

Variational aspects of fluid-structure interaction based on joint work¹ with B. Benešová & S.Schwarzacher

Malte Kampschulte

Mathematisches Institut
Fakultät für Mathematik und Informatik
Universität Leipzig

Katedra matematické analýzy
Matematicko-fyzikální fakulta
Univerzita Karlova Praha

Modelling, PDE Analysis and computational mathematics in materials science
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CHARLES
UNIVERSITY



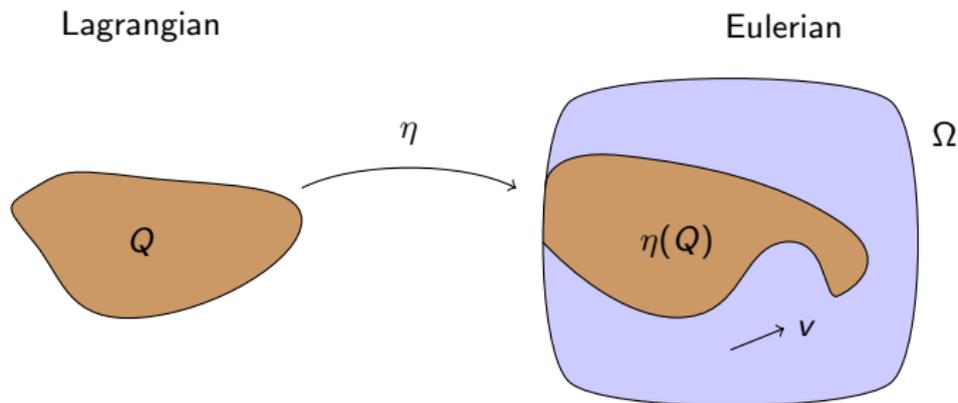
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MINISTRY OF EDUCATION,
YOUTH AND SPORTS

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Fluid structure interaction



System of equations

$$\left\{ \begin{array}{ll} \rho_s \partial_t^2 \eta + DE(\eta) + D_2 R(\eta, \partial_t \eta) = f_s & \text{in } Q \\ \rho_f (\partial_t + v \cdot \nabla) v - \nu \Delta v + \nabla p = f_f & \text{in } \Omega(t) := \Omega \setminus \eta(t, Q) \\ \nabla \cdot v = 0 & \text{in } \Omega(t) \\ v \circ \eta = \partial_t \eta & \text{in } \partial Q \end{array} \right.$$

+ equivalence of forces at the interface + boundary & initial data.

Sources of nonlinearities & nonconvexities

$$\begin{cases} \rho_s \partial_t^2 \eta + DE(\eta) + D_2 R(\eta, \partial_t \eta) = f_s & \text{in } Q \\ \rho_f (\partial_t + v \cdot \nabla) v - \nu \Delta v + \nabla p = f_f & \text{in } \Omega(t) \\ v \circ \eta = \partial_t \eta & \text{in } \partial Q \end{cases}$$

In the equation

- ▶ Transport terms $(\partial_t + v \cdot \nabla)v$
- ▶ Large strain elasticity DE (in general)
- ▶ Injectivity constraints $\det \nabla \eta > 0$

In boundary/coupling conditions

- ▶ Change between Lagrangian and Eulerian reference $v \circ \eta = \partial_t \eta$

In the domain itself

- ▶ $\Omega(t) := \Omega \setminus \eta(Q, t)$, $v : \Omega(t) \rightarrow \mathbb{R}^n$

The three regimes of continuum mechanics

Static (\neq stationary)

Goal: Find a stable stationary point of the potential energy

$$DE(\eta) = f_s, \quad v = 0$$

- ▶ Clear formulation as **minimization problem**
- ▶ Extremely well studied, mostly from **variational** point of view

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Quasistatic

Goal: Evolve slowly, trading energy against dissipation

$$D_2R(\eta, \partial_t \eta) + DE(\eta) = f_s, \quad -\nu \Delta v + \nabla p = f_f$$

- ▶ **Gradient flow structure**
- ▶ Amenable to variational methods (**Minimizing movements**)

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Dynamic (inertial)

Goal: Evolve at higher speeds, where conservation of momentum becomes significant

$$\rho_s \partial_{tt} \eta + D_2R(\eta, \partial_t \eta) + DE(\eta) = f_s, \quad \rho_f (\partial_t + v \cdot \nabla) v - \nu \Delta v + \nabla p = f_f$$

- ▶ Variational structure sometimes present, but not in form of minimizers
- ▶ Classically the **realm of PDE methods**, which **do not cope well with non-convexity**

Time-delayed approach [Benešová, K., Schwarzacher '24]

Time-delayed equation

Why not solve

$$\rho \frac{\partial_t \eta - \partial_t \eta(\cdot - h)}{h} + DE(\eta) + D_2 R(\eta, \partial_t \eta) = \text{forces} \quad (\text{TD})$$

instead?

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General plan

- ▶ On $[0, h]$: treat $\rho \frac{\partial_t \eta(\cdot - h)}{h}$ as fixed data and $\rho \frac{\partial_t \eta}{h} = D_{\partial_t \eta} \int_Q \frac{\rho}{h} |\partial_t \eta|^2 dx$

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 \Rightarrow solution on $[0, h]$ via minimizing movements
- ▶ Testing (TD) with $\partial_t \eta$ (or using De Giorgi estimate) gives

$$\int_{t-h}^t \frac{\rho}{2} \|\partial_t \eta\|^2 dt + E(\eta(t)) + \int_0^t R + R^* dt \leq E(\eta_0) + \int_{0-h}^0 \frac{\rho}{2} \|\partial_t \eta\|^2 dt + W_{\text{forces}}$$

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\Rightarrow allows to iterate on $[h, 2h], [2h, 3h], \dots$

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- ▶ Energy estimate telescopes and is uniform in h
 \Rightarrow limit $h \rightarrow 0$ is possible on the level of the PDE

An existence result

Theorem [Benešová, K., Schwarzacher '24]

Assume that E and R satisfy some conditions and Q and Ω are regular enough. Then **there exists a weak solution to the full bulk FSI-problem** up until the first (self-)contact of the solid. Additionally the solution obeys an energy inequality.

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¹Terms and conditions apply:

- ▶ Energy $E : W^{2,q} \rightarrow \mathbb{R}$, $q > n$ is coercive, weakly lsc., bounded from below, DE exists, has some sort of continuity as well as a Minty-type property, E finite implies $\det \nabla \eta > 0$ uniformly
- ▶ Dissipation R is 2-homogeneous, weakly lsc., has a Korn inequality for bounded energies, $D_2 R$ exists and has some sort of continuity
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Covers a large class of physical reasonable materials. In particular E and space of deformations can be highly non-convex.

Closing remarks

Some other results using the method

- ▶ **Existence for compressible, bulk FSI** [Breit, K., Schwarzacher '24]
- ▶ Poroelasticity [Benešová, K., Schwarzacher '23]
- ▶ Thin solids [K., Schwarzacher, Sperone '23]
- ▶ FSI past contact [K., Muha, Trifunović '24]
- ▶ **Solid-solid collisions** [Češík, Gravina, K. '24a/b (to appear)]
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Other aspects

- ▶ The method is connected to an **energetical modelling procedure** (Energy+Dissipation+kinematics \Rightarrow weak/measure valued-solution)
- ▶ The method is well suited to coupling different problems (**Fluid-structure interaction**, multiphysics)
- ▶ Many possible applications in progress/still unexplored

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Thank you for your attention.