\\ A(\phi) &= 5 \cdot 10^{-3} \cdot \left[1 + \tanh(5[\cot(\pi\phi^*) - \cot(\pi\phi)])\right] \end{split}$$

with $\phi^* = \int_\Omega \phi_0$ denoting the total mass



Convergence rates for the errors in ϕ (top left), $\bar{\mu}$ (top right), q (middle left), \bar{q} (middle right) and the combined error (bottom) for different ε

Viscoelastic separation

- Cahn-Hilliard and *q*-equation initial data:

$$\begin{split} \phi_0(x,y) &= 0.4 + \xi(x,y), \quad q_0 = 0, \quad \xi(x,y) \sim \mathcal{U}[-0.0025, 0.0025] \\ \gamma &= \varepsilon = 10^{-3}, \quad f(\phi) = (\phi - 0.95)^2 (\phi - 0.05)^2 \end{split}$$

$$A(\phi) = \frac{1}{2} \left[1 + \tanh(10[\cot(\pi\phi^*) - \cot(\pi\phi)]) \right], \quad \phi^* = \int_{\Omega} \phi_0$$



Snapshots of the volume fraction ϕ with pure phases at $\phi = 0$ and $\phi = 1$ M. Lukáčová -Medviďová (Johannes Gutenberg University of Mainz): Analysis and Numerics of Viscoelastic Phase Separation



Full viscoelastic separation

• characteristic FEM

•
$$\phi_0(x) = 0.4 + \xi(x), q_0 = 0, \mathbf{u}_0 = \mathbf{0}, \mathbf{C}_0 = \frac{1}{\sqrt{2}}\mathbf{I}$$

 $\xi(x) \text{ from } [-10^{-3}, 10^{-3}]$



Full viscoelastic separation

• $\phi_0(x) = 0.4 + 0.2 \sin\left(\frac{2\pi x}{128}\right) \sin\left(\frac{2\pi y}{128}\right), q_0 = 0, \mathbf{u}_0 = \mathbf{0}, \mathbf{C}_0 = \frac{1}{\sqrt{2}}\mathbf{I}$



$$\begin{aligned} \frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{u} &= \operatorname{div}(\eta \mathrm{D}\mathbf{u}) - \nabla p + \operatorname{div}(\mathbf{T}), \\ \frac{\partial \mathbf{C}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{C} &= (\nabla \mathbf{u}) \mathbf{C} + \mathbf{C} (\nabla \mathbf{u})^{\top} \\ &+ \Phi(\operatorname{tr}(\mathbf{C})) \mathbf{I} - \chi(\operatorname{tr}(\mathbf{C})) \mathbf{C} + \varepsilon \Delta \mathbf{C}, \\ \operatorname{div}(\mathbf{u}) &= 0, \quad \mathbf{T} &= \operatorname{tr}(\mathbf{C}) \mathbf{C}. \end{aligned}$$

• $\Phi:=\mathrm{tr}(\mathbf{C})+a$ and $\chi:=\mathrm{tr}(\mathbf{C})^2+a|\mathrm{tr}(\mathbf{C})|$ for a given $a\geq 0$

Weak dissipative sol. in 3D / Peterlin model

Theorem (Brunk, ML, Lu (DCDS'22))

• initial data $(\mathbf{u}_0, \mathbf{C}_0) \in [L^2_{\sigma} \times L^2(\Omega)^{3 \times 3}_{SPD}]$, T > 0. There exists a global weak solution of the Peterlin system, s.t.

$$\begin{split} \mathbf{u} &\in C_w([0,T]; L^2(\Omega)) \cap L^2(0,T; V) \cap C([0,T]; L^q(\Omega)) \cap W^{1,\frac{4}{3}}(0,T; V^*), \\ \mathbf{C} &\in C_w([0,T]; L^2(\Omega)) \cap L^2(0,T; H^1(\Omega)) \cap L^4(\Omega_T) \\ &\quad \cap C([0,T]; L^q(\Omega)) \cap W^{1,\frac{4}{3}}(0,T; H^{-1}(\Omega)), \\ &\quad \chi(\operatorname{tr}(\mathbf{C}))\mathbf{C} \in L^{\frac{4}{3}}(\Omega_T), \qquad \Phi(\operatorname{tr}(\mathbf{C})) \in L^2(\Omega_T), \quad \text{for any } 1 \leq q < 2 \end{split}$$

Weak dissipative sol. in 3D / Peterlin model

Theorem (Brunk, ML, Lu (DCDS'22))

• initial data $(\mathbf{u}_0, \mathbf{C}_0) \in [L^2_{\sigma} \times L^2(\Omega)^{3 \times 3}_{SPD}]$, T > 0. There exists a global weak solution of the Peterlin system, s.t.

