

# Tensor fields on manifolds

## Tensors

Let  $V$  be a real vector space of dimension  $n$  with basis  $M = \{e_1, \dots, e_n\}$ . Let

$$V^* = \{f: V \rightarrow \mathbb{R} \mid f \text{ is linear}\}$$

be the dual space of  $V$  and  $M^* = \{\varepsilon_1, \dots, \varepsilon_n\}$  be the dual basis to  $M$ , that is

$$\varepsilon_j(e_i) = \delta_{ij} = \begin{cases} 1, & i=j \\ 0, & i \neq j \end{cases}$$

Definition Assume that  $V_1, \dots, V_k$  are finite dim. real vector spaces. A map

$$f: V_1 \times \dots \times V_k \longrightarrow \mathbb{R}$$

is called multilinear if for every  $v_i, v_i' \in V_i$  where  $i=1, \dots, k$  and  $\lambda \in \mathbb{R}$ :

$$\cdot) f(v_1, \dots, v_{i-1}, v_i + v_i', v_{i+1}, \dots, v_k) = f(v_1, \dots, v_{i-1}, v_i, v_{i+1}, \dots, v_k) + f(v_1, \dots, v_{i-1}, v_i', v_{i+1}, \dots, v_k) \text{ and}$$

$$\cdot) f(v_1, \dots, \lambda v_i, \dots, v_k) = \lambda f(v_1, \dots, v_i, \dots, v_k)$$

Definition Let  $k, l \in \mathbb{N} \cup \{0\}$ . A tensor of type  $(k, l)$  on  $V$  is a multilinear map

$$\underbrace{V \times \dots \times V}_k \times \underbrace{V^* \times \dots \times V^*}_l \longrightarrow \mathbb{R}$$

We denote by  $T^{k,l}(V)$  the set of tensors of type  $(k, l)$  on  $V$ .

Lemma a)  $T^{k,l}(V)$  is a vector space with operations

$$T, S \in T^{k,l}(V), \lambda \in \mathbb{R}:$$

$$\cdot) (T+S)(v_1, \dots, v_k, \alpha_1, \dots, \alpha_l) = T(v_1, \dots, v_k, \alpha_1, \dots, \alpha_l) + S(v_1, \dots, v_k, \alpha_1, \dots, \alpha_l) \text{ and}$$

$$\cdot) (\lambda T)(v_1, \dots, v_k, \alpha_1, \dots, \alpha_l) = \lambda T(v_1, \dots, v_k, \alpha_1, \dots, \alpha_l)$$

where  $v_1, \dots, v_k \in V, \alpha_1, \dots, \alpha_l \in V^*$

b) If  $\alpha_1, \dots, \alpha_k \in V^*$  and  $v_1, \dots, v_l \in V$  then,

$$\alpha_1 \otimes \dots \otimes \alpha_k \otimes v_1 \otimes \dots \otimes v_l: V \times \dots \times V \times V^* \times \dots \times V^* \longrightarrow \mathbb{R}$$

$$(\alpha_1 \otimes \dots \otimes \alpha_k \otimes v_1 \otimes \dots \otimes v_l)(u_1, \dots, u_k, \beta_1, \dots, \beta_l) =$$

$$= \alpha_1(u_1) \cdot \alpha_2(u_2) \cdot \dots \cdot \alpha_k(u_k) \cdot \beta_1(v_1) \cdot \dots \cdot \beta_l(v_l) \text{ where } u_1, \dots, u_k \in V, \beta_1, \dots, \beta_l \in V^*$$

is a tensor of type  $(k, l)$  on  $V$ .

c) If  $M = \{e_1, \dots, e_n\}$  is a basis of  $V$  and  $M^* = \{\varepsilon_1, \dots, \varepsilon_n\}$  is the dual basis, then

$$M^{k,l} = \left\{ \varepsilon_{i_1} \otimes \dots \otimes \varepsilon_{i_k} \otimes e_{j_1} \otimes \dots \otimes e_{j_l} : i_1, \dots, i_k, j_1, \dots, j_l \in \{1, \dots, n\} \right\}$$

is a basis of  $T^{k,l}(V)$ . Hence  $\dim T^{k,l}(V) = n^{k+l}$ .

Proof is left as an exercise. □

Examples:  $\cdot) T^{1,0}(V) \cong V^*$  and  $T^{0,1}(V) \cong V$ .

