

Symbol of differential operators

Definition A smooth vector bundle of dimension n is a triple

(E, M, π) (or $\pi: E \rightarrow M$) where

(VB1) E is a smooth manifold of dimension $m+n$,

(VB2) M is a --- m ,

(VB3) $\pi: E \rightarrow M$ is smooth map such that for every $x \in M$ the preimage $\pi^{-1}(x)$ is a real vector space of dimension n

which satisfies the following local triviality condition:

(LTC) $\forall x \in M$ there exists an open set $U_x \subseteq M$ together with a diffeomorphism

$$\Phi_x: U_x \times \mathbb{R}^n \rightarrow \pi^{-1}(U_x)$$

such that for every $x' \in U_x$ we have that

$$\Phi_x(x', v) \in \pi^{-1}(x')$$

and that the map

$$\mathbb{R}^n \ni v \mapsto \Phi_x(x', v) \in \pi^{-1}(x')$$

is a linear isomorphism.

The space E is called the total space, M is called the base and π is called the canonical projection.

Remark: $E = \bigcup_{x \in M} \mathbb{R}^n$ and locally E looks as the product $U_x \times \mathbb{R}^n$. However E need not be a global product $M \times \mathbb{R}^n$.

Example: If M is a smooth manifold, then TM, T^*M are smooth vector bundles of dimension n over M . Here TM as a vector bundle is (TM, M, π_{TM}) . Other examples are $\Lambda^k T^*M, T^{k,l}M$ for $k=0,1,\dots, l=0,1,\dots$.

Definition Let (E, M, π) be a vector bundle of dimension n .

Then a section of (E, M, π) is a smooth map

$$s: M \rightarrow E \text{ such that } \pi \circ s: M \rightarrow M$$

is the identity map on M . We denote by

$\Gamma(E)$ the set of all smooth sections of (E, M, π) .

Example $\Gamma(TM) \cong \mathcal{X}(M)$, $\Gamma(T^*M) \cong \Omega^1(M)$,

$\Gamma(\Lambda^k T^*M) \cong \Omega^k(M)$, $k=0,1,\dots$.

Example $(E = M \times \mathbb{R}^m, M, \pi)$ is an example of an m -dimensional vector bundle over M which is called the trivial vector bundle.

$\Gamma(E) \cong \mathcal{C}^\infty(M, \mathbb{R}^m) = \{f: M \rightarrow \mathbb{R}^m \mid f \text{ smooth}\}$

Lemma Let (E, M, π) be a smooth vector bundle over M .

Then $\Gamma(E)$ is a vector space (of possible infinite dimension) with operations:

$$1) (f_1 + f_2)(x) = f_1(x) + f_2(x)$$

$$2) (\lambda f)(x) = \lambda \cdot f(x)$$

where $f_1, f_2, \lambda \in \Gamma(E)$, $\lambda \in \mathbb{R}$, $x \in M$.

Let us fix $x \in M$ and $\Phi_x: \mathcal{N}_x \times \mathbb{R}^m \rightarrow \pi^{-1}(U_x)$ be the map as in (LTC). Assume that $f \in \Gamma(E)$. Then we may restrict f to the open set U_x and we get a composition

$$\mathcal{N}_x \hookrightarrow M \xrightarrow{f} E$$

which takes values in $\pi^{-1}(U_x)$. And so using the inverse of Φ_x^{-1} we may consider

$$\mathcal{N}_x \hookrightarrow M \xrightarrow{f} E \xrightarrow{\Phi_x^{-1}} \mathcal{N}_x \times \mathbb{R}^m$$

$$\mathcal{N}_x \ni x' \longmapsto (x', (f_1(x'), \dots, f_m(x'))).$$

We see that in the trivialization Φ_x over U_x the section f can be viewed as a function

$$\mathcal{N}_x \longrightarrow \mathbb{R}^m, \quad x' \longmapsto (f_1(x'), \dots, f_m(x')).$$

However note that this function depends on the choice of Φ_x .

Example If $\varphi: U \rightarrow \mathbb{R}^m$ is a chart on a smooth manifold M with coordinate vector fields $\{\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_m}\}$, then we know that $X \in \mathcal{X}(M)$ is over U given by

$$X|_U = \sum_{i=1}^m a_i(x) \frac{\partial}{\partial x_i} \text{ for some uniquely determined}$$

functions $a_i: U \rightarrow \mathbb{R}$ $(i=1, \dots, m)$. These functions a_1, \dots, a_m are precisely the functions prescribing the section f of the vector bundle TM over the set U .

If $k \in \mathbb{N}_0$ and f, \bar{f}_x are as above with f given by the collection

$$U_x \rightarrow \mathbb{R}^m, \quad x' \mapsto (f_1(x'), \dots, f_m(x')),$$

then it can be verified that the following definition does not depend on the choice of \bar{f}_x :

Definition We write

$$j_x^k f = 0 \text{ if}$$

all partial derivatives of all f_1, \dots, f_m up to order k vanish at x .