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• the energy inequality holds a.e. $t\in(0,T)$

$$\begin{split} &\left(\int_{\Omega} \frac{1}{2} |\mathbf{u}(t)|^2 + \frac{1}{4} |\operatorname{tr}(\mathbf{C}(t))|^2 \,\mathrm{dx}\right) + \int_{0}^{t} \int_{\Omega} \eta |\mathrm{D}\mathbf{u}|^2 + \frac{\varepsilon}{2} |\nabla \operatorname{tr}(\mathbf{C})|^2 \,\mathrm{dx} \,\mathrm{d\tau} + \\ &\int_{0}^{t} \int_{\Omega} \frac{1}{2} |\operatorname{tr}(\mathbf{C})|^4 + \frac{a}{2} |\operatorname{tr}(\mathbf{C})|^3 \,\mathrm{dx} \,\mathrm{d\tau} \\ &\leq \int_{0}^{t} \int_{\Omega} \frac{1}{2} |\operatorname{tr}(\mathbf{C})|^2 + \frac{a}{2} \operatorname{tr}(\mathbf{C}) \,\mathrm{dx} \,\mathrm{d\tau} + \left(\int_{\Omega} \frac{1}{2} |\mathbf{u}(0)|^2 + \frac{1}{4} |\operatorname{tr}(\mathbf{C}(0))|^2\right) \end{split}$$

- If a = 0 the conformation tensor C is symmetric positive semi-definite
- If a > 0 and $tr(\log \mathbf{C}_0) \in L^1(\Omega)$ then $\tilde{\mathbf{C}}$ is symmetric positive definite and

$$\operatorname{tr}(\log \mathbf{C}) \in L^{\infty}(0,T;L^{1}(\Omega)) \cap L^{2}(0,T;H^{1}(\Omega)),$$

$$\operatorname{tr}(\mathbf{C}^{-1}),\operatorname{tr}(\mathbf{C}^{-1})\operatorname{tr}(\mathbf{C}) \in L^{1}(0,T;L^{1}(\Omega)).$$

$$\left(\int_{\Omega} \frac{1}{2} |\mathbf{u}(t)|^2 + \frac{1}{4} |\operatorname{tr}(\mathbf{C}(t))|^2 - \frac{1}{2} \operatorname{tr}(\log \mathbf{C}(t)) \, \mathrm{dx} \right)$$

$$+ \int_0^t \int_{\Omega} \eta |\mathrm{D}\mathbf{u}|^2 + \frac{\varepsilon}{2} |\nabla \operatorname{tr}(\mathbf{C})|^2 + \frac{\varepsilon}{6} |\nabla \operatorname{tr}(\log \mathbf{C})|^2 + \frac{1}{2} \chi(\operatorname{tr}(\mathbf{C})) \operatorname{tr}(\mathbf{T} + \mathbf{T}^{-1} - 2\mathbf{I}) \, \mathrm{dx} \, \mathrm{d\tau}$$

$$\leq \left(\int_{\Omega} \frac{1}{2} |\mathbf{u}(0)|^2 + \frac{1}{4} |\operatorname{tr}(\mathbf{C}(0))|^2 - \frac{1}{2} \operatorname{tr}(\log \mathbf{C}(0)) \, \mathrm{dx} \right).$$

Hybrid kinetic-macroscopic model

Fokker-Planck equation for the viscoelastic part

$$\begin{split} \partial_t \phi + \mathbf{u} \cdot \nabla_{\mathbf{x}} \phi &= \operatorname{div}_{\mathbf{x}} \left((1 + \varepsilon_0) m(\phi) \nabla_{\mathbf{x}} \mu - m^{1/2}(\phi) \nabla_{\mathbf{x}} \left(A(\phi) q \right) \right), \\ \mu &= -\gamma \Delta_{\mathbf{x}} \phi + f'(\phi), \\ \partial_t q + \mathbf{u} \cdot \nabla_{\mathbf{x}} q &= -\frac{1}{\tau(\phi)} q + \varepsilon_1 \Delta_{\mathbf{x}} q + A(\phi) \operatorname{div}_{\mathbf{x}} \left(\nabla_{\mathbf{x}} \left(A(\phi) q \right) - m^{1/2}(\phi) \nabla_{\mathbf{x}} \mu \right), \\ \partial_t \mathbf{u} + \left(\mathbf{u} \cdot \nabla_{\mathbf{x}} \right) \mathbf{u} &= \operatorname{div}_{\mathbf{x}} \left(\eta(\phi) \mathbf{D}_{\mathbf{x}} \mathbf{u} - p \mathbf{I} + \mathbf{T}(\psi) \right) - \phi \nabla_{\mathbf{x}} \mu, \\ \operatorname{div}_{\mathbf{x}} (\mathbf{u}) &= 0, \\ \mathbf{T}(\psi) &= \gamma_3(\langle |\mathbf{R}|^2 \rangle) \langle \mathbf{R} \otimes \mathbf{R} \rangle, \\ \partial_t \psi + \mathbf{u} \cdot \nabla_{\mathbf{x}} \psi + \operatorname{div}_{\mathbf{R}} \left(\nabla_{\mathbf{x}} \mathbf{u} \mathbf{R} \psi \right) \\ &= \gamma_2(\phi, \langle |\mathbf{R}|^2 \rangle) \Delta_{\mathbf{R}} \psi + \operatorname{div}_{\mathbf{R}} \left(\gamma_1(\phi, \langle |\mathbf{R}|^2 \rangle) \mathbf{R} \psi \right) + \varepsilon_2 \Delta_{\mathbf{x}} \psi \end{split}$$

 $\gamma_1,\gamma_2,\gamma_3$ are connected to the functions χ,Φ in the Peterlin model

$$\langle f \rangle \equiv \int_{R^3} f(\mathbf{R}) \psi(\mathbf{x}, t, \mathbf{R}) d\mathbf{R} \dots \psi$$
 is the probability density distribution $\mathbf{C}(\psi) \equiv \langle \mathbf{R} \otimes \mathbf{R} \rangle$

Existence of weak solutions for the kinetic system