1)  $T^{1,1}(V) \cong \text{End}(V) = \{\varphi: V \rightarrow V \mid \varphi \text{ is } \mathbb{R}\text{-linear}\}$   
 If  $v \in V$  and  $T \in T^{1,1}(V)$  are fixed, then the map  $V^* \rightarrow \mathbb{R}$ ,  
 $\alpha \mapsto T(v, \alpha)$  is linear and so there is unique  $v_T \in V$   
 such that  $T(v, \alpha) = \alpha(v_T)$ . It is easy to verify that  
 the map  $\varphi_T: V \rightarrow V$ ,  $\varphi_T(v) = v_T$  is linear and that

$$T^{1,1}(V) \ni T \mapsto \varphi_T \in \text{End}(V)$$

is linear. Since it is clearly injective and  $\dim T^{1,1}(V) = n^2 = \dim \text{End}(V)$ ,  
 it is a linear isomorphism. Also note that if

$$T = \sum_{i,j=1}^m T_{ij}^i \varepsilon_j \otimes e_i, \text{ then } [\varphi_T]_M = (\varphi_{ij})_{i,j=1}^{m,m} \text{ where } \varphi_{ij} = T_{ij}^i.$$

2)  $T^{0,2}(V)$  is by definition the vector space of bilinear maps  $V \times V \rightarrow \mathbb{R}$ .

$$\text{If } T = \sum_{i,j=1}^m T_{ij} \varepsilon_i \otimes \varepsilon_j, \text{ then } [T]_M = (T_{ij}) \in M(m, \mathbb{R})$$

is the matrix of  $T$  with respect to  $M$ .

### Coefficients of tensors and change of basis

Let  $M' = \{\varepsilon_1', \dots, \varepsilon_m'\}$  be another basis of  $V$  and

$$[\text{Id}]_{M'}^M = (a_{ij}) \in GL(m, \mathbb{R})$$

be the change of basis matrix from  $M$  to  $M'$ , that is

$$\varepsilon_j = \sum_{i=1}^m a_{ij} \varepsilon_i'$$

Let  $(M')^* = \{\varepsilon_1', \dots, \varepsilon_m'\}$  be the dual basis to  $M'$ , then

$$[\text{Id}]_{(M')^*}^{M^*} = \left[ ([\text{Id}]_{M'}^M)^{-1} \right]^T = \left( [\text{Id}]_{M'}^M \right)^T = (b_{ij})^T \in GL(m, \mathbb{R}).$$

Let us consider the associated tensors of type  $(1,1)$

$$\Lambda = \sum_{i,j=1}^m \Lambda_{ij}^i \varepsilon_j \otimes e_i \text{ and } \Lambda^{-1} = \sum_{i,j=1}^m (\Lambda^{-1})_{ij}^i \varepsilon_j \otimes e_i$$

where  $\Lambda_{ij}^i = a_{ij}$  and  $(\Lambda^{-1})_{ij}^i = b_{ij}$ . We will from now on write  
 $\varepsilon^i := \varepsilon_i$ ,  $\varepsilon'^i = \varepsilon_i'$ ,  $i = 1, \dots, m$ . Note that

$$\varepsilon_j = \sum_{i=1}^m \Lambda_{ij}^i \varepsilon_i', \quad \varepsilon_j' = \sum_{i=1}^m (\Lambda^{-1})_{ij}^i \varepsilon_i, \quad \varepsilon^i = \sum_{j=1}^m (\Lambda^{-1})_{ij}^i \varepsilon_j', \quad \varepsilon'^i = \sum_{j=1}^m \Lambda_{ij}^i \varepsilon_j.$$

