

Tensors

Let V be a real vector space of dim. $n \in \mathbb{N}$ with basis $M = \{e_1, \dots, e_n\}$. Let V^* be the dual vector space, that is $V^* = \{f: V \rightarrow \mathbb{R} \mid f \text{ is linear}\}$, and $M^* = \{\varepsilon_1, \dots, \varepsilon_n\}$ be the dual basis, that is

$$\varepsilon_i(e_j) = \delta_{ij} = \begin{cases} 1, & i=j \\ 0, & i \neq j \end{cases}$$

I will denote vectors in V in latin and dual vectors from V^* by greek letters. $V \cong (V^*)^*$.

$$\boxed{V \ni v \mapsto (\alpha \mapsto \alpha(v))}$$

$$\boxed{\begin{array}{l} f \text{ is linear:} \\ \rightarrow f(u+v) = f(u) + f(v), \quad u, v \in V \\ \rightarrow f(\lambda u) = \lambda f(u) \\ \quad \lambda \in \mathbb{R}, u \in V \end{array}}$$

Definition

Let V_1, \dots, V_k be f.d. real vector spaces. A map

$$f: V_1 \times \dots \times V_k \rightarrow \mathbb{R}$$

is called multilinear if

$$\rightarrow f(v_1, \dots, v_{i-1}, v_i + v_i', v_{i+1}, \dots, v_k) = f(v_1, \dots, v_k) + f(v_1, \dots, v_{i-1}, v_i', v_{i+1}, \dots, v_k)$$

$$\rightarrow f(v_1, \dots, v_{i-1}, \lambda v_i, v_{i+1}, \dots, v_k) = \lambda f(v_1, \dots, v_k)$$

whenever $v_i, v_i' \in V_i$, $i = 1, \dots, k$ and $\lambda \in \mathbb{R}$. (In other words, f is linear in each component.)

Remark $V_1 \times \dots \times V_k$ is also a vector space with

$$\rightarrow (v_1, \dots, v_k) + (v_1', \dots, v_k') = (v_1 + v_1', \dots, v_k + v_k')$$

$$\rightarrow \lambda (v_1, \dots, v_k) = (\lambda v_1, \dots, \lambda v_k)$$

where $v_i, v_i' \in V_i$, $i = 1, \dots, k$, $\lambda \in \mathbb{R}$. Note that the concept of multilinear map on $V_1 \times \dots \times V_k$ differs from the concept of linear map $V_1 \times \dots \times V_k \rightarrow \mathbb{R}$ (if $k > 1$).

Definition A tensor of type (k, l) (where $k, l \in \mathbb{N} \setminus \{0\}$) on the vector space V is a multilinear map

$$\underbrace{V \times \dots \times V}_k \times \underbrace{V^* \times \dots \times V^*}_l \rightarrow \mathbb{R}.$$

I will denote $T^{k,l}(V)$ the set of all tensors of type (k, l) on V .

Lemma 1) $T^{k,l}(V)$ is a vector space with operations

$$\cdot) (T+S)(v_{11}, \dots, v_{k1}, \alpha_{11}, \dots, \alpha_l) = T(v_{11}, \dots, v_{k1}, \alpha_{11}, \dots, \alpha_l) + S(v_{11}, \dots, v_{k1}, \alpha_{11}, \dots, \alpha_l)$$

$$\ast) (\lambda T)(v_{11}, \dots, v_{k1}, \alpha_{11}, \dots, \alpha_l) = \lambda T(v_{11}, \dots, v_{k1}, \alpha_{11}, \dots, \alpha_l)$$

where $\lambda \in \mathbb{R}$, $v_i \in V$, $\alpha_j \in V^*$, $T, S \in T^{k,l}(V)$, $i=1, \dots, k$, $j=1, \dots, l$.