Given $f_1 \in \Gamma(E)$, then we denote by

$j_x^k f_1$ the equivalence class

$\{ f_2 \in \Gamma(E) : \text{all partial derivatives of } f_1 - f_2 \in \Gamma(E) \text{ up to order } k \text{ vanish at } x \}$.

Definition We call $j_x^k f$ the k -jet of f at point x .

Example: $M = \mathbb{R}^m$, $E = M \times \mathbb{R}^m$ so that $\Gamma(E) \cong \mathcal{C}(\mathbb{R}^m, \mathbb{R}^m)$,

then for $x = 0 \in \mathbb{R}^m$ we have that

$$\begin{aligned} j_0^0 f = 0 & \text{ iff } f = (f_1, \dots, f_m), \quad f_i(0) = 0, \quad i = 1, \dots, m \\ j_0^1 f = 0 & \text{ iff } j_0^0 f = 0, \quad \frac{\partial f_j}{\partial x_i}(0) = 0, \quad i = 1, \dots, m, \quad j = 1, \dots, m \\ j_0^2 f = 0 & \text{ iff } j_0^1 f = 0, \quad \frac{\partial^2 f_\ell}{\partial x_i \partial x_j} = 0, \quad i, j = 1, \dots, m, \quad \ell = 1, \dots, m \\ & \vdots \end{aligned}$$

Example: $M = \mathbb{R}^m$, $E = TM$, $X \in \mathfrak{X}(M)$ then

$$j_0^k X = 0 \text{ iff } X = \sum_{i=1}^m a_i \frac{\partial}{\partial x_i}, \quad j_0^k a_i = 0, \quad i = 1, \dots, m.$$

Definition Let (E, M, π_E) and (F, M, π_F) be vector bundles over the base M . A linear map

$$D: \Gamma(E) \rightarrow \Gamma(F)$$

is called a differential operator of order at most k if

$$Df(x) = 0 \quad \text{whenever} \quad j_x^k f = 0 \quad \text{for any } x \in M, f \in \Gamma(E).$$

D is called a differential operator of order k if it is a differential operator of order at most k but not of order at most $k-1$.

Example: 1) $d: \Omega^k(M) \rightarrow \Omega^{k+1}(M)$, $k=0, \dots, m-1$; $m = \dim M$, is a diff. operator of order 1 since in a local chart

$$d\left(\sum_I f_I dx_I\right) = \sum_I \sum_{i=1}^m \frac{\partial f_I}{\partial x_i} dx_i \wedge dx_I,$$

2) $\Delta: \mathcal{C}^\infty(M) \rightarrow \mathcal{C}^\infty(M)$ is a differential operator of order 2 since in a local chart

$$\Delta f = -\frac{1}{\sqrt{\det g}} \sum_{i=1}^m \frac{\partial}{\partial x_i} \left(\sum_{j=1}^m \frac{\partial f}{\partial x_j} g^{ij} \sqrt{\det g} \right), f \in \mathcal{C}^\infty(M)$$

Assume that

$$D: \Gamma(E) \rightarrow \Gamma(F)$$

is a diff. op. of order k and that $f \in \mathcal{C}^\infty(M)$. If $\sigma \in \Gamma(E)$, then we can consider

$$\Gamma(E) \rightarrow \Gamma(F), \sigma \mapsto [D, f]\sigma := D(f\sigma) - f(D\sigma).$$

It can be verified $[D, f]$ is a differential operator of order $k-1$.

We can now iterate this construction k times and so if

f_1, \dots, f_k are smooth functions on M , then

$$\Gamma(E) \rightarrow \Gamma(F); \sigma \mapsto \left[\dots \left[[D, f_1], f_2 \right], \dots, f_k \right] \sigma$$

is a differential of order 0. But this means

that

$$\left[\dots \left[[D, f_1], f_2 \right], \dots, f_k \right] \sigma(x)$$

depends only on $j_x^0 \sigma = \sigma(x)$. Moreover it can be verified that it depends only on $df_1(x), \dots, df_k(x) \in T_x^* M$ and it is

symmetric in df_1, \dots, df_k . We see that for fixed $x \in M$ and D we get a map

$$(S \circ D) \quad S^k T_x^* M \otimes E_x \longrightarrow F_x$$

$$\left((df_1, \dots, df_k), \sigma(x) \right) \longmapsto \sigma_k(D)(df, \sigma) := [\dots [[D, f_1], \dots, f_k] \sigma(x),$$

$$df = (df_1, \dots, df_k).$$

Definition The map $(S \circ D)$ is called the symbol of D .

Details can be found in

L. Nicolaescu: Geometry of Manifolds, Chapter 10, see RGI.

If we now fix $v \in T_x^* M$, $x \in M$ and choose $f \in C^\infty(M)$

so that $v = df_x(x)$ then by the symbol of D determined by v and x is also understood the map

$$(S \circ DI) \quad E_x \longrightarrow F_x, \quad \sigma_k(D)(v, \sigma)$$

$$\text{with } df = (df_1, \dots, df_k).$$

Definition The map $(S \circ DI)$ is called the symbol of D determined by $v \in T_x^* M$.

The map in $(S \circ DI)$ is given by a homogeneous polynomial of degree k in components of v .