If  $T \in T^{k,l}(V)$ , then we may write

$$T = \sum_{i_1, \dots, i_k, j_1, \dots, j_l=1}^m T_{i_1, \dots, i_k, j_1, \dots, j_l} \varepsilon^{i_1} \otimes \dots \otimes \varepsilon^{i_k} \otimes e_{j_1} \otimes \dots \otimes e_{j_l} =$$

$$= \sum_{i_1, \dots, i_k, j_1, \dots, j_l=1}^m \sum_{p_1, \dots, p_k} \sum_{q_1, \dots, q_l} T_{i_1, \dots, i_k, j_1, \dots, j_l} (\Lambda^{-1})_{p_1, i_1}^{i_1} \dots (\Lambda^{-1})_{p_k, i_k}^{i_k} \Lambda_{j_1, q_1}^{q_1} \dots \Lambda_{j_l, q_l}^{q_l} \varepsilon^{p_1} \otimes \dots \otimes \varepsilon^{p_k} \otimes e_{q_1} \otimes \dots \otimes e_{q_l}$$

$$= \sum_{p_1, \dots, p_k, q_1, \dots, q_l=1}^m (T')_{p_1, \dots, p_k, q_1, \dots, q_l} \varepsilon^{p_1} \otimes \dots \otimes \varepsilon^{p_k} \otimes e_{q_1} \otimes \dots \otimes e_{q_l}$$

where

$$(CCT) \quad (T')_{p_1, \dots, p_k, q_1, \dots, q_l} = \sum_{i_1, \dots, i_k, j_1, \dots, j_l=1}^m T_{i_1, \dots, i_k, j_1, \dots, j_l} (\Lambda^{-1})_{p_1, i_1}^{i_1} \dots (\Lambda^{-1})_{p_k, i_k}^{i_k} \Lambda_{j_1, q_1}^{q_1} \dots \Lambda_{j_l, q_l}^{q_l}$$

## Operations on tensors

### 1) Tensor product

Let  $T \in T^{k,0}(V)$  and  $S \in T^{l,0}(V)$ . Then

$$T \otimes S \in T^{k+l,0}(V), \quad T \otimes S(v_{11}, \dots, v_{k+l}) = T(v_{11}, \dots, v_k) S(v_{k+11}, \dots, v_{k+l})$$

where  $v_i \in V, i=1, \dots, k+l$

### 2) Symmetrization and alternation

Let  $T \in T^{k,0}(V)$  and  $S \in T^{l,0}(V)$ . Then  $T \circ S$  and  $T \wedge S \in T^{k+l,0}(V)$  are defined by

$$(T \circ S)(v_{11}, \dots, v_{k+l}) = \sum_{\sigma \in S_{k+l}} \frac{1}{(k+l)!} T(v_{\sigma(1)}, \dots, v_{\sigma(k)}) S(v_{\sigma(k+1)}, \dots, v_{\sigma(k+l)})$$

$$(T \wedge S)(v_{11}, \dots, v_{k+l}) = \sum_{\sigma \in S_{k+l}} \frac{\text{sgn } \sigma}{(k+l)!} T(v_{\sigma(1)}, \dots, v_{\sigma(k)}) S(v_{\sigma(k+1)}, \dots, v_{\sigma(k+l)})$$

where  $v_{11}, \dots, v_{k+l} \in V$  and  $S_{k+l}$  is the permutation group on  $\{1, \dots, k+l\}$  and  $\text{sgn } \sigma$  is the sign of  $\sigma \in S_{k+l}$ .

Now  $T \circ S$  is symmetric in the sense that

$$(T \circ S)(v_{11}, \dots, v_{i1}, \dots, v_{j1}, \dots, v_{k+l}) = (T \circ S)(v_{11}, \dots, v_{j1}, \dots, v_{i1}, \dots, v_{k+l})$$

while  $T \wedge S$  is skew-symmetric in the sense that

$$(T \wedge S)(v_{11}, \dots, v_{i1}, \dots, v_{j1}, \dots, v_{k+l}) = - (T \wedge S)(v_{11}, \dots, v_{j1}, \dots, v_{i1}, \dots, v_{k+l}).$$

Example:  $V = \mathbb{R}^m, v_{11}, \dots, v_m \in \mathbb{R}$ , then the map

$$(v_{11}, \dots, v_m) \mapsto \det(v_{11}, \dots, v_m)$$

is a skew-symmetric tensor of type  $(m, 0)$ . Here

$(v_{11}, \dots, v_m) \in M(n, \mathbb{R})$  is the matrix with columns  $v_{11}, \dots, v_m$ .