2) If $\alpha_{11}, \dots, \alpha_{k1} \in V^*$, $v_{11}, \dots, v_{l1} \in V$ then the map

$$(\alpha_{11} \otimes \dots \otimes \alpha_{k1} \otimes v_{11} \otimes \dots \otimes v_{l1}) : \underbrace{V \times \dots \times V}_k \times \underbrace{V^* \times \dots \times V^*}_l \rightarrow \mathbb{R}$$

$$(\alpha_{11} \otimes \dots \otimes \alpha_{k1} \otimes v_{11} \otimes \dots \otimes v_{l1})(\mu_{11}, \dots, \mu_{k1}, \beta_{11}, \dots, \beta_{l1}) = \alpha_{11}(\mu_{11}) \dots \alpha_{k1}(\mu_{k1}) \beta_{11}(v_{11}) \dots \beta_{l1}(v_{l1}),$$

where $\mu_{11}, \dots, \mu_{k1} \in V$ and $\beta_{11}, \dots, \beta_{l1} \in V^*$, is a tensor of type (k,l) on V .

3) The (ordered) set

$$\{ \varepsilon_{i_1} \otimes \dots \otimes \varepsilon_{i_k} \otimes e_{j_1} \otimes \dots \otimes e_{j_l} \mid i_1, \dots, i_k, j_1, \dots, j_l \in \{1, \dots, n\} \}$$

is a basis of $T^{k,l}(V)$.

Proof is left as an exercise. \square

Examples : 1) $T^{1,0}(V) \cong V^*$, $T^{0,1}(V) \cong (V^*)^* \cong V$

2) $T^{1,1}(V) \cong \text{End}(V) = \{ \varphi: V \rightarrow V \mid \varphi \text{ is linear} \}$

$$T^{1,1}(V) \rightarrow \text{End}(V)$$

$T \in T^{1,1}(V)$, $v \in V$ be fixed

$$V^* \ni \alpha \mapsto T(v, \alpha) \in \mathbb{R}$$

since T is linear in the second argument, then this map $V^* \rightarrow \mathbb{R}$ is linear, we know that there is a unique $v_T \in V$ such

$$\alpha \mapsto T(v, \alpha) = \alpha(v_T)$$

since T is linear in the first argument, then

$V \ni v \mapsto v_T \in V$ is also linear, put

$$\varphi_T: V \rightarrow V, \varphi_T(v) := v_T$$

it is easy to verify that the map

$$T^{1,1}(V) \rightarrow \text{End}(V), \quad T \mapsto \varphi_T$$

is linear, injective and (by dimensional reasons

$\dim T^{1,1}(V) = n^{1+1} = n^2 = \dim \text{End}(V)$) it is an isomorphism

basis $\mathcal{M} = \{\varepsilon_1, \dots, \varepsilon_n\}$ of V , dual basis $\mathcal{M}^* = \{\varepsilon_1, \dots, \varepsilon_n\}$ of V^*

if $T = \sum_{i,j=1}^n T_{ij}^i \varepsilon_j \otimes \varepsilon_i \mapsto \varphi_T$ is uniquely det.

$$T_{ij}^i \in \mathbb{R}$$

$$\text{by } [\varphi_T]_{\mathcal{M}} = (\varphi_{ij})_{i,j=1,\dots,n}^{\delta=1,\dots,n}$$

$$\varphi_{ij} = T_{ij}^i \text{ for every } i,j=1,\dots,n.$$

$$c) \quad T^{2,0}(V) = \{f: V \times V \rightarrow \mathbb{R} \mid f \text{ multilinear}\}$$

$$= \{f: V \times V \rightarrow \mathbb{R} \mid f \text{ bilinear}\}$$

$$T = \sum_{i,j=1}^n T_{ij} \varepsilon_i \otimes \varepsilon_j \mapsto$$

$$f: V \times V \rightarrow \mathbb{R} \text{ bilinear}$$

$$[f]_{\mathcal{M}} = (T_{ij})_{i,j=1,\dots,n}^{\delta=1,\dots,n}$$

$$\{\varepsilon_i \otimes \varepsilon_j \mid i,j=1,\dots,n\}$$

is a basis of $T^{2,0}(V)$

Coefficients of tensors and change of basis of V

Let us assume that $\mathcal{M}' = \{\varepsilon_1', \dots, \varepsilon_n'\}$ is a different basis of V , $(\mathcal{M}')^* = \{\varepsilon_1', \dots, \varepsilon_n'\}$ be the dual basis

$$[\text{Id}]_{\mathcal{M}'}^{\mathcal{M}} = (a_{ij})_{i,j=1,\dots,n}^{\delta=1,\dots,n} \in M(n, \mathbb{R}) = M_{n \times n}(\mathbb{R})$$

$$e_j = \sum_{i=1}^n a_{ij} \varepsilon_i', \quad j=1,\dots,n$$

$$[\text{Id}]_{(\mathcal{M}')^*}^{(\mathcal{M})^*} = \left(([\text{Id}]_{\mathcal{M}'}^{\mathcal{M}})^T \right)^{-1} = \left([\text{Id}]_{\mathcal{M}}^{\mathcal{M}'} \right)^T = \left[(b_{ij})_{i,j=1,\dots,n}^{\delta=1,\dots,n} \right]^T \in M(n, \mathbb{R})$$

$$\varepsilon_j = \sum_{i=1}^n b_{ji} \varepsilon_i, \quad j=1,\dots,n$$

$$\varepsilon_j' = \sum_{i=1}^n b_{ij} \varepsilon_i, \quad j=1,\dots,n$$

$$\varepsilon_j' = \sum_{i=1}^n a_{ji} \varepsilon_i, \quad j=1,\dots,n$$

$$M(\Lambda, \mathbb{R}) \ni (a_{ij})_{\substack{j=1, \dots, m \\ i=1, \dots, m}} \mapsto \Lambda = \sum_{i, j=1}^m \Lambda_{ij}^i \varepsilon_j \otimes e_i \quad \Lambda_{ij}^i = a_{ij}$$

$$M(\Lambda, \mathbb{R}) \ni (b_{ij})_{\substack{j=1, \dots, m \\ i=1, \dots, m}} \mapsto \Lambda^{-1} = \sum_{i, j=1}^m (\Lambda^{-1})_{ij}^i \varepsilon_j \otimes e_i \quad (\Lambda^{-1})_{ij}^i = b_{ij}$$

I will write from now on

$$\varepsilon^i := \varepsilon_i, \quad (\varepsilon')^i := \varepsilon'_i, \quad i = 1, \dots, m.$$

We have

$$e_j = \sum_{i=1}^m \Lambda_{ij}^i e_i', \quad e_j' = \sum_{i=1}^m (\Lambda^{-1})_{ij}^i e_i$$

$$\varepsilon^j = \sum_{i=1}^m (\Lambda^{-1})_{ij}^i \varepsilon'^i, \quad \varepsilon'^j = \sum_{i=1}^m \Lambda_{ij}^i \varepsilon^i$$

$$T \in T^{k, \ell}(V) \quad T_{i_1 \dots i_k}^{j_1 \dots j_\ell} \in \mathbb{R}$$

$$T = \sum_{\substack{i_1, \dots, i_k \\ j_1, \dots, j_\ell = 1}}^m T_{i_1 \dots i_k}^{j_1 \dots j_\ell} \varepsilon^{i_1} \otimes \dots \otimes \varepsilon^{i_k} \otimes e_{j_1} \otimes \dots \otimes e_{j_\ell}$$

$$= \sum_{\substack{i_1, \dots, i_k \\ j_1, \dots, j_\ell = 1}}^m T_{i_1 \dots i_k}^{j_1 \dots j_\ell} \sum_{\substack{p_1, \dots, p_k \\ q_1, \dots, q_\ell = 1}}^m (\Lambda^{-1})_{p_1}^{i_1} \dots (\Lambda^{-1})_{p_k}^{i_k} \Lambda_{j_1}^{q_1} \dots \Lambda_{j_\ell}^{q_\ell} \varepsilon'^{p_1} \otimes \dots \otimes \varepsilon'^{p_k} \otimes e_{q_1} \otimes \dots \otimes e_{q_\ell}$$