If  $\{e_{11}, \dots, e_m\}$  is the standard basis of  $\mathbb{R}^m$  with the dual basis  $\{\varepsilon_{11}, \dots, \varepsilon_m\}$ , then this tensor is

$$\varepsilon_{11} \wedge \dots \wedge \varepsilon_m.$$

## Cotangent bundle and smooth 1-forms

Let  $(M, \mathcal{A})$  be a smooth manifold of dim.  $m$  where  $\mathcal{A} = \{\varphi_\alpha: U_\alpha \rightarrow \mathbb{R}^m \mid \alpha \in A\}$ .  
 If  $x \in M$ , we know that  $T_x M$  is a real vector space of dim.  $m$ .  
 Let  $T_x^* M := (T_x M)^*$  be the dual vector space and put  

$$T^* M = \bigcup_{x \in M} T_x^* M.$$

We sometimes write  $(x, \alpha)$  instead of  $\alpha \in T_x^* M$ . Note that there is a canonical projection  $\pi: T^* M \rightarrow M$ ,  $\pi(x, \alpha) = x$ .

Let  $\varphi: U \rightarrow \mathbb{R}^m$  be a chart from  $\mathcal{A}$  with coordinate functions  $x_1, \dots, x_m$  and associated vector fields  $\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_m}$  on  $U$ . Recall that

$$B_x^\varphi = \left\{ \frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_m} \right\}$$

is a basis of  $T_x M$  for every  $x \in U$ . Let  $(B_x^\varphi)^* = \{dx_1, \dots, dx_m\}$  be the dual basis of  $T_x^* M$ , that is

$$dx_i \left( \frac{\partial}{\partial x_j} \right) = \delta_{ij}, \quad i, j = 1, \dots, m.$$

The map  $\Phi: \pi^{-1}(U) \rightarrow \mathbb{R}^m \times \mathbb{R}^m = \mathbb{R}^{2m}$   

$$\Phi(x, \alpha) = (\varphi(x), [\alpha]_{(B_x^\varphi)^*})$$

is injective and its image is  $\varphi(U) \times \mathbb{R}^m$ . The inverse map is

$$\Phi^{-1}: \varphi(U) \times \mathbb{R}^m \rightarrow \pi^{-1}(U)$$

$$\Phi^{-1}((x_1, \dots, x_m), (q_1, \dots, q_m)) = (\varphi^{-1}(x_1, \dots, x_m), \sum_{i=1}^m q_i dx_i).$$

As in the case of  $TM$ , it can be shown (using CCT) that

Theorem There is a canonical smooth structure on  $T^* M$  determined by atlas

$$\mathcal{A}_{T^* M} = \{ \Phi_\alpha: \pi^{-1}(U_\alpha) \rightarrow \mathbb{R}^{2m} \mid \alpha \in A \}$$

so that  $T^* M$  is a smooth manifold of dimension  $2m$  and  $\pi: T^* M \rightarrow M$  is smooth.

Proof is a repetition of that for  $TM$ . □

Definition  $(T^* M, \mathcal{A}_{T^* M})$  is called the cotangent bundle of  $M$ . A smooth 1-form on  $M$  is a smooth map

$$\alpha: M \rightarrow T^* M$$

such that  $\pi \circ \alpha = \text{Id}_M$ . We denote by  $\Omega^1(M)$  the set of 1-forms on  $M$ .

Example If  $f \in \mathcal{C}_A^1(M)$ , then  $df \in \Omega^1(M)$  defined by  $df(x, v) = v(f)$  where we view  $v \in T_x M = D_x M$ . In the coordinates on  $U$ ,

$$df(x) = \sum_{i=1}^m \left( \frac{\partial}{\partial x_i} f \right)(x) dx_i. \quad \text{The 1-form is usually called the differential of } f.$$

## Tensor fields on manifolds

Put  $T_x^{k,l} M = T^{k,l}(T_x M)$  where  $k, l \in \mathbb{N} \cup \{0\}$  and

$$T^{k,l} M = \bigcup_{x \in M} T_x^{k,l} M.$$

We know that  $T_x^{k,l} M$  is a vector space of dim  $m^{k+l}$ . Following the construction smooth atlas on  $TM$  and  $T^* M$ , it follows that also

$T^{k,l} M$  is a smooth manifold of dim  $m + m^{k+l}$  and that the canonical projection  $\pi: T^{k,l} M \rightarrow M$  which is smooth.

Definition A. A smooth tensor field on  $M$  of type  $(k, l)$  is a smooth map  $T: M \rightarrow T^{k,l}M$  such that  $\pi_* T = \text{Id}_M$ . We denote by  $\mathcal{T}^{k,l}(M)$  the set of all tensor fields of type  $(k, l)$  on  $M$ .

### Local descriptions of tensor fields

Let  $\varphi: U \rightarrow \mathbb{R}^m$  be the chart on  $M$  as above and  $T \in \mathcal{T}^{k,l}(M)$ . By definition,  $T(x) \in T_x^{k,l}M$  for every  $x \in U$ . We know that

$$(B_x^\varphi)_{k,l} = \left\{ dx_{i_1} \otimes \dots \otimes dx_{i_k} \otimes \frac{\partial}{\partial x_{j_1}} \otimes \dots \otimes \frac{\partial}{\partial x_{j_l}} \mid i_1, \dots, i_k, j_1, \dots, j_l \in \{1, \dots, m\} \right\}$$

is a basis of  $T_x^{k,l}M$  for every  $x \in U$ . Hence we may write

$$T(x) = \sum_{\substack{i_1, \dots, i_k \\ j_1, \dots, j_l}} T_{i_1, \dots, i_k}^{j_1, \dots, j_l}(x) dx_{i_1} \otimes \dots \otimes dx_{i_k} \otimes \frac{\partial}{\partial x_{j_1}} \otimes \dots \otimes \frac{\partial}{\partial x_{j_l}}, \quad x \in U,$$

where  $T_{i_1, \dots, i_k}^{j_1, \dots, j_l}(x)$  are smooth functions of  $x_1, \dots, x_m$ .

Examples  $\mathcal{T}^{(1,0)}(M) = \mathcal{X}(M)$  and  $\mathcal{T}^{(0,1)}(M) = \mathcal{X}^*(M)$ .

Definition A' (Alternative definition of tensor fields)

A smooth tensor field on  $M$  of type  $(k, l)$  is a multilinear map

$$T: \underbrace{\mathcal{X}(M) \times \dots \times \mathcal{X}(M)}_{k \text{ copies}} \times \underbrace{\mathcal{X}^*(M) \times \dots \times \mathcal{X}^*(M)}_{l \text{ copies}} \rightarrow \mathcal{C}^\infty(M).$$

such that

$$\begin{aligned} \text{(LOF)} \quad T(X_{1,1}, \dots, X_{j,1}, \dots, X_k, \theta_{1,1}, \dots, \theta_l)(x) &= f(x) T(X_{1,1}, \dots, X_k, \theta_{1,1}, \dots, \theta_l)(x) \\ &= T(X_{1,1}, \dots, X_k, \theta_{1,1}, \dots, \theta_l)(x) \end{aligned}$$

for every  $X_{1,1}, \dots, X_k \in \mathcal{X}(M)$ ,  $\theta_{1,1}, \dots, \theta_l \in \mathcal{X}^*(M)$ ,  $f \in \mathcal{C}^\infty(M)$  and  $j=1, \dots, k$ ,  $i=1, \dots, l$ .  
Proof can be found in xxx.  $\square$

Notation We will sometimes write  $T_x$  instead of  $T(x)$  for  $T \in \mathcal{T}^{(k,l)}(M)$  and  $x \in M$ .

### Operations on tensor fields

Lemma

1)  $\mathcal{T}^{k,l}(M)$  is a vector space with operations  $(T+S)(x) = T(x) + S(x)$  and  $(\lambda T)(x) = \lambda T(x)$ , where  $T, S \in \mathcal{T}^{k,l}(M)$  and  $\lambda \in \mathbb{R}$ .

2) If  $T \in \mathcal{T}^{k,0}(M)$  and  $S \in \mathcal{T}^{l,0}(M)$ , then

$T \otimes S$  and  $T \wedge S$  and  $T \circ S$  defined by

$$(T \otimes S)(x) = T(x) \otimes S(x) \text{ and } (T \circ S)(x) = T(x) \circ S(x) \text{ and}$$

$$(T \wedge S)(x) = T(x) \wedge S(x) \text{ are smooth tensor fields}$$

on  $M$  of type  $(k+l, 0)$ .