$$= \sum_{\substack{q_1, \dots, q_\ell \\ p_1, \dots, p_k = 1}}^m (T')_{p_1 \dots p_k}^{q_1 \dots q_\ell} \varepsilon'^{p_1} \otimes \dots \otimes \varepsilon'^{p_k} \otimes e_{q_1} \otimes \dots \otimes e_{q_\ell}$$

$$(T')_{p_1 \dots p_k}^{q_1 \dots q_\ell} = \sum_{\substack{i_1, \dots, i_k \\ j_1, \dots, j_\ell = 1}}^m T_{i_1 \dots i_k}^{j_1 \dots j_\ell} (\Lambda^{-1})_{p_1}^{i_1} \dots (\Lambda^{-1})_{p_k}^{i_k} \Lambda_{j_1}^{q_1} \dots \Lambda_{j_\ell}^{q_\ell}$$

Remark: Here the only important thing is to note the coefficients of T w.r. to M and M' can be computed using the matrices

$$[\text{Id}]_M^{M'}, \quad [\text{Id}]_M^M$$

Operations on tensors

.) Tensor product

$$T \in T^{k,0}(V), S \in T^{l,0}(V)$$

$$T \otimes S \in T^{k+l,0}(V)$$

$$T \otimes S(v_1, \dots, v_{k+l}) = T(v_1, \dots, v_k) \cdot S(v_{k+1}, \dots, v_{k+l})$$

.) Symmetrization and alternation (or skew-symmetrization)

$$T \in T^{k,0}(V), S \in T^{l,0}(V)$$

$$\bullet\bullet) T \circ S \in T^{k+l,0}(V), T \circ S(v_1, \dots, v_{k+l})$$

$$= \sum_{\sigma \in S_{k+l}} \frac{1}{(k+l)!} T(v_{\sigma(1)}, \dots, v_{\sigma(k)}) S(v_{\sigma(k+1)}, \dots, v_{\sigma(k+l)})$$

S_{k+l} .. permutation group on $\{1, \dots, k+l\}$

$\sigma \in S_{k+l}$ permutation

$$v_1, \dots, v_{k+l} \in V$$

$T \circ S$ is symmetric in the sense that

$$T \circ S(v_1, \dots, v_i, \dots, v_j, \dots, v_{k+l}) = T \circ S(v_1, \dots, v_j, \dots, v_i, \dots, v_{k+l})$$

$$\bullet\bullet) T \wedge S \in T^{k+l,0}(V), T \wedge S(v_1, \dots, v_{k+l}) =$$

$$\sum_{\sigma \in S_{k+l}} \frac{\text{sgn}(\sigma)}{(k+l)!} T(v_{\sigma(1)}, \dots, v_{\sigma(k)}) S(v_{\sigma(k+1)}, \dots, v_{\sigma(k+l)})$$

$\text{sgn}(\sigma)$.. the sign of $\sigma \in S_{k+l}$

$T \wedge S$ is skew-symmetric in the sense that

$$T \wedge S(v_1, \dots, v_i, \dots, v_j, \dots, v_{k+l}) = -T \wedge S(v_1, \dots, v_j, \dots, v_i, \dots, v_{k+l})$$

Example $V = \mathbb{R}^n, v_1, \dots, v_n \in \mathbb{R}^n$

$$(v_1, \dots, v_n) \mapsto \det(v_1, \dots, v_n)$$

$(v_1, \dots, v_n) \in M(n, \mathbb{R})$ whose columns are v_1, \dots, v_n

is a skew-symmetric tensor of type $(n, 0)$

and this tensor is equal to

$\varepsilon_1 \wedge \dots \wedge \varepsilon_n$ where $\{\varepsilon_1, \dots, \varepsilon_n\}$ is the standard basis of \mathbb{R}^n
and $\{\varepsilon^1, \dots, \varepsilon^n\}$ is the dual basis.

Cotangent bundle

Let (M, \mathcal{U}) be a smooth manifold of dim m with

$$\mathcal{U} = \{ \varphi_\alpha: U_\alpha \rightarrow \mathbb{R}^m \mid \alpha \in A \}$$

$x \in M$ is fixed, then $T_x M$ is a vector space of dim m and $T_x^* M := (T_x M)^*$ be the dual vector space.

Let $\varphi: U \rightarrow \mathbb{R}^m$ be a fixed chart on M , then we know that

$$B_x^\varphi = \left\{ \frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_m} \right\}$$

is a basis of $T_x M$ for every $x \in U$. Here x_1, \dots, x_m are the associated coordinate functions.

Let

$$(B_x^\varphi)^* = \{ dx_1, \dots, dx_m \}$$

be the dual basis of $T_x^* M$ for every $x \in U$, that is

$$dx_i \left(\frac{\partial}{\partial x_j} \right) = \begin{cases} 1, & i=j \\ 0, & i \neq j. \end{cases}$$

Let us write $(x, \alpha) := \alpha \in T_x^* M$. Let

$$T^* M = \bigcup_{x \in M} T_x^* M \quad (\text{disjoint union}).$$

Definition We call $T_x^* M$ the cotangent space at x and $T^* M$ the cotangent bundle.

Construction of a (canonical) smooth atlas on $T^* M$

Note that there is a canonical projection

$$\pi: T^* M \rightarrow M, \quad \pi(x, \alpha) = x.$$

Define

$$\Phi: \pi^{-1}(U) \rightarrow \mathbb{R}^m \times \mathbb{R}^m = \mathbb{R}^{2m}$$

$$\Phi(x, \alpha) = (\varphi(x), [\alpha]_{(B_x^\varphi)^*})$$

$[\alpha]_{(B_x^\varphi)^*}$ coefficients of α w.r. to $(B_x^\varphi)^*$

$\text{Im } \Phi = \varphi(U) \times \mathbb{R}^m$. The inverse map is

$$\Phi^{-1}(x_1, \dots, x_m, q_1, \dots, q_m) = \left(\varphi^{-1}(x_1, \dots, x_m), \sum_{i=1}^m q_i dx_i \right).$$

Let $\psi: U \rightarrow \mathbb{R}^m$ be a differentiable chart on M with coordinate functions y_1, \dots, y_m . Then on $U \cap V$ we have two different bases of $T_x M$, $x \in U \cap V$, which are $\{\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_m}\}$ and $\{\frac{\partial}{\partial y_1}, \dots, \frac{\partial}{\partial y_m}\}$ and dually, we have two different bases of $T_x^* M$ $\{dx_1, \dots, dx_m\}$ and $\{dy_1, \dots, dy_m\}$. Recall that

$$\frac{\partial}{\partial x_j} = \sum_{i=1}^m a_{ij}(x) \frac{\partial}{\partial y_i}, \quad j=1, \dots, m$$

$$a_{ij}(x) = \frac{\partial (\psi \circ \psi^{-1})_i}{\partial x_j}(\psi(x)), \quad i, j=1, \dots, m$$

$$(a_{ij}(x))_{\substack{i,j=1, \dots, m}} = [\text{Id}]_{\substack{B_x^\psi \\ B_x^\psi}} = \left([\text{Id}]_{\substack{(B_x^\psi)^* \\ (B_x^\psi)^*}} \right)^T$$

If we write $y_i = (\psi \circ \psi^{-1})_i$, $i=1, \dots, m$,

$$\text{then } dy_j = \sum_{i=1}^m \frac{\partial y_j}{\partial x_i} dx_i = \sum_{i=1}^m \frac{\partial (\psi \circ \psi^{-1})_j}{\partial x_i} dx_i = \sum_{i=1}^m a_{ji}(x) dx_i$$

Theorem The collection

$$\mathcal{A}_{T^*M} = \{ \Phi_\alpha: \pi^{-1}(U_\alpha) \rightarrow \mathbb{R}^m \mid \alpha \in A \}$$

is a smooth atlas on T^*M .