Definition

Let  $f: M \rightarrow N$  be a smooth map of manifolds and  $T$  be a tensor field of type  $(k, 0)$  on  $N$ . Then  $f^*T$  is a tensor field of type  $(k, 0)$  on  $M$ , called the pullback of  $T$ , defined by

$$(f^*T)(x)(v_1, \dots, v_k) = T_{f(x)}(T_x f(v_1), \dots, T_x f(v_k)).$$

Validity of the previous definition:

1)  $(f^*T)(x): T_x M \times \dots \times T_x M \rightarrow \mathbb{R}$  is multilinear since  $T_{f(x)}$  is multilinear and  $T_x f$  is linear.

•)  $f^*T: M \rightarrow T^{(k,0)}M$  is smooth since if  $\varphi: U \rightarrow \mathbb{R}^m$  is a chart on  $M$  around  $x_0$  and  $\rho: V \rightarrow \mathbb{R}^n$  is a chart around  $f(x_0)$  with coordinate functions  $y_1, \dots, y_m$  and

$$T(y) = \sum_{i_1, \dots, i_k=1}^m T^{i_1 \dots i_k}(y) dy_{i_1} \otimes \dots \otimes dy_{i_k} \text{ on } f(U) \cap V, \text{ then}$$

$$\begin{aligned} f^*T(x) &= \sum_{i_1, \dots, i_k=1}^m T^{i_1 \dots i_k}(f(x)) \sum_{l_1=1}^m \frac{\partial f_{i_1}}{\partial x_{l_1}} dx_{l_1} \otimes \dots \otimes \sum_{l_k=1}^m \frac{\partial f_{i_k}}{\partial x_{l_k}} dx_{l_k} \\ &= \sum_{l_1, \dots, l_k=1}^m \sum_{i_1, \dots, i_k=1}^m T^{i_1 \dots i_k}(f(x)) \frac{\partial f_{i_1}}{\partial x_{l_1}} \dots \frac{\partial f_{i_k}}{\partial x_{l_k}} dx_{l_1} \otimes \dots \otimes dx_{l_k} \end{aligned}$$

on  $U \cap f^{-1}(V)$  where  $f_i$  is the  $i$ -th component of

$$\rho \circ f \circ \varphi^{-1}: \varphi(f^{-1}(V) \cap U) \rightarrow \rho(f(U) \cap V).$$

$$\begin{matrix} \cap & \cap \\ \mathbb{R}^m & \mathbb{R}^n \end{matrix}$$

We see that  $f^*T$  has smooth coefficients and so it is a smooth tensor field of type  $(k,0)$  on  $M$ .

### Examples

1)  $f: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ ,  $f(x,y,z) = (x^2+y, xz, z^3)$

$\theta \in \Omega^1(\mathbb{R}^3)$   $\theta = dz + xdy$ , then

$$\begin{aligned} f^*\theta &= d(z^3) + (x^2+y) d(xz) \\ &= 3z^2 dz + (x^2+y)(zdy + ydz) \\ &= (x^2+y)zdy + (3z^2+xy)dz \end{aligned}$$

2)  $f$  as above and  $d\lambda^3 = dx \wedge dy \wedge dz$  (Lebesgue measure on  $\mathbb{R}^3$ )

then  $f^*d\lambda^3 = |\text{Jac } f| dx \wedge dy \wedge dz = 3z^3(2x^2 - y^2) d\lambda^3$

$\text{Jac } f = \begin{pmatrix} 2x & y & 0 \\ zy & xz & xy \\ 0 & 0 & 3z^2 \end{pmatrix}$  is the Jacobi matrix of  $f$

$|\text{Jac } f| = \det \text{Jac } f = 3z^2(2x^2z - y^2z) = 3z^3(2x^2 - y^2)$ .

### Lemma

Let  $f: M \rightarrow N$  be smooth. Then

- 1)  $f^*: T^{(0,k)}(N) \rightarrow T^{(0,k)}(M)$  is linear and
- 2)  $f^*T \otimes f^*S = f^*(T \otimes S)$  when  $T \in T^{(0,k)}(M)$  and  $S \in T^{(0,l)}(M)$ .

### Lie derivative of tensor fields

Definition Let  $\text{Fl}^X$  be the flow of  $X \in \mathfrak{X}(M)$  and  $T \in T^{(k,0)}(M)$ . Then the Lie derivative of  $T$  along  $X$  is defined as

$$\mathcal{L}_X T = \frac{d}{dt} \left( (\text{Fl}_t^X)^* T \right) \Big|_{t=0} \in T^{(k,0)} M.$$

Note that  $((\text{Fl}_t^X)^*)^* T_x(v) = T_{\text{Fl}_t^X(x)}(T \text{Fl}_t^X(v))$ .

Theorem Let  $X \in \mathfrak{X}(M)$ . Then

- 1)  $L_X : \mathcal{T}^{k,0}(M) \rightarrow \mathcal{T}^{k,0}(M)$  is linear.
- 2)  $L_X(T \otimes S) = L_X T \otimes S + T \otimes L_X S$  where  $T \in \mathcal{T}^{k,0}M$  and  $S \in \mathcal{T}^{l,0}M$ .
- 3)  $(L_X \theta)(\psi) = X(\theta(\psi)) - \theta(L_X(\psi))$  where  $\theta \in \Omega^1(M)$  and  $\psi \in \mathfrak{X}(M)$
- 4) If  $X = \sum_{i=1}^m a_i(x) \frac{\partial}{\partial x_i}$  and  $\theta = \sum_{i=1}^m \alpha_i(x) dx_i$  in a chart  $U$ , then
 
$$L_X \theta = \sum_{j=1}^m \left[ \sum_{i=1}^m \left( a_i(x) \frac{\partial \alpha_j}{\partial x_i} + \alpha_i(x) \frac{\partial a_i}{\partial x_j}(x) \right) \right] dx_j \quad \text{on } U.$$

Proof: ad1) Follows from the fact that  $(\text{Fl}_t^X)^* : \mathcal{T}^{k,0}M \rightarrow \mathcal{T}^{k,0}M$  is linear.

ad2) Follows from Leibniz rule for ordinary functions.

ad3) Let us fix an open chart  $\varphi: U \rightarrow \mathbb{R}^m$  on  $M$  assume that  $\text{Fl}_t^X$  is defined for every  $t \in J$  and  $x \in U$  where  $J$  is an open interval containing 0. Assume that

$$X = \sum_{i=1}^m a_i(x) \frac{\partial}{\partial x_i}, \quad \psi = \sum_{i=1}^m b_i(x) \frac{\partial}{\partial x_i} \quad \text{and} \quad \theta = \sum_{i=1}^m \alpha_i(x) dx_i \quad \text{on } U.$$

Let  $(\Phi_t)_i$  be the  $i$ -th component of  $\text{Fl}_t^X$  in the coordinates on  $U$ . Let us fix  $x \in U$  and consider the flow

$$t \mapsto \text{Fl}_t^X(x) = (\Phi_t)(x). \quad \text{Then}$$

$$\begin{aligned} (L_X \theta)_x(\psi(x)) &= \frac{d}{dt} \left( \sum_{i=1}^m \alpha_i(\Phi_t(x)) \sum_{j=1}^m \frac{\partial (\Phi_t)_i}{\partial x_j}(x) b_j(x) \right) \Big|_{t=0} \\ &= \sum_{i=1}^m \sum_{l=1}^m a_l(x) \frac{\partial \alpha_i}{\partial x_l}(x) \delta_{ij} b_j(x) \\ &\quad + \sum_{i=1}^m \alpha_i(x) \sum_{j=1}^m \frac{d}{dt} \frac{\partial (\Phi_t)_i}{\partial x_j} \Big|_{t=0} b_j(x) \\ &= \sum_{i,j=1}^m a_i(x) \frac{\partial \alpha_j}{\partial x_i} b_j + \sum_{i=1}^m \alpha_i(x) \sum_{j=1}^m \frac{\partial a_i}{\partial x_j}(x) b_j(x) \\ &= \sum_{i,j=1}^m a_i(x) \frac{\partial}{\partial x_i} (\alpha_j(x) b_j(x)) - \sum_{i,j=1}^m \alpha_j(x) \left( a_i(x) \frac{\partial b_j}{\partial x_i}(x) - b_i(x) \frac{\partial a_j}{\partial x_i}(x) \right) \\ &= (X \alpha(\psi))(x) - \alpha(L_X \psi)(x). \end{aligned}$$

ad4) Follows from the proof of 3). □

Remark: The formula 4) can be written invariantly as

$$\text{(Cartan formula)} \quad L_X \theta = i_X d\theta + di_X \theta.$$

Here  $d$  is the de Rham differential and  $i_X$  is the insertion operator determined by  $X$ .