Proof is just a repetition of that for the tangent bundle. \square

Def We denote by $\Omega^1(M)$ the space of all smooth 1-forms on M where a smooth 1-form on M is a smooth map

$$\omega: M \rightarrow T^*M \quad \text{such that } T\omega = \text{Id}_M.$$

Example If $f \in C^\infty(M)$, then $df \in \Omega^1(M)$ is defined

$$\text{as } df(x)(v) = v(f). \quad \text{Here } v \in T_x M = D_x M$$

as a derivation at $x \in M$. In local coordinates,

$df(x) = \sum_{i=1}^m \left(\frac{\partial f}{\partial x_i} \right) dx_i$. This is called the exterior derivative of f

Tensor bundle over M

Put $T_x^{k,l} M := T_x^{k,l}(T_x M)$ where $x \in M$ and $k, l \in \mathbb{N} \cup \{0\}$. And also put

$T^{k,l} M = \bigcup_{x \in M} T_x^{k,l} M$. As before $T^{k,l} M$

has a canonical structure of smooth manifold of dim $m + m^{k+l}$. Note that there is a canonical projection

$\pi: T^{k,l} M \rightarrow M$ which is defined in an obvious way.

Definition We call $T^{k,l} M$ a tensor bundle of M of type (k, l) . We call a smooth map $T: M \rightarrow T^{k,l} M$ such that $\pi \circ T = \text{Id}_M$ a ∇ tensor field of type (k, l) on M and we denote by $T^{k,l}(M)$ the set of all ∇ smooth tensor fields of type (k, l) on M .

Alternative definition of smooth tensor fields

Definition A smooth tensor field of type (k, l) on M is a map

$$T: \underbrace{\mathcal{F}(M) \times \dots \times \mathcal{F}(M)}_{k \text{ copies}} \times \underbrace{\Omega^1(M) \times \dots \times \Omega^1(M)}_{l \text{ copies}} \longrightarrow \mathcal{C}_{\mathcal{A}}^{\infty}(M)$$

such that

$$(LOF) \quad T(X_{i_1}, \dots, X_{i_k}, f, X_{j_1}, \dots, X_{j_l})(x) = f(x) T(X_{i_1}, \dots, X_{i_k}, X_{j_1}, \dots, X_{j_l})(x) \\ = T(X_{i_1}, \dots, X_{i_k}, X_{j_1}, \dots, X_{j_l}, f)(x)$$

where $X_{i_1}, \dots, X_{i_k} \in \mathcal{F}(M)$, $X_{j_1}, \dots, X_{j_l} \in \Omega^1(M)$, $f \in \mathcal{C}_{\mathcal{A}}^{\infty}(M)$, $x \in M$

and $i = 1, \dots, k$ and $j = 1, \dots, l$.

((LOF) T is linear w.r. to multiplication by smooth function on M).

Operations on tensor fields

Lemma 1) $\mathcal{T}^{k,l}(M)$ is a vector space with operations

$$(T+S)(x) = T(x) + S(x), \quad (\lambda T)(x) = \lambda T(x)$$

where $T, S \in \mathcal{T}^{k,l}(M)$, $x \in M$, $\lambda \in \mathbb{R}$ (and we are using that $T(x) \in T_x^{k,l}M = T^{k,l}(T_x M)$).

2) If $T \in \mathcal{T}^{k,0}(M)$ and $S \in \mathcal{T}^{l,0}(M)$, then

$$T \otimes S, T \circ S, T \wedge S \in \mathcal{T}^{k+l,0}(M) \quad \text{where}$$

$$(T \otimes S)(x) = T(x) \otimes S(x), \quad (T \circ S)(x) = T(x) \circ S(x) \quad \text{and}$$

$$(T \wedge S)(x) = T(x) \wedge S(x).$